OPERATION MANUAL

RESISTOMAT® 2329

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The measurement solution.   **burster**

E U - K o n f o r m i t ä t s e r k l ä r u n g (nach EN ISO/IEC 17050-1:2010)
EU-Declaration of conformity (in accordance with EN ISO/IEC 17050-1:2010)

Name des Ausstellers:
Issuer's name: burster präzisionsmesstechnik gmbh & co kg

Anschrift des Ausstellers: Talstr. 1-5
Issuer's address: 76593 Gernsbach, Germany

Gegenstand der Erklärung: RESISTOMAT® zur schnellen Widerstandsmessung in der Automation
Object of the declaration: *RESISTOMAT® for Fast Resistance Measurement in Automated Processes*

Modellnummer(n) (Typ):   2329
Model number / type:

Diese Erklärung beinhaltet obengenannte Produkte mit allen Optionen
This declaration covers all options of the above product(s)

Das oben beschriebene Produkt ist konform mit den Anforderungen der folgenden Dokumente:
The object of the declaration described above is in conformity with the requirements of the following documents:

Dokument-Nr. *Documents No.*	Titel *Title*	Ausgabe *Edition*
2011/65/EU	Richtlinie zur Beschränkung der Verwendung bestimmter gefährlicher Stoffe in Elektro- und Elektronikgeräten *Directive on the restriction of the use of certain hazardous substances in electrical and electronic equipment*	2011
2014/35/EU	Richtlinie zur Harmonisierung der Rechtsvorschriften der Mitgliedsstaaten über die Bereitstellung elektrischer Betriebsmittel zur Verwendung innerhalb bestimmter Spannungsgrenzen auf dem Markt *Directive on the harmonization of the laws of the Member States relating to the making available on the market of electrical equipment designed for use within certain voltage limits*	2014
2014/30/EU	Richtlinie zur Harmonisierung der Rechtsvorschriften der Mitgliedsstaaten über die Elektromagnetische Verträglichkeit *Directive on the harmonization of the laws of the Member States relating to electromagnetic compatibility*	2014
EN 61010-1	Sicherheitsbestimmungen für elektrische Mess-, Steuer-, Regel- und Laborgeräte – Teil 1: Allgemeine Anforderungen *Safety requirements for electrical equipment for measurement, control and laboratory use – Part 1: General requirements*	2010 + Cor.:2011
EN 61326-1	Elektrische Mess-, Steuer-, Regel- und Laborgeräte – EMV-Anforderungen – Teil 1: Allgemeine Anforderungen *Electrical equipment for measurement, control and laboratory use – EMC requirements – Part 1: General requirements*	2013
EN 55011	Industrielle, wissenschaftliche und medizinische Geräte – Funkstörungen – Grenzwerte und Messverfahren *Industrial, scientific and medical equipment – Radio-frequency disturbance characteristics – Limits and methods of measurement*	2009

Gernsbach   20.04.2016   i.V. Christian Karius
Ort */ place*   Datum */ date*   *Quality Manager*

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*According EN ISO/IEC 17050 this document **is valid without a signature**.*

1. General Information

1.0 Safety

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WARNING

Special caution is required in the case of inductive test devices!

If
- the plugs are pulled out of their sockets,
- the measurement current is switched over,
- the cables tear,
- the terminals on the test device are loose,
- the unit is switched off during measurement,
- the power is interrupted during measurement,
- the measurement current changes for any other reason:

then   extremely dangerous inductive voltages can be generated under these physical conditions!

</div>

A danger arises when ever the current flow through the test object is interrupted. In this case, an extremely hazardous voltage is induced in the test object. Therefore, particular caution is required when the test object is being disconnected from the RESISTOMAT® or if the contacts slip off or drop while energy is still stored in the test object. As the RESISTOMAT® does not indicate the level of this energy, the test object must be short-circuited prior to disconnection in order for it to discharge fully.

For safety reasons, inductive test objects must not be unplugged from the device.
If a partially or fully grounded inductive test unit is unplugged from the device, a voltage flashover might occur in the plug, thus exposing the operator to the flow of current in the electrical circuit of the test object. This is extremely hazardous !!!!

Great care must be exercised if the device exhibits abnormal behaviour.
For example: No response to actuation of controls;
         No supply of measurement results;
         Unusual displays.
In such cases, always short-circuit the inductive test object and then disconnect it.

1.1 Applications

The RESISTOMAT® type 2329 is particularly suitable for measurements of low impedances in automation technology, and is capable of performing up to 50 measurements per second without any problem.
This device complies with the latest CE guidelines and is designed for use in the laboratory as well as heavy-duty industrial applications.
Classification and selection can be performed using a 2-fold and 4-fold comparator with switching outputs; this feature is particularly useful for conducting serial tests.
The measurement of contact resistances (dry-circuit measurement) constitutes a special application, as the load voltage in this case is limited to 20 mV (DIN 41640, Part 4 and IEC 132-1) to prevent 'wetting'.
The RS232 (standard) and IEEE488 (optional) computer interfaces allow fully automatic testing stations to be set up. The PLC interface of the device allows it to be easily integrated into production control systems.

Typical applications include measurements of the resistance and conductivity of:

- Melting fuses
- Airbag triggers
- Magnetic coils for automobiles and electrical fittings
- Plug-contacts and switches
- Commutator welded-joints
- Meter samples in cable manufacture
- Conducting tracks
  etc.

1.2 Description

This device operates on the basis of proven 4-wire technology, whereby line and contact resistances are eliminated. The measurement lines are monitored with an integrated cable-breakage sensor.

Needless to say, temperature compensation has been included for different test materials, such as copper, brass, tungsten etc. Temperatures are measured using a Pt100 sensor, infrared sensor (pyrometer) or any temperature transmitter equipped with an analog output.

For the measurement of low inductances, the measurement inputs are equipped with a special protective mechanism which prevents voltage peaks from damaging the device when it is disconnected from the test object.
If test measurements involving several different parameters need to be performed in an automatic measuring system, up to 32 device settings such as the measurement range, limiting values, temperature coefficient etc. can be stored for this purpose. These settings are called up by means of a 5-bit pattern. Naturally, all device settings can also be performed via the RS232 or optional IEEE488 interface.

For serial measurements and production monitoring, the integrated datalogger can be used to store up to 20.000 measured values, which can be divided into 32 individual blocks. A digital filter is used to preselect the measured values to be stored. The stochastic datalogger evaluation menu displays the maximum, minium and average values, as well as the standard deviation.

2. Preparation for Operation

2.1 Unpacking the device

The device weighs 5.2 kg and is enclosed in a suitable, shockproof packaging.
Unpack the device carefully and ensure that the scope of delivery is complete.

Standard scope of delivery includes: 1 RESISTOMAT® micro-ohmmeter type 2329
                                          1 Connecting cable
                                          1 Copy of this manual
                                          1 Demo disk.

Check the device thoroughly for any signs of damage.
If any damage seems to have occurred during transport, please notify the supplier within 72 hours.
The packaging should be retained so that it can be examined by the manufacturer and/or supplier.
The RESISTOMAT® type 2329 must only be transported in its original or an equivalent packaging.

2.2 Commissioning the device

Ensure that the mains voltage selector is set to the correct supply voltage. Using the accompanying cable, connect the device to a standard, grounded socket.

Important: On no account should the device be switched on if it seems to have been damaged during transport.
Dispersion from the mains network can give rise to hazardous voltages on the housing and at the measurement input.

2.3 Supply voltage

The supply voltage has been set to 230 V~ at the factory; it can be changed using the rotary selector switch.

Supply voltage: 230 V~ ± 10 %

Frequency range: 47 Hz ... 63 Hz

Power consumption: 25 VA

Fuse rating: 0.125 AT
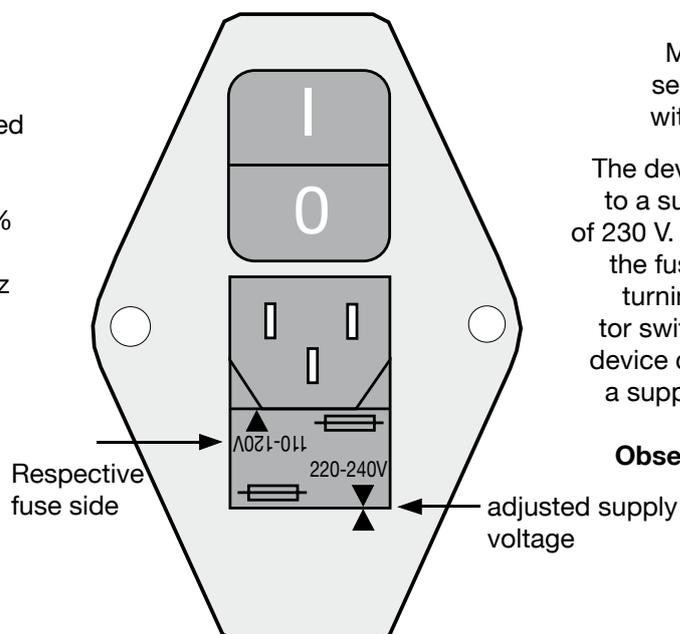
Mains voltage selector switch with fuse catch

The device is preset to a supply voltage of 230 V. By removing the fuse catch and turning the selector switch 180°, the device can be set to a supply voltage of 115 V.
Observe the fuse rating!

Respective fuse side

110-120V

220-240V

adjusted supply voltage

2.4 Mains fuse

The mains fuse is located below the mains connection socket on the rear panel of the device.
Before replacing the fuse, ensure that the device has been properly disconnected from the mains (remove the connection cable from grounded socket).
Only use original 5 x 20 mm, 0.125 AT fuses for 230 V~ and 0.2 AT fuses for 115 V~.

2.5 Power supply and connection of signal lines

Mains socket
Mains switch
Mains selector switch with fuse catch (see page 9)
Pt100 connection (pin assignment on page 14)
Measurement input (pin assignment on page 14)

207-253 V   0,125 AT
104-126 V   0,2 AT
47- 63 Hz   25 VA

Pt100

Respective fuse side

110-120V   220-240V

adjusted supply voltage

45 V max.

Ix   0,63 AM

Rx

ACHTUNG!
VOR ÖFFNEN DES GERÄTES NETZSTECKER ZIEHEN: SERVICE NUR DURCH FACHLEUTE NUR ANGEGEBENE SICHERUNGSWERTE VERWENDEN.

WARNING!
TO PREVENT ELECTRICAL SHOCK DO NOT OPEN COVERS: REFER TO QUALIFIED PERSONNEL NO USER SERVICEABLE PARTS INSIDE.

CAUTION!
TO PREVENT FIRE REPLACE ONLY WITH SAME TYPE AND SHOWN RATING OF FUSE.

DIGITAL I/O PORT

IEEE 488

Analog - I/O
1/5 - Analog - I/O
6 in 0-10 V   = /100 kΩ
7 in 0-20 mA = /14 Ω
9 Out 0-10 V = /0,3 mA

RS232

Ext. 24 V $_{DC}$
30 V max.

2329.0009

2329.0008

Additional 5 x 20 mm, 0.63 A M fine wire fuse for the measurement current

Input/output for analog (see page 14)

(Optional) IEEE488 interface pin assignment (see page 15) description (see page 67)

PE-FE connection (see page 15)

RS232 interface (see page 15) pin assignment (from page 65)

Digital input/output for PLC (see page 16) and description (see page 69)

- For reasons of electromagnetic compatibility, the mains socket of the device must only be connected to the 230 V~ (115 V~) mains network using the ferrite-coated, shielded cable included in the scope of delivery.

- The optional IEEE488 bus-connection plug is standardized. To observe applicable interference protection guidelines, only a shielded interface cable and shielded plugs must be used.

- The standard RS232 interface must only be connected using a shielded, twisted cable and shielded plugs.

- The Pt100 terminal must only be connected to a Pt100 sensor by means of a shielded cable. The cable shield must not be located on the plug housing in the event of any uncertainty concerning the sensor ground, as this might result in measurement errors caused by double-ground compensation currents.

- The Rx measurement input must only be connected using a cable with individually shielded wires. The maximum permissible capacitance here is 10 nF. The observation of this limit is particularly important in the case of high-impedance test objects.

2.6 Operational test

After the device is turned on, the following text is displayed for about 5 seconds:

```
RESISTOMAT TYP 2329
SN:          123456
VERSION:     V201202
CAL:         C0001
DATE:        16.12.13
TIME:        13:25:26
┌──────┬──────┬──────┬──────┐
│ LANG │ TIME │      │ MAIN │
└──────┴──────┴──────┴──────┘
```

Exception: This text does not appear if a quick start has been activated in access menu (see chapter 4.3.3.1)

2.7 Calibration

The device is calibrated before delivery.

The measurement instruments used for this purpose comply with DIN ISO 9000ff standards.

The device should be re-calibrated once every year or so.

Re-calibration is performed via the RS232 interface; this task should only be carried out by the manufacturer.

Basic balancing of the individual measurement ranges is described in Chapter 4.4.4.13 titled "Balancing".

2.8 Storage

Permissible storage temperatures lie between -10°C and 60 °C.

If the device has been exposed to moisture during storage, ensure that it is completely dry on the inside and outside before commissioning it.

No other measures are required for commissioning after storage.

3. Control Elements and Connections

3.1 Front panel

A touch-sensitive membrane keypad is used here.
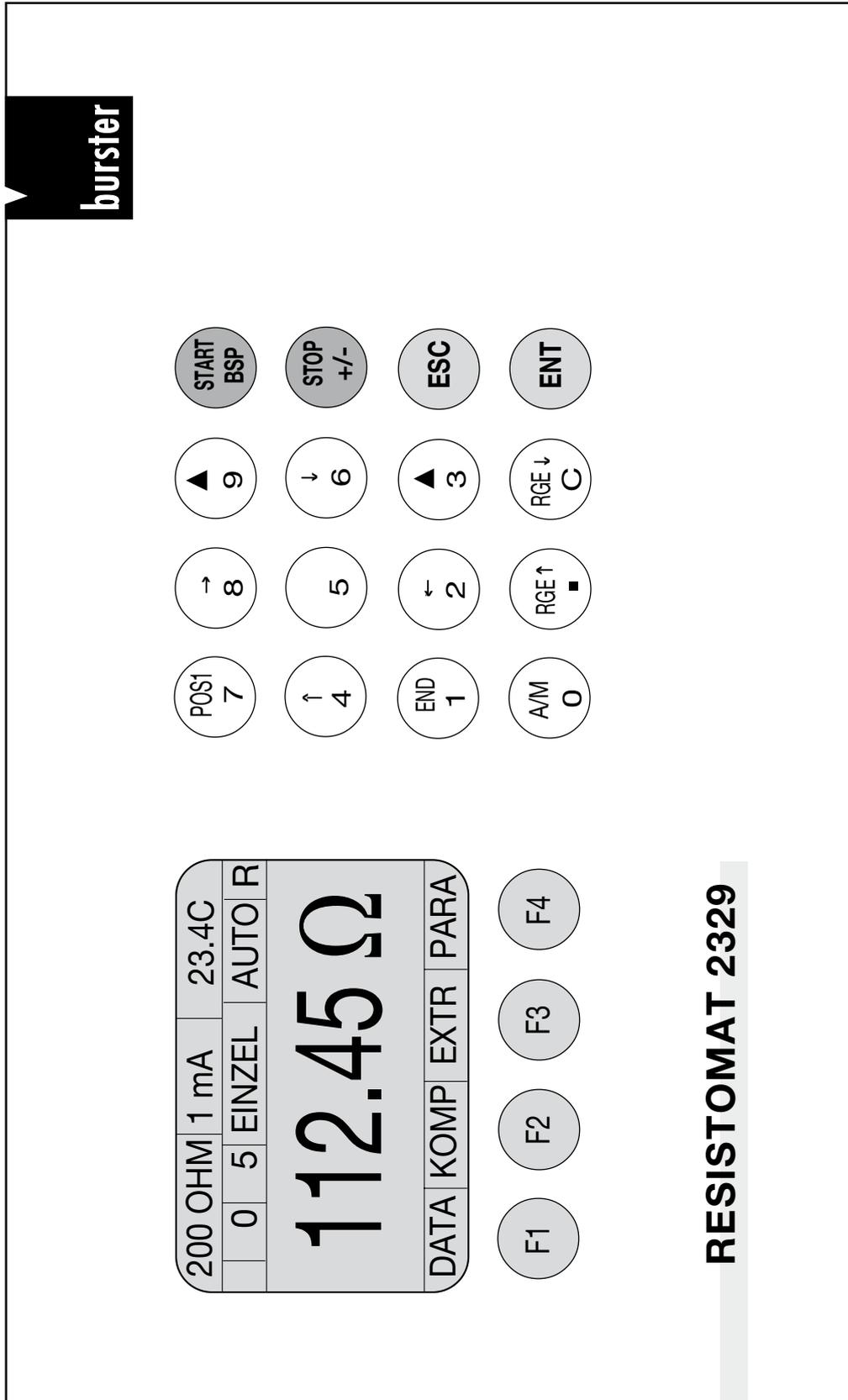
As shown in the illustration, some keys have a dual function.

3.1.1 Description of the individual keys

Key	Description
[BSP]	: This key (Backspace) is used to delete the character entered last.
[START]	: This key commences a measurement.
[+/-]	: This key is used to enter the sign of a numerical value.
[STOP]	: This key is used to stop a measurement.
[ESC]	: This key is used to cancel a current entry, and exit the input mode
[ENT]	: This key is used to acknowledge an entry or a selection.
[9] [↑]	: Number 9. : The Page-Up key is used to select the previous page of a multi-page menu.
[6] [↑→]	: Number 6. : The right cursor key is used to select parameter values.
[3] [↓→] page	: Number 3. : The Page-Down key is used to select the next in a multi-page menu.
[C] and	: This key is used to fully delete the current entry repeat the input procedure from the beginning, without exiting the input mode.
[RGE ↓]	: When manual range selection is active, this key is used to select the next lower measuring range in the main menu.

Key	Description
[8] [↑]	: Number 8. : The cursor-up key is used to select a parameter in a menu.
[5]	: Number 5.
[2] [↓]	: Number 2. : The cursor-down key is used to select a parameter in a menu.
[.] [RGE↑]	: Entry of a decimal point. : When manual range selection is active, this key is used to select the next higher measuring range in the main menu.
[7] [POS1]	: Number 7. : This key effects a jump to the first parameter in any menu window.
[4] [←]	: Number 4. : The left cursor key is used to select parameter values.
[1] [END]	: Number 1. : This key effects a jump to the last parameter in a menu window.
[0] [A/M]	: Number 0. : When a measurement is not in progress, this key is used to changeover between automatic and manual range selection in the main menu.
[F1], [F2],[F3], [F4]	: These programmable keys have different functions depending on the menu in which they are used. Their designations are displayed in the bottom line of each menu.

3.1.2 Description of the terminals
Measurement input
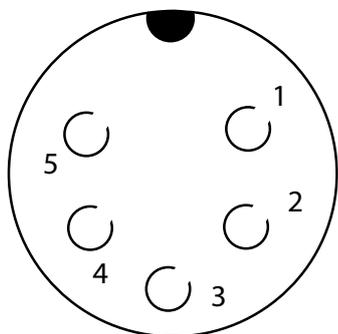
1	+ U
2	+ I
3	Analog GND
4	- I
5	- U

Plug housing	:	Potential PE
Counter-plug	:	burster type 9900-V172

View of the socket

Note: The current path is protection with a 5 x 20 [mm] 0.63 MT fuse (located on the rear panel of the device.
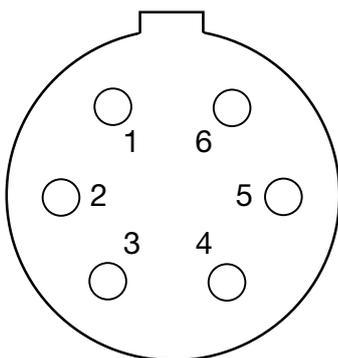
Pt100 input

1	+ U
2	+ I
3	- I
4	Functional ground
5	Functional ground
6	- U

Plug housing	:	Potential PE
Counter-plug	:	burster type 4291-0

Two-wire technique can be used if the corresponding sensor terminals are bridged.

View of the socket

Note: **NEVER** apply the cable shield to the plug housing if there is any uncertainty

Analog I/O

1	Analog GND
2	NC
3	NC
4	NC
5	Analog GND
6	0-10 V input for temperature measurement (R_E >100 kΩ)
7	4/0-20 mA input for temperature measurement (R_E < 20 Ω)
8	NC
9	0-10 V analog output of the measurement signal ($I_{max} \leqq 0.2$ mA)
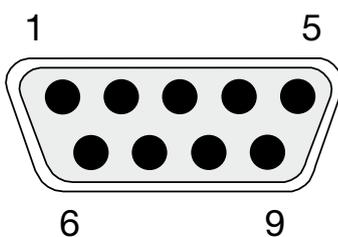
9 pole Sub MinD plug
View of the plug

Plug housing	:	Potential PE
Counter-plug	:	Type 9900-V609

Note: The mA input (pin 7) is protected internally by a 5 x 20 [mm] 0.25 AT fuse.

RS232 interface

```
5          1

9          6
```

9 pole Sub MinD
socket
View of socket

1	NC
2	TXD
3	RXD
4	
5	**Digital GND (internally grounded)**
6	
7	NC
8	
9	NC

Bridged inside the device
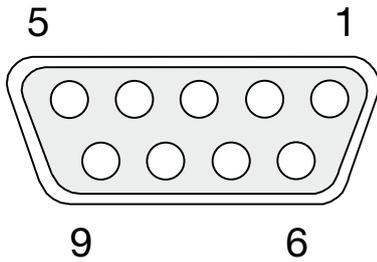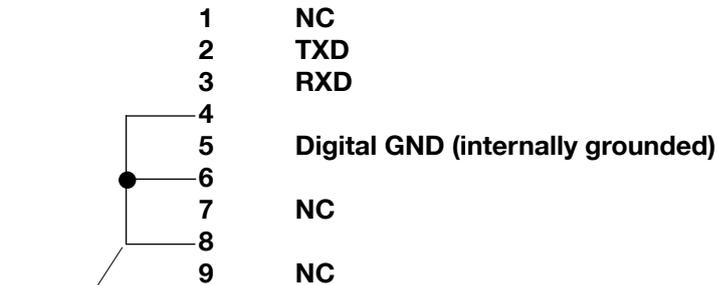
Plug housing	:	Potential PE
Counter-plug	:	Type 9900-V209
Matching data cable	:	Type 9305-K001

IEEE488 interface

```
1        13

DIO1          DIO5
DIO2          DIO6
DIO3          DIO7
DIO4          DIO8
EOI           REN
DAV           GND
NRFD          GND
NDAC          GND
IFC           GND
SRQ           GND
ATN           GND
CABLE         GND
SHIELD

12       24
```
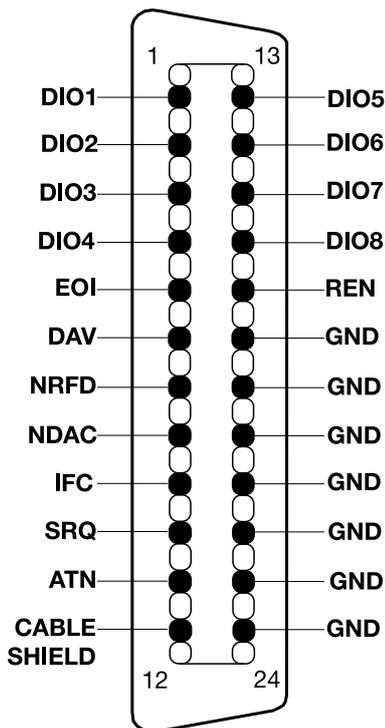
The 24-pole IEEE488 bus plug-connector is standardized and has the displayed pin assignment.

To comply with applicable interference protection guidelines (VDE 0871B), all interface cables and plugs must be shielded at both ends.

| Plug housing | : | Potential PE |
| Matching data cable | : | Type 5230-001 |

GND is internally grounded.

PE-FE connection

Device socket

In the case of ungrounded (or unearthed) test objects, PE-FE must be connected to the short-circuit bridge.

In the case of grounded (or earthed) test objects, the short-circuit bridge must be removed, otherwise double-ground compensation currents might arise and lead to measurement errors.

| Black: | FE Functional earth |
| Yellow/green: | PE Protective earth |

Digital I/O

Pin	4 LV*	2 LV*	
1	<<	<	Potential-free relay output for evaluation
2	<		
3	=	=	
4	>		P_{max} = 30 W
5	>>	>	U_{max} = 48 V
6	ROOT RELAY		I_{max} = 1 A
7	MEASUREMENT IN PROGRESS		
8	MEASUREMENT COMPLETE		
9	MEASUREMENT ERROR		
10	<<	<	
11	<		PLC output for evaluation
12	=	=	
13	>		
14	>>	>	
15	OUTPUT 1		
16	OUTPUT 2		
17	OUTPUT 3		
18	+ EXT. SUPPLY		+ 24 V PLC
19	+ EXT. SUPPLY		for Pin 7-35
20	- EXT. SUPPLY		0V PLC
21	START/STOP MEASUREMENT		
22	START/STOP COMPARATOR		
23	START/STOP DATALOGGER		
24	START/STOP MAX/MIN		
25	START/STOP PRINTER		
26	SAVE device setting pins 28 -32		
27	INPUT 1		
28	Bin 0		BINARY SELECTION OF THE DEVICE SETTING
29	Bin 1		
30	Bin 2		
31	Bin 3		
32	Bin 4		
33	INPUT 2		
34	INPUT 3		
35	INPUT 4		
36			FOOT SWITCH START/STOP
37			

24 V

START   STOP

*LV = Limit value

37 pole Sub MinD
View of the socket

Plug housing: Potential PE
Counter-plug: Type 2304-Z001

3.1.3 Block diagram

The block diagram illustrates the internal structure of the Model 2329, showing connections between components including Temperature compensation (Pt100), 0 … 20 mA, 4 … 20 mA, 0 … 10 V inputs, D/A converter, Keyboard, Display, I/O Interface, Relays, RS232 (IEEE488), µP, Clock, Datalogger, Memory, A/D converter, Current source, Protective circuit, Controlling, Analog output 0 … 10 V, and Rx.

4. Manual Operation

4.1 General instructions
4.1.1 Meaning of the individual display segments

Status line I

Measurement range, measurement current or 20 mV for dry-circuit measurements.
Temperature with active TC or set point value with Δ %

Status line II

Error status,
memory number loaded last,
continuous or single-frame measurement, manual or automatic range selection, R or Z measurement procedure.

200 OHM		1mA		23.4C	
0	5	SINGLE	AUTO	R	

$$112.45\ \Omega$$

DATA	COMP	ENVE	PARA

Measurement field

The measurement value loaded last.

Meaning of the function keys.

4.1.2 Overview of controls

Control example for device settings see appendix pageSeite 143

Device switch on

Page 24 — Identification display

F1 → Page 25 — Language adjustment

F2 → Page 25 — Clock/Date input

F4 or after 5 sec.

F4 → Page 26 — Main menu (measure stoped)

Enter

Page 28 — Code Input

Correkt Code → Page 28 — Access protect — F4 Hauptmenü

F3 → Page 30 — PLC test menu — F4 Hauptmenü

START / STOP

F4 → Page 27 — Main menu (measure started)

F 1: Datalogger Start/Stop
F 2: Comparator Start/Stopp
F 3: Max-/Min value Start/Stop
F 4: Printer Start/Stop

F1 → Page 32 — Datalogger evaluation — F4 main menu

F2 → Page 34 — Comparator evaluation — F4 main menu — F 1 in main menu

F3 → Page 35 — Max-/Min value evaluation — F4 main menu — F 2 in main menu

F4 → Page 35 — Parameter selection — F4 main menu

Page 35 — Measure parameter

Page 42 — Datalogger adjustment

Page 45 — Comparator adjustment

Page 47 — Temperature comp.

Page 49 — Display select

Page 50 — Interface config.

Page 53 — Adjustment storage

Page 55 — Printer adjustment

Page 57 — Status display

Page 58 — Auxiliary input/output

Page 59 — Input scaling

Page 62 — Contrast adjustment

Page 63 — Calibration

F3 — Main menu / F4 — Parameter select

4.1.3 Measurement errors
Error tolerances and influence variables (for the standard procedure)

Resistance measurement (display range of 2000 and 20000):

Range	Measured value %	Conv.: Minimum Digits	Conv.: Medium Digits	Conv.: Standard Digits	Conv.: Maximum Digits
200 mΩ	0.03	± 4	± 3	± 2.5	± 2
2 Ω	0.03	± 4	± 3	± 2.5	± 2
20 Ω	0.03	± 4	± 3	± 2.5	± 2
200 Ω	0.03	± 4	± 3	± 2.5	± 2
2 kΩ	0.03	± 4	± 3	± 2.5	± 2
20 kΩ	0.03	± 4	± 3	± 2.5	± 2
200 kΩ	0.03	± 4	± 3	± 2.5	± 2

Temperature coefficient: 20 ppm/K   Conv. = Conversion settings (see chapter 4.4.4.1)

20 mV mode

Resolution	Display ranges		Measured value %	Conv.: Minimum Digits	Conv.: Medium Digits	Conv.: Standard Digits	Conv.: Maximum Digits
2000	0.0 mΩ ... 200.000 mΩ		0.05	4	3	2.5	2
	0.200 Ω ... 2.000 Ω		0.05				
	2.00 Ω ... 4.09 Ω		0.1				
20000	0.00 mΩ ... 200.00 mΩ		0.05	4	3	2.5	2
	0.2000 Ω ... 0.6000 Ω		0.05				
	0.600 Ω ... 4.099 Ω		0.10				

Temperature coefficient: 20 ppm/K

In the 20 mV mode, the total resistance of the test object and the lines connected to it must amount to at least 200 mOhm. If this value is fallen short of, the measurement current becomes too high and the device outputs an error (current transmitter overloaded!). As the resistance increases, the measurement current drops and the measured results become more uncertain. (I_{min} = 1 mA, I_{max} = 100 mA)

Type	Error	TC	
*Pt100 (without sensor type)	0.07 K	20 ppm/K of ohmic value	I ca. 0.8 mA
U input	1.5 mV	25 ppm/K	R_E > 100 kΩ
I input	3 µA	20 ppm/K	R_E < 20 Ω

*Error including measurement and linearization with respect to the DIN characteristic (range - 100 °C ... + 300 °C). The error of the temperature sensor is not included.

Analog output
- Analog output of the measurement amplifier (with respect to "-I" or analog ground). Error: 2.5 %, TC 80 ppm/K
- 10 V correspond to the maximum display value (except in the 20 mV mode). Capacity: <= 0.2 mA
- Output resistance: <= 0.1 Ω.

This output supplies the measurement signal (zero measurement - if active, cable-breakage test and measurement "ON"). This function is not recommended in the 20 mV mode, as the value of the measurement current is unknown here. As no specific current is used, only a part of the required information is available

4.1.4 Measurement rate

The RESISTOMAT® 2329 was developed to allow quick and reliable measurements of ohmic resistances. The hardware and software are geared especially toward PLC-controlled measurements. The fastest measurements are achieved by triggering via a PLC or footswitch and evaluation of the results in combination with EOC. The single-frame measurement mode and manual range selection are used as a rule.

Every additional function increases the load on the process and reduces the achievable measurement rate.

Resolution range	20.000 C min	20.000 C med	20.000 C stand	20.000 C max	2.000 C min	2.000 C med	2.000 C stand	2.000 C max
200 mΩ	45 ms	78 ms	145 ms	276 ms	15 ms	20 ms	39 ms	91 ms
2 Ω	45 ms	78 ms	145 ms	276 ms	15 ms	20 ms	39 ms	91 ms
20 Ω	22 ms	40 ms	80 ms	145 ms	15 ms	20 ms	39 ms	65 ms
200 Ω	22 ms	40 ms	80 ms	145 ms	15 ms	20 ms	39 ms	65 ms
2 kΩ	30 ms	50 ms	80 ms	145 ms	15 ms	20 ms	39 ms	65 ms
20 kΩ	74 ms	95 ms	158 ms	263 ms	22 ms	26 ms	45 ms	72 ms
200 kΩ	283 ms	336 ms	442 ms	756 ms	76 ms	80 ms	100 ms	179 ms
20 mV	107 ms	187 ms	345 ms	660 ms	35 ms	55 ms	82 ms	240 ms

C = Conversion settings (see chapter 4.4.4.1)

Note:

All times were determined with the following settings:

Measurement procedure: Standard, "R" (identical to SINGLE-COMP during single-frame measurements).

No temperature compensation, no interface operation, no max.-min., no datalogger, no printer, no comparator.

Range selection: Manual

Times are measured from the falling edge of the footswitch to the rising edge of the PLC - EOC.

Internally, the free processor capacity is always made available to the measurement procedure. Every additionally activated function and every interface command (PLC, printer, RS232 and IEEE488) slows down the measurement.

Activating the temperature compensation slows down the measurement procedure.

The times must be determined with the following factors:

Range	Resolution 20.000	Resolution 2.000
200 mΩ	1.8	1.8
2 Ω	1.8	1.8
20 Ω	1.8	1.8
200 Ω	1.8	1.8
2 kΩ	1.8	1.8
20 kΩ	2.1	2.1
200 kΩ	2.5	2.5
20 mV	1.8	2.6

Measurement procedures without compensation (without a reference measurement) are faster.
Times must be determined with the following factors:

Resolution range	20.000 C min	20.000 C med	20.000 C stand	20.000 C max	2.000 C min	2.000 C med	2.000 C stand	2.000 C max
200 mΩ	0.7	0.7	0.6	0.6	0.8	0.7	0.7	0.6
2 Ω	0.7	0.7	0.6	0.6	0.8	0.7	0.7	0.6
20 Ω	0.7	0.7	0.6	0.6	0.8	0.7	0.7	0.6
200 Ω	0.7	0.7	0.6	0.6	0.8	0.7	0.7	0.6
2 kΩ	0.7	0.7	0.6	0.6	0.8	0.7	0.7	0.6
20 kΩ	0.7	0.7	0.6	0.6	0.8	0.7	0.7	0.6
200 kΩ	0.7	0.7	0.6	0.6	0.8	0.7	0.7	0.6
20 mV	0.7	0.7	0.6	0.6	0.8	0.7	0.7	0.6

C = Conversion settings (see chapter 4.4.4.1)

The "REF-COMP" reference measurement
takes roughly the same time as the measurement without compensation.

The datalogger, comparator and max./min. recording
each take 0.5 ms longer.

The R and Z test settings
serve to match measurement procedures to long current-settling times caused primarily by inductive resistances.

For Z, the internal settling (or transient) times are increased by a factor of three and a waiting period elapses to allow the measurement current to stabilize. In this case, it is not possible to activate automatic range selection while a measurement is in progress, or activate the 20 mV mode.

If Z has been selected, ohmic resistances result in measurement times which are longer by a factor of 1.1 - 2, depending on the selected measurement range. In the event of an error, the time taken to detect cable-breakage rises to approximately 3 seconds, to allow the maximum charging time of the test object to elapse.

Errors occurring on the "R" setting
take approximately 4 ms to (1 ms + the standard measurement time) to detect, depending on their nature. In the case of extremely brief measurements, the time taken to detect cable-breakage is longer than the standard measurement time, as the waiting and evaluation times are added in this case.

With automatic range selection active, it might take very long to detect an interruption, as all the high ranges need to be checked first. For this reason, it is highly advisable to use manual range selection at testing stations involving short cycle times.

With REMOTE control active,

all additional program sections need
to be interrogated internally.
If PLC operation is involved, this
prolongs the measurement times by
the following factors:

Range	Factor
200 mΩ	1.2
2 Ω	1.2
20 Ω	1.2
200 Ω	1.2
2 kΩ	1.2
20 kΩ	1.4
200 kΩ	1.5
20 mV	1.4

With operation via an interface
(Init,Status:Operation:Event?,Fetch?,...), the measurement times depend heavily on the computer in use and the programming technique.

The faster the computer and the interface card, the more frequent the interruptions in the 2329's measurement process and the greater the drainage of its processing capacity.

Therefore, if a fast computer is in use, it should only be used to trigger the measurement and fetch the results once the measurement is complete.

With an RS232,
this can be achieved by configuring queues on the PC having the same magnitude as the expected measurement time. Subsequently, the status register can be used to determine whether the measurement is OK. If so, the measured value can be requested and read out. This is probably the fastest method.

Compared with standard PLC measurements without REMOTE control, the measurement time in this case increases by roughly 4 ms prior to a measurement (command decoding) and approximately 42 ms after the measurement (286/12 MHz, QBasic). The actual measurement time with constant scanning of the status register increases by approximately 25 %.

For example: Number 2000, fastest setting, standard procedure: 15 ms + 25 % + 4 ms + 42 ms = 65 ms.

Under identical conditions - but with the measurement-value display deactivated via a control command - the response time drops to roughly 22 ms after completion of a measurement.

For example: Number 2000, fastest setting, standard procedure: 15 ms + 25 % + 4 ms + 22 ms = 45 ms.

With an IEEE488,
the 2329 can be configured such that it triggers an SRQ on the completion of a measurement or the occurrence of a measurement error. This eliminates the need for constant polling during the actual measurement. With an IEEE488 and 286/12 MHz, QBasic and SRQ mode, the measurement time rises to roughly 2 ms before a measurement (command decoding) and roughly 3 ms after the measurement. The actual measurement is ony prolonged by the REMOTE factor (see above).

For example: Number 2000, fastest setting, standard procedure: 15 ms + 20 % + 2 ms + 3 ms = 23 ms.

With an IEEE488 and constant polling of the status register,
the processor's capacity is heavily dependent on the performance of the PC processor, the IEEE488 card and the rate of program execution. This leads to incalculable delays. With a slow PC (286), a slow IEEE488 card and use of the QBasic interpreter, the measurement time increases by up to 40 %.

With an IEEE488 with 286/12 MHz, QBasic and continuous polling, the total measurement time is prolonged by approx. 2 ms before the actual measurement measurement (command decoding) and 9 ms following the actual measurement. The actual measurement time increases by up to 40 %. **This type of operation is extremely impractical.**

For example: 200 mΩ-range, number 2.000, fastest setting C$_{min}$, standard procedure:
$$15 \text{ ms} + 40 \text{ \%} + 2 \text{ ms} + 9 \text{ ms} = 32 \text{ ms.}$$
For example: 200 kΩ-range, number 20.000, fastest setting C$_{max}$, standard procedure:
$$756 \text{ ms} + 40 \text{ \%} + 2 \text{ ms} + 9 \text{ ms} = 1.069 \text{ ms.}$$

Under identical conditions, but with the measurement-value display deactivated via a control command, the response time following completion of a measurement does not decrease, because the 2329 has sufficient time to transfer the measurement result before it is displayed.

4.2. Identification menu

When the device is turned on, the following display appears:

RESISTOMAT TYPE 2329			
SN:	123456		$\rightarrow$ Serial number
VERSION:	V201202		$\rightarrow$ Software version
CAL:	C0001		$\rightarrow$ Calibration date*
DATE:	16.12.13		$\rightarrow$ Current date
TIME:	13:25:26		$\rightarrow$ Current time
LANG	CLK		CONT

Identification display following activation.

* The calibration number provides a count of the calibrations performed so far. This number also appears in the test log, and decisively determines whether or not the device needs to be reset.

This display appears for 5 seconds, unless a key is pressed in the meantime or a quick start (page 30) was activated.

Pressing the [F1] key (LANG) invokes the language menu where the required language can be selected.

Pressing the [F2] key (CLK) invokes the menu for setting the date and time.

Pressing the [F4] key (CONT) invokes the main menu.

If no key is pressed within 5 seconds following activation, the main menu is invoked.

4.2.1 Selecting a language

This menu is invoked by pressing the [F1] key while the identification menu is being displayed following activation of the device.

```
┌─────────────────────────────┐
│ SELECT   LANGUAGE           │
├─────────────────────────────┤
│                             │
│ LANGUAGE:      ENGLISH      │
│                             │
│                             │
│                             │
│                             │
│                             │
│                     ┌───────┤
│                     │ RETU  │
└─────────────────────┴───────┘
```

Language selection display

The operating language is selected in this menu.
The [←] and [→] cursor keys are used to select one of the following languages: GERMAN, ENGLISH, FRENCH.
Pressing the [F4] key (RETUrn) saves the language setting and effects a return to the main menu.

4.2.2 Setting the date and time

```
┌─────────────────────────────┐
│      DATE AND TIME          │
├─────────────────────────────┤
│ DATE:          16.12.2013   │
│ TIME:          15.24.35     │
│                             │
│                             │
├───────┬──────┬──────┬───────┤
│ INPUT │      │      │ RETU  │
└───────┴──────┴──────┴───────┘
```

Display of the menu for setting the date and time

The [↑] and [↓] cursor keys are used to select the required parameter. The selected parameter is displayed inversely.
The [POS1] key is used to select the 1st parameter in a window.
The [END] key is used to select the last parameter in a window.

A new value for the selected parameter can now be entered. Pressing the [F 1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to enter the date and time.
The [BSP] key is used to delete the character entered last.
The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.
The [ESC] key is used to cancel the current entry, and exit the input mode.
The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

Pressing the [F4] key (RETUrn) saves the set date and time - provided that they are valid - and effects a return to the main menu.

4.3 Main menu

4.3.1 Measurement stopped

S 1.1	S 1.2	S 1.3

200 OHM	1mA	23.4C	→	**Status line 1**

| 0 | 5 | SINGLE | AUTO | R | → | **Status line 2** |

S 2.1 S 2.2 S 2.3 S 2.4 S 2.5 S 2.6

$$112.45 \, \Omega$$

→ **Meas. value field**

| DATA | COMP | ENVE | PARA | → | **Footer** |

| F 1 | F 2 | F 3 | F 4 |
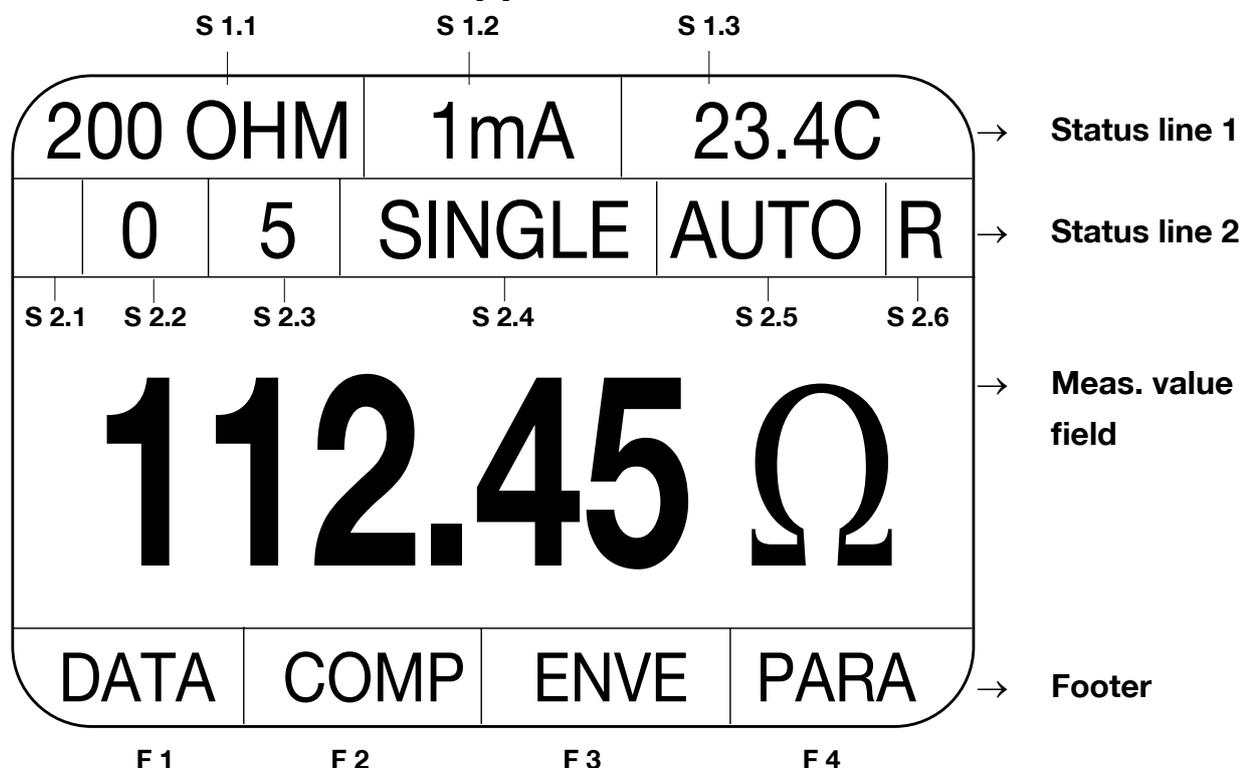
Display with a measurement stopped

Display in status line 1:	S 1.1	Measuring range
	S 1.2	Measuring current or 20 mV with dry-circuit measurement
	S 1.3	Temperature with temperature compensation or setpoint value with Δ % display
Display in status line 2:	S 2.1	Sample character (a sequential number from 0 to 9, only while a measurement is in progress)
	S 2.2	Error status (see page 138) or comparator evaluation
	S 2.3	The memory number loaded last
	S 2.4	Continuous or single-frame measurement
	S 2.5	Manual or automatic range selection
	S 2.6	R or Z measurement procedure

Display in the measurement-value field: The value measured last
Display in the footer: Designation of the function keys

The following entries are possible in this menu:

[F1] key (DATA):	This invokes the datalogger evaluation and configuration menus.
[F2] key (COMP):	This invokes the comparator evaluation and configuration menus.
[F3] key (ENVE):	This invokes the max./min, evaluation menu.
[F4] key (PARA):	This invokes the parameter selection menu.

[ENT] key:	Pressing the ENTER key invokes the code input menu.
[START] key:	Pressing this key commences a measurement.
[A/M] key:	This key is used to switch over between automatic and manual range selection.

The [RGE ↑] and [RGE ↓] keys are used to select ranges manually in the corresponding mode (not in the case of dry-circuit measurements).

4.3.2 Measurement started

S 1.1   S 1.2   S 1.3

| 200 OHM | 1mA | 32.4C | → **Status line 1** |

| 5 | 0 | 9 | SINGLE | AUTO | R | → **Status line 2** |

S 2.1 S 2.2   S 2.3   S 2.4   S 2.5   S 2.6

134.68 Ω

→ **Meas. value field**

| DATA | COMP | ENVE | PARA | → **Footer** |

F 1   F 2   F 3   F 4
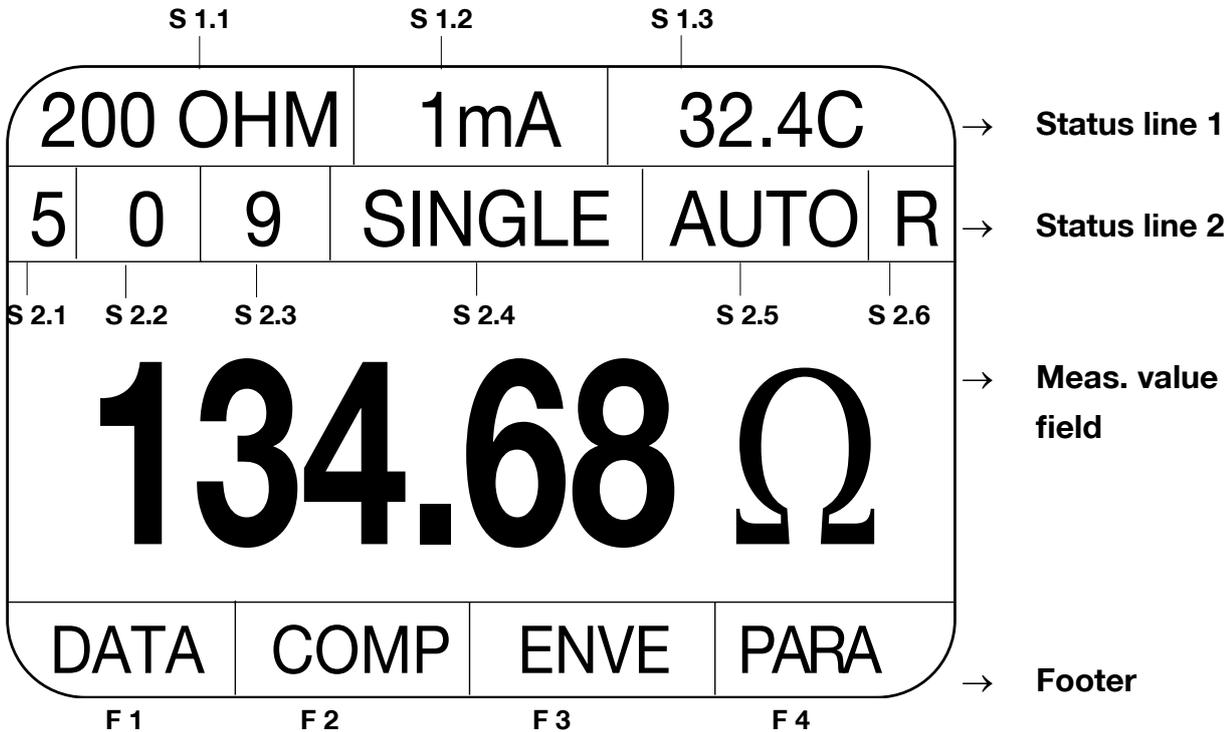
Display with a measurement in progress

Display in status line 1:	S 1.1	Measuring range
	S 1.2	Measuring current or 20 mV with dry-circuit measurement
	S 1.3	Temperature with temperature compensation or setpoint value with ∆ % display
Display in status line 2:	S 2.1	Sample character (a sequential number from 0 to 9)
	S 2.2	Error status (see page 138) or comparator evaluation
	S 2.3	The memory number loaded last
	S 2.4	Continuous or single-frame measurement
	S 2.5	Manual or automatic range selection
	S 2.6	R or Z measurement procedure

R = purely ohmic load
Z = load with inductive component

Display in the measurement-value field: Present measurement value
Display in the footer: Designation of the function keys

The following entries are possible in this menu:

F1 key [DATA]:   This starts/stops the datalogger if the datalogger setting menu has been released for access (page 42). When the datalogger is operating, the [F1] key designation is displayed inversely.

F2 key [COMP]:   This starts/stops the datalogger if the comparator setting menu has been released for access (page 45). When the comparator is operating, the [F2] key designation is displayed inversely.

F3 key [ENVE]:   This starts/stops the recording of max./min. values if the corresponding function has been released for access (page 35). While max./min. values are being recorded, the [F3] key designation is displayed inversely.

F4 key [PRINT]:   This starts/stops the printer if the printer configuration menu has been released for access (page 55). When the datalogger is operating, the [F4] key designation is displayed inversely.

[STOP] :   The present measurement is stopped.

[RGE ↑] and (RGE ↓):   These keys are used to select ranges in the manual mode if R has been set (not in the case of dry-circuit measurements).

4.3.3 Code input menu

This menu is invoked by pressing the [ENT] key in the main menu while a measurement is stopped.

```
┌─────────────────────────────────┐
│         CODE  INPUT             │
├─────────────────────────────────┤
│                                 │
│  PLEASE ENTER CODE              │
│  4 NUMBERS: ****                │
│                                 │
│                                 │
│                                 │
├───────┬───────┬───────┬─────────┤
│       │       │       │  RETU   │
└───────┴───────┴───────┴─────────┘
```

Display of the code
input menu

This menu is used to enter a 4 digits code in order to invoke the access menu (2609) or put the device into a defined state (9062) with the default values applying at the time of delivery.

Various items can be enabled and disabled in the access menu. Items marked with an asterisk (*) are in the enabled state.
If the device is put into a defined state using the code, so that the default values are restored, all user settings are deleted.

The code is entered with numeric keys [0] to [9].
Each numeric entry is confirmed by the display of an asterisk (*).
In accordance with the entered code, the access menu is invoked or the device assumes a defined, initial state.

The [ESC] key is used to cancel a code entry procedure.

Pressing the [F4]key (RETUrn) effects a return to the main menu.

4.3.3.1 Access menu

This menu is invoked following the entry of the correct code in the code input menu (chapter 4.3.3).

```
┌─────────────────────────┬───────┐
│        ACCESS           │  S 1  │
├─────────────────────────┴───────┤
│                                 │
│ *  MEAS. PARAMETER              │
│ *  DISPLAY                      │
│    COMPARATOR CONF.             │
│    COMPARATOR EVAL.             │
├───────┬───────┬───────┬─────────┤
│  ON   │  OFF  │  PLC  │  RETU   │
└───────┴───────┴───────┴─────────┘
```

Display of the access menu
(page 1)

```
┌─────────────────────────────┬──────┐
│          ACCESS             │ S 2  │
├─────────────────────────────┴──────┤
│                                    │
│ *  PRINTER                         │
│ *  TEMPERATURE COMP.               │
│    CALIBRATION                     │
│ *  MAN. RANGE SELECT               │
│                                    │
├────────┬────────┬────────┬─────────┤
│   ON   │  OFF   │  PLC   │  RETU   │
└────────┴────────┴────────┴─────────┘
```

Display of the access menu (page 2)

```
┌─────────────────────────────┬──────┐
│          ACCESS             │ S 3  │
├─────────────────────────────┴──────┤
│                                    │
│ *  SCALED INPUT                    │
│ *  DATALOGGER CONF.                │
│    MAX/MIN RESET                   │
│    CONTRAST                        │
│                                    │
├────────┬────────┬────────┬─────────┤
│   ON   │  OFF   │  PLC   │  RETU   │
└────────┴────────┴────────┴─────────┘
```

Display of the access menu (page 3)

```
┌─────────────────────────────┬──────┐
│          ACCESS             │ S 4  │
├─────────────────────────────┴──────┤
│                                    │
│ *  DISPLAY STATUS                  │
│    AUX. INPUT/OUTPUT               │
│    MAX/MIN START                   │
│ *  DATE/TIME                       │
│                                    │
├────────┬────────┬────────┬─────────┤
│   ON   │  OFF   │  PLC   │  RETU   │
└────────┴────────┴────────┴─────────┘
```

Display of the access menu (page 4)

```
┌─────────────────────────────────────┐
│         ACCESS            │   S 5    │
├───────────────────────────┴──────────┤
│                                      │
│  *  FAST START                       │
│  *  CALIBRATION                      │
│  *  MAN. RANGE SELECT                │
│                                      │
├────────┬────────┬────────┬───────────┤
│   ON   │  OFF   │  PLC   │   RETU    │
└────────┴────────┴────────┴───────────┘
```
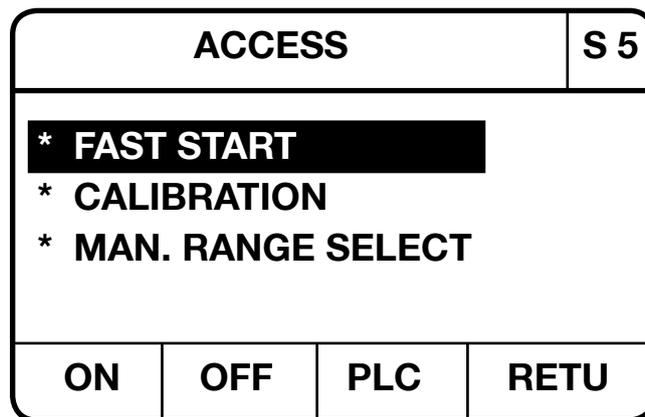
Display of the access menu (page 5)

Access to various other menus is enabled and disabled in this menu.

The following entries are possible in this menu:

[F1] key (ON):   The selected menu is enabled and marked with an asterisk .
[F2] key (OFF):   The selected menu is disabled.
[F3] key (PLC):   The PLC test menu is invoked.
[F4] key (RETUrn):   This effects a return to the main menu.

The [▲] and [▼] keys are used to switch between the various pages.

The [↑] and [↓] cursor keys are used to select the required parameter on the current page. The selected parameter is displayed inversely.

The [POS1] key is used to select the 1st parameter in a window.
The [END] key is used to select the last parameter in a window.

The MAN. RANGE SELECTION parameter (on page 5 of the menu) is enabled and disabled from the main menu using the RGE ↑ and RGE ↓ keys respectively.

4.3.3.2 Test PLC inputs and outputs

```
              ┌──────────────────────────────┐
              │        PLC  OUTPUTS          │
     Pin 1    │  PIN 1 .  .  .  .  .  PIN 17 │  Pin 17
              │  00010  010  10100  100      │
              │        PLC INPUTS            │  Pin 6 = Root of the relay
              │                              │        (not displayed)
              │  PIN 21 .  .  .  .  .  PIN 35│
              │  00100  1 0  01000  010      │  Pin 35
     Pin 21   ├────────┬────────┬────────┬───┤
              │  SET   │  RES   │ HOME   │RETU│
              └────────┴────────┴────────┴───┘
```
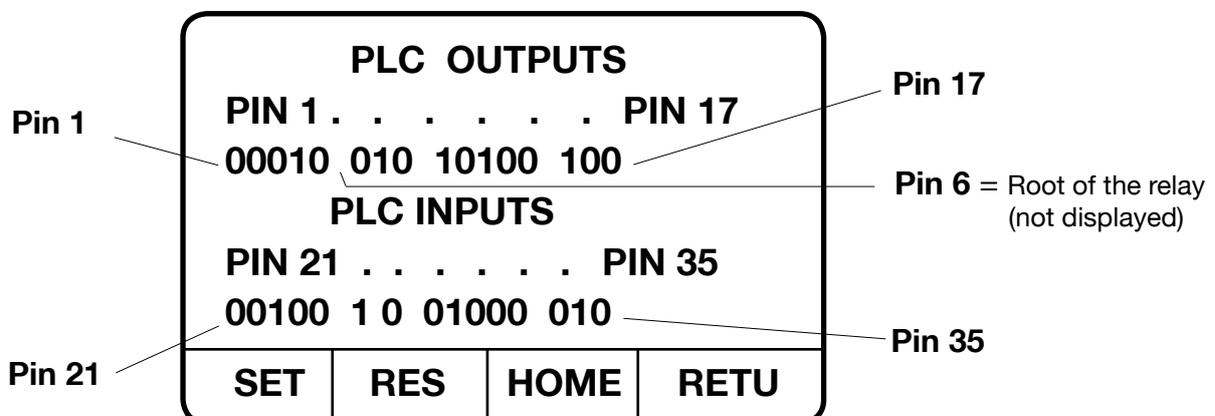
This menu is used to test the PLC interface. The input levels are indicated, and the output levels can be set and reset here.

This menu is invoked with the [F3] key (PLC) from the access menu.

The signals are present at the 37- pole SUB-MIN-D socket.
The inputs and outputs need to be connected and supplied from an external source. Pulse diagrams and pin assignments are provided in the chapter on the PLC interface on pageSeite 65.

The 16 outputs are allocated to pins 1 to 17.
Output sequence: S0, S1, S2, S3, S4
                                                          MEAS-RUN, MEAS-END, MEAS-ERR
                                                          EV1, EV2, EV3, EV4, EV5
                                                          OUT-AUX1, OUT-AUX2, OUT-AUX3

The 15 inputs are allocated to pins 21 to 35.
Input sequence: MEAS-1/0, COMP-1/0, DATA-1/0, EXT-1/0, DRU-1/0
                                                          LATCH, IN-AUX1, IN-AUX2, IN-AUX3, IN-AUX4,
                                                          SET0, SET1, SET2, SET3, SET4

Description and pin assignment (page 17)

[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn):   This effects a return to the access menu.

The [→] and [←] cursor keys are used to select the individual output pins.
The selected pin is displayed inversely.

[F1] key (SET):   The selected output pin is set to 1.
[F2] key (RES):   The selected output pin is reset to 0.

4.4. Function keys while a measurement is stopped
4.4.1 Datalogger evaluation menu
4.4.1.1 Display of the individual measurement values

BLOCK: 12	DATALOG.: 12
MEAS.	NUMBER: 15
MEAS. VAL.:	123.45 mOHM
SIZE:	625 (18)
DATE:	01.08.13
TIME:	13:12:15.34

INPUT	STAT	CONF	RETU

**Display of the
datalogger evaluation menu**
(display of the individual
measurement values)

The values stored in the datalogger can be viewed individually in this menu.

The following entries are possible:

[F4] key (RETUrn):   This effects a return to the main menu.
[F3] key (CONF):   This invokes the datalogger setting menu.
[F2] key (STAT):   This invokes the datalogger evaluation menu.

The [↑] and [↓] cursor keys are used to select the required parameter. The selected parameter is displayed inversely. Only the selected parameter can be changed.

The [POS1] key is used to select the 1st parameter in a window.
The [END] key is used to select the last parameter in a window.

Specifying the **MEAS**urement **NUMBER**:
The [→] and [←] cursor keys are used to increment and decrement the measurement value number.

Pressing the [F 1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to enter a measurement-value number between 1 and 20000.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

Specifying the **Block** number:
The [→] and [←] cursor keys are used to increment and decrement the block number.

Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to enter a block number ranging between 0 and 31.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

The [F2] key (STAT) is used to invoke the stochastic datalogger evaluation menu.

Note: The memory is capable of holding 20000 measurement values. A measurement value can be invoked and displayed by entering the corresponding number or by using the [→] and [←] cursor keys.

The memory capacity of 20000 measurement values can be divided into 32 differently sized blocks.

The "SIZE" parameter indicates the number of memory locations reserved for a block (e.g. 625) followed - in parentheses - by the number of measurement values currently stored in this block (e.g. 18).

The measurement values in a block can be evaluated statistically. The minimum, maximum and average values as well as the standard deviation can be displayed (chapter. 4.4.1.2). In addition to a number ranging from 0 ... 31, every block can also be assigned a 10 character ID (numeric entry via the keypad, alphanumeric entry via a PC).

4.4.1.2 Stochastic datalogger evaluation menu

BLOCK: 12	DATALOG 12
AVERAGE:	123.46 mOHM
MINIMUM:	122.31 mOHM
MAXIMUM:	124.18 mOHM
DEVIATION:	5.26 mOHM
SIZE:	625 (18)
INPUT	MEAS	CONF	RETU

Display of the stochastic datalogger evaluation menu

This menu is used for the stochastic evaluation of individual datalogger blocks.

The following entries are possible:

[F4] key (RETUrn):   This effects a return to the main menu.
[F3] key (CONF):   This invokes the datalogger setting menu.

Specifying the **Block** number:
The [→] and [←] cursor keys are used to increment and decrement the block number.

Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to enter a block number ranging between 0 and 31.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

The [F2] key (MEAS) invokes the datalogger evaluation menu for displaying individual measurement values.

4.4.2 Comparator evaluation menu

```
┌─────────────────────────────────┐
│  <<:        2                    │
│  < :        9                    │
│  = :        126                  │
│  > :        10                   │
│  >>:        4                    │
│  SUM:       151                  │
│ ┌──────┬──────┬──────┬────────┐ │
│ │ RES  │ LIM  │ CONF │ RETU   │ │
│ └──────┴──────┴──────┴────────┘ │
└─────────────────────────────────┘
```

**Comparator
evaluation menu
(with 4 limiting values)**

```
┌─────────────────────────────────┐
│                                 │
│  < :        9                    │
│  = :        126                  │
│  > :        10                   │
│                                 │
│  SUM:       145                  │
│ ┌──────┬──────┬──────┬────────┐ │
│ │ RES  │ LIM  │ CONF │ RETU   │ │
│ └──────┴──────┴──────┴────────┘ │
└─────────────────────────────────┘
```

**Comparator
evaluation menu
(with 2 limiting values)**

- With 2 limiting values:

<	:	All values	$<$	Limiting value 1		
=	:	All values	$\geqq$	Limiting value 1 and	$\leqq$	limiting value 2
>	:	All values	$>$	Limiting value 2		

- With 4 limiting values:

<<	:	All values	$<$	Limiting value 1		
<	:	All values	$\geqq$	Limiting value 1 and	$<$	than limiting value 2
=	:	All values	$\geqq$	Limiting value 2 and	$\leqq$	than limiting value 3
>	:	All values	$>$	Limiting value 3 and	$\leqq$	than limiting value 4
>>	:	All values	$>$	Limiting value 4		

The following entries are possible:

The [F4] key (RETUrn)   effects a return to the main menu
The [F1] key (RESet)   resets the current statistical values
The [F3] key (CONF)   invokes page 1 of the comparator setting menu (page 45)
The [F2] key (LIM)   invokes page 2 of the comparator setting menu (page 46)

4.4.3 Max/Min evaluation menu

```
┌──────────────────────────────────┐
│       MAX/MIN FUNCTION           │
├──────────────────────────────────┤
│ ████████████████████████████████ │
│ MAX/MIN :      OFF               │
│ MINIMUM :      123.45 OHM        │
│ MAXIMUM :      124.10 OHM        │
│ DIFF:            0.65 OHM        │
├────────┬──────┬──────┬──────────┤
│ RES    │      │      │  RETU    │
└────────┴──────┴──────┴──────────┘
```

Display of
max/min-
evaluation menu

The following entries are possible:

The [F1] key (RES) is used to reset the values.
The [F4] key (RETUrn) effects a return to the main menu.

The [→] and [←] cursor keys are used to activate and deactivate the MAX/MIN function.

4.4.4 Parameter selection menu

```
┌──────────────────────────────────┐
│ MEAS. PARAMETER          │ S 1 │ │
├──────────────────────────┴─────┐ │
│                                  │
│ DISPLAY                          │
│ COMPARATOR CONFIG.               │
│ DATALOGGER CONFIG                │
│ PRINTER                          │
│ TEMPERATURE COMP.                │
├────────┬──────┬──────┬──────────┤
│ SEL    │      │      │  RETU    │
└────────┴──────┴──────┴──────────┘
```

Display of the
parameter selection menu
(page 1)

```
┌──────────────────────────────────┐
│ INTERFACES               │ S 2 │ │
├──────────────────────────┴─────┐ │
│                                  │
│ STORE CONFIG.                    │
│ DISPLAY STATUS                   │
│ AUX. INPUT/OUTPUT                │
│ SCALED INPUTS                    │
│ CONTRAST                         │
├────────┬──────┬──────┬──────────┤
│ SEL    │      │      │  RETU    │
└────────┴──────┴──────┴──────────┘
```

Display of the
parameter selection menu
(page 2)

```
┌─────────────────────────────┬───────┐
│ CALIBRATION                 │  S 3  │
├─────────────────────────────┴───────┤
│                                      │
│                                      │
│                                      │
│                                      │
│                                      │
├────────┬────────┬────────┬───────────┤
│  SEL   │        │        │   RETU    │
└────────┴────────┴────────┴───────────┘
```
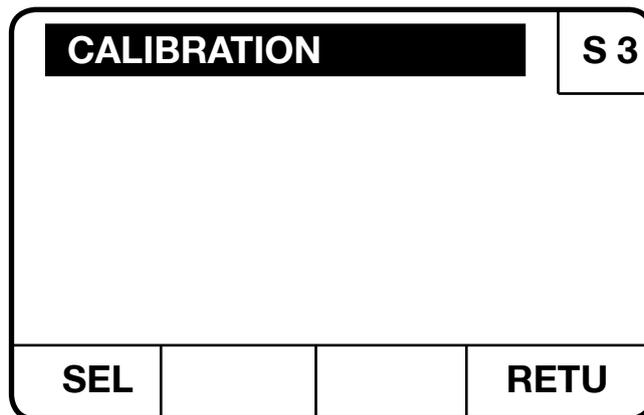
Display of the
parameter selection menu
(page 2)

This menu is used to select other menus.

The following entries are possible:

The [F4] key (RETUrn) effects a return to the main menu.

This menu display covers 3 pages.

The [↑] and [↓] cursor keys are used to select the required parameter on the current page. The selected parameter is displayed inversely.

The [POS1] key is used to select the 1st parameter in a window.
The [END] key is used to select the last parameter in a window.
Pressing the [F1] key (SELect) invokes the menu related to the selected parameter.

4.4.4.1 Measurement parameter menu
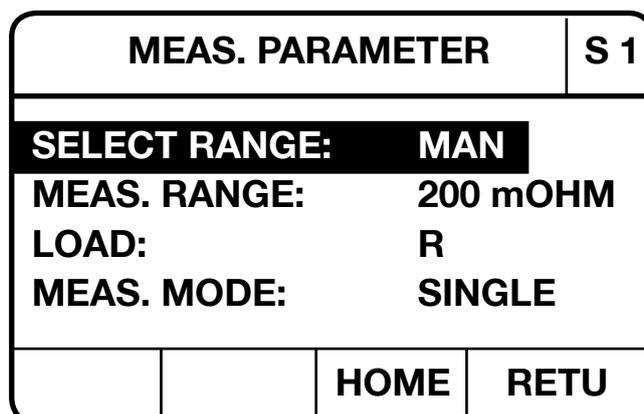
```
┌─────────────────────────────┬───────┐
│     MEAS. PARAMETER         │  S 1  │
├─────────────────────────────┴───────┤
│  SELECT RANGE:        MAN            │
│  MEAS. RANGE:         200 mOHM       │
│  LOAD:                R              │
│  MEAS. MODE:          SINGLE         │
├────────┬────────┬────────┬───────────┤
│        │        │  HOME  │   RETU    │
└────────┴────────┴────────┴───────────┘
```

Display of the
measurement parameter
menu
(page 1)

```
┌─────────────────────────────┬───────┐
│     MEAS. PARAMETER         │  S 2  │
├─────────────────────────────┴───────┤
│  AVERAGE:             100            │
│  AVER. MODE:          CONT           │
│  RESOLUTION:          2000           │
│  20 mV LIMITING:      OFF            │
├────────┬────────┬────────┬───────────┤
│ INPUT  │        │  HOME  │   RETU    │
└────────┴────────┴────────┴───────────┘
```
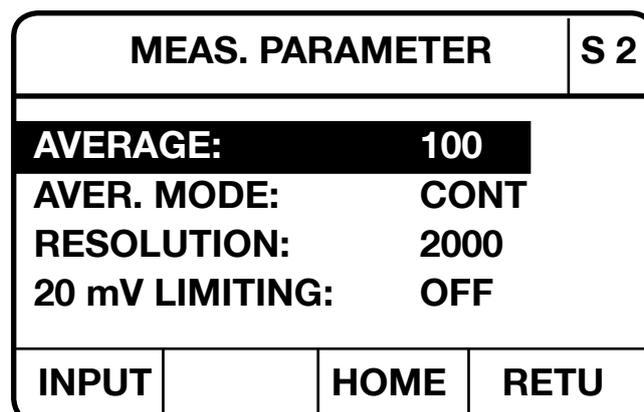
Display of the
measurement parameter
menu
(page 2)

```
┌─────────────────────────────────┐
│   MEAS. PARAMETER        │ S 3  │
│─────────────────────────────────│
│ A/D CONV:      STANDARD          │
│ MEAS. -SQ.:    SINGLE COMP.      │
│                                  │
│                                  │
│   INPUT   │      │ HOME │ RETU   │
└─────────────────────────────────┘
```

Display of the measurement parameter menu (page 3)

Various measurement parameters can be set in this menu.

The following entries are permissible:

The [F3] key (HOME) effects a return to the main menu.
Mit der [F4] key (RETUrn) effects a return to the parameter selection menu.

This menu display covers 3 pages.

The [▲] and [▼] keys are used to switch between the three pages.

The [↑] and [↓] cursor keys are used to select the required parameter on the current page. The selected parameter is displayed inversely.

The [POS1] key is used to select the 1st parameter in a window.
The [END] key is used to select the last parameter in a window.

Specifying the **SELECT RANGE**
The [→] and [←] cursor keys are used to select one of the following options:
MAN: The measuring range must be selected manually.
AUTO: The device automatically selects the appropriate measuring range.
On a change from MAN to AUTO, the device first selects the 200 kOHM range.
A change between MAN and AUTO can also be made with the A/M key in the main menu.

The following display appears in the AUTO mode:

```
┌─────────────────────────────────┐
│   MEAS. PARAMETER        │ S 1  │
│─────────────────────────────────│
│ SELECT RANGR:      AUTO          │
│ MIN. RGE:          200 mOHM      │
│ LOAD:              R             │
│ MEAS. MODE:        SINGLE        │
│─────────────────────────────────│
│      │ A-HI │ HOME │ RETU        │
└─────────────────────────────────┘
```

The currently smallest measuring range is indicated.

Display of the measurement parameter menu (page 1) when AUTO is selected

When automatic range selection is active, the permissible measuring ranges can be limited in order to optimize the measurement rate.
For example: A - HI = 200 Ω
                A - LO =   2 Ω
With these settings, the device only measures in the 2 Ω, 20 Ω and 200 Ω ranges.

Pressing the [F2] key (A-HI) displays the largest permissible measuring range. The F2 field is cleared and the F1 field is marked with (A-LO). Pressing the [F1] key effects a return to the display of the smallest permissible measuring range. The smallest/largest measuring ranges can be adjusted with the [→] and [←] cursor keys. A prerequisite here is that the smallest measuring range must always be smaller than the largest measuring range.

Selecting the **MEAS**uring **RANGE** in the MANual mode
The [→] and [←] cursor keys are used to select the required measuring range in the manual mode. The measuring range can also be selected with the [RGE↑] and [RGE↓] keys in the main menu. This is also possible while a measurement is in progress, if R has been set.
Possible measuring ranges: 200 mOHM, 2 OHM, 20 OHM, 200 OHM, 2 kOHM, 20 kOHM and 200 kOHM.

Selecting the **TEST OBJECT**
The [→] and [←] cursor keys are used to select one of the following options:
R   Measurement procedure for purely ohmic loads
Z   Measurement procedure for loads with an inductive component, such as coils, transformers
          and motor windings.

Selecting the **MEAS**urement **MODE**
The [→] and [←] cursor keys are used to select one of the following options:
SINGLE   The device only performs one single measurement.
CONTINUOUS The device continues performing measurements until it is stopped.

Specifying the number of **AVERAGES**
Pressing the [F1] key (INPUT) invokes the input mode.
Numeric keys [0] to [9] are used to specify the number of average values.
The [BSP] key is used to delete the character entered last.
The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.
The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

Selecting the type of **INDICATION**
The [→] and [←] cursor keys are used to set one of the following options:
MOVING   A moving average value is indicated on every conversion.
REFRESH   The average value is formed from the set number of measurement values in each
                       case and output subsequently.

Note
REFRESH   means that with a set number of 10, a new average value is displayed every 10
                       measurements. The first time an average value is formed, an S is displayed by the
                       measurement-value counter (see chapter. 4.3.1.); the subsequent average values are
                       counted from 0 to 9 etc.
MOVING   means that with a set number of 10, a new average value is displayed 10
                       measurements following the start of a measurement or the occurrence of a
                       measurement error (as described above). On every further internal measurement,
                       the values are used to form a new average value which is then displayed.

Specifying the **RESOLUTION**
The [→] and [←] cursor keys are used to set one of the following options:
20000   Resolution of 20000 (4 1/2 digit display).
  2000   Resolution of 2000 (3 1/2 digit display).

Specifying the **20 mV LIMIT**
The [→] and [←] cursor keys are used to set one of the following options:
ON   The 20 mV limit is active.
OFF   The 20 mV limit is inactive.

Note

Dry-circuit measurement in accordance with DIN IEC 512 Part 2:

Dry-circuit measurements and the 20 mV technique are always used for testing switches and plugs which operate at low voltages.

To verify the proper transfer of signals by plugs and switches, any extraneous layers which have formed must not be allowed to decompose during the measurement.

DIN IEC 512 Part 2 stipulate a maximum test voltage of 20 mV.

In the 20 mV mode, the total resistance of the test object and the lines connected to it must amount to at least 200 mΩ. If this value is fallen short of, the measurement current becomes too high and the device outputs an error (current transmitter overloaded!). As the resistance increases, the measurement current drops and the measured results become more uncertain, as the load on the A/D converter decreases.

The analog output cannot be used in the 20 mV mode (refer to measurement errors in chapter. 4.1.3).

Only one measuring range is available for dry-circuit measurements.

Only the display format is switched in accordance with the internal measurement resolution.

Specifying the number of **CONV**ersions for the A/D converter

The [→] and [←] cursor keys are used to set one of the following values:

|	
MINIMUM	Lowest number of conversions.
MEDIUM	2nd lowest number of conversions.
STANDARD	2nd highest number of conversions.
MAXIMAL	Highest number of conversions.
ITEST	Measurement current monitoring (continuity tester)

Note

This device is equipped with a very fast AD converter whose conversion time can be adjusted over 4 stages. The conversion time of each stage depends on the selected measurement range and resolution (refer to the measurement rate in chapter. 4.1.4)

Specifying the **MEAS**urement **PROC**edure

The [→] and [←] cursor keys are used to select one of the following options:

REF-COMP	Zero measurement for compensation of thermoelectric potentials.
NO COMP	No zero measurement (the values of the reference measurement are used).
SINGLE COMP	A zero measurement is only performed once at the start.
STANDARD	A zero measurement and a measurement with I or U are performed alternately.
I-Test	Measurement current monitoring (continuity tester).

Note:

Standard procedure

Reference compensation

This reference measurement
is stored in the device
together with the adjusted
range.

I

W   W   t

Zero measurement
with interrupted
current circuit

Start

Cable rupture
test

No compensation

I

W   W   t

Measurement

On single shot measurement
current at zero
on repeat measurement
repetition of the measurement
till the STOP key is pressed.

Start   Cable rupture
test
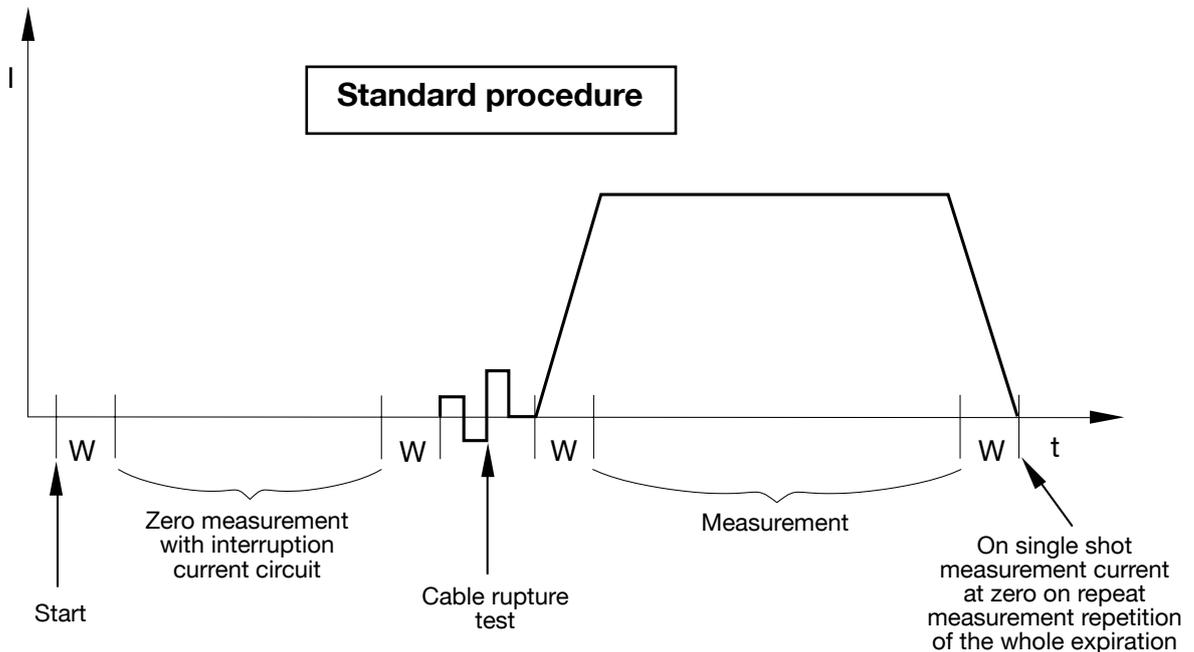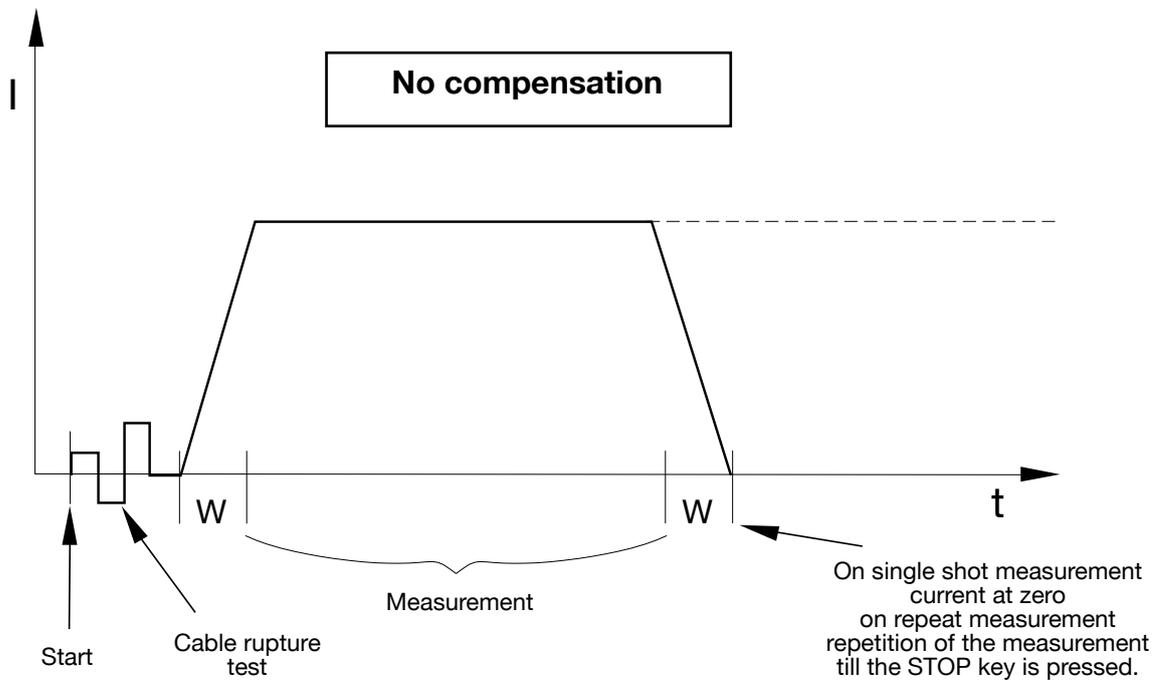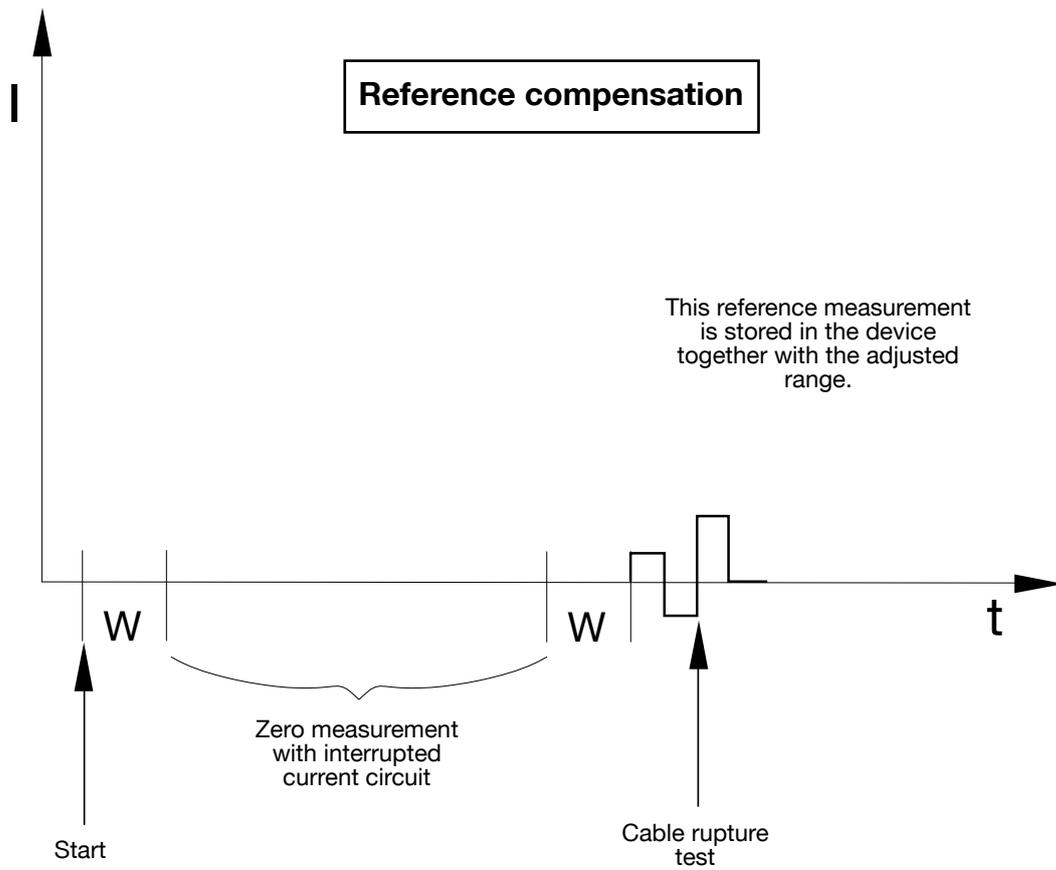
The values of the last reference measurement in the corresponding range are used to calculate the resistance.

Single compensation

I

W   W   W   W

Zero measurement
with interrupted
current circuit.

Start

Cable rupture
test

Measurement

On single shot
measurement current at
zero on repeat measurement
repetition of the
measurement till the STOP
key is pressed.

I-Test

I

W

Evaluation

t

Start

Cable rupture
test
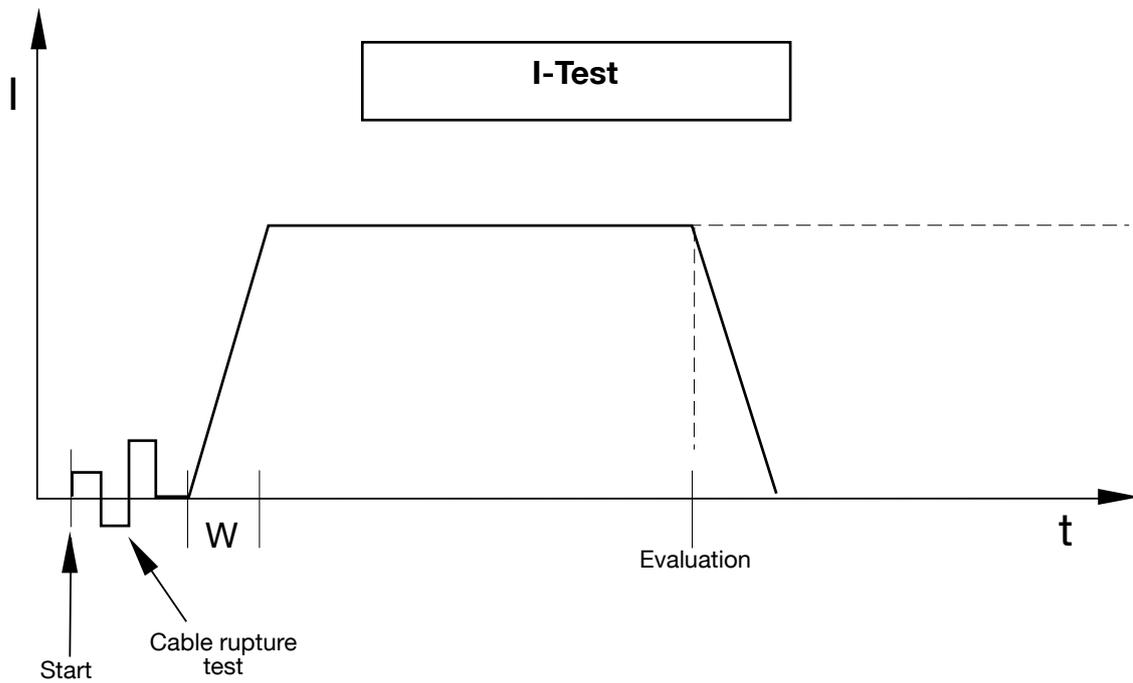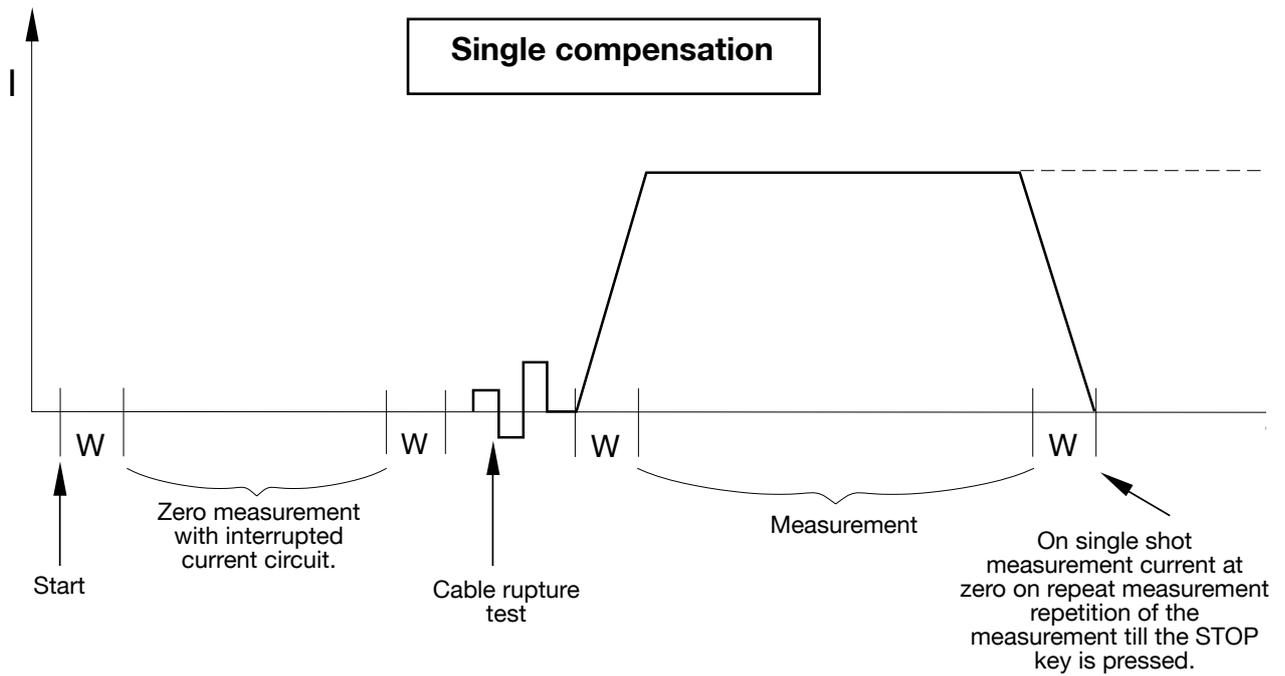
This measurement procedure is only a measurement current monitoring (continuity tester).
If the measurement current is o.k. you get at the display a large = in the meas. value field.

If the meas. current is to less or zero you get at the display a large > in the meas. value field.
The meas. range (meas. current) depends of the resistance of the test object.

At this meas. mode only manual range selection is possible. After a stable meas. current ensue the evaluation:

1.)   At 2 comparator limits   =   ->   meas. current   o.k.

                                              >   ->   meas. current   not o.k.

        Corresponding the PLC-signal will set.

2.)   At 4 comparator limits   =   ->   meas. current   o.k.

                                              >>   ->   meas. current   not o.k.

        Corresponding the PLC-signal will set.

This meas. mode you can also select via RS232 or IEEE488 interface with the instruction code FRES:MODE:ITEST. The meas. rate depends of the conversion settings.

	$C_{MINIMUM}$	C_{MEDIUM}	$C_{STANDARD}$	$C_{MAXIMAL}$
Meas. time at single shot and the 1. meas at continuous meas.	13 ms	21.5 ms	30 ms	37.5 ms
Meas. time from 2. meas. at continuous meas.	16 ms	32 ms	50.5	63.5 ms

C = Conversion settings (see chapter 4.4.4.1)

4.4.4.2 Datalogger setting menu

```
AVAIL MEMORY:   8230
DATALOGGER: OFF
BLOCK:     2   1234567890
SIZE:          100  (18)
FILTER:        ALL
DELETE:        BLOCK
INPUT  |        | HOME | RETU
```

Display of the datalogger setting menu

The parameters for the datalogger are set in this menu.

The following entries are possible:

[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn):   This effects a return to the parameter selection menu or the datalogger evaluation menu, depending on where the present menu was invoked from.

The [↑] and [↓] cursor keys are used to select the various parameters in the menu. The selected parameter is displayed inversely. Only the selected parameter can be changed.

The [POS1] key is used to select the 1st parameter in the window.
The [END] key is used to select the last parameter in the window.

The size of the **available memory** which has not yet been assigned to a block is indicated.
The **DATALOGGER** can be activated and deactivated with the [→] and [←] cursor keys respectively.

Specifying a **BLOCK**:
The BLOCK parameter consists of two values: The block number and an ID with a maximum length of 10 digits.

The [←] and [→] cursor keys are used to select the block number and ID. The selected value is displayed inversely. Only the selected value can be changed.

Specifying a BLOCK number:
Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to enter a value between 0 and 31 for the block number.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

Specification a BLOCK ID:
Pressing the [F1] key (INPUT) invokes the input mode.
Numeric keys [0] to [9] and the [.] key are used to enter the block ID.
The same ID cannot be assigned to more than one block.

The [BSP] key is used to delete the character entered last.
The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.
The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

Specifying the **SIZE**:
Pressing the [F1] key (INPUT) invokes the input mode.
Numeric keys [0] to [9] are used to enter a value of between 0 and 20000 for the size of the selected block (0 means that the block is inactive).
The total size of all 32 blocks must not exceed a value of 20000. The total size can be reduced at a later stage if the memory is not yet fully allocated (the number of allocated memory locations is displayed in parentheses).

The [BSP] key is used to delete the character entered last.
The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.
The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

Selecting a **FILTER**:
The [→] and [←] cursor keys are used to set the following values:
ALL   :   Save all values.
GOOD   :   Only save good values (those within the comparator limits).
BAD   :   Only save bad values (those outside the comparator limits).
Xth VALUE   :   Save every Xth measured value.
hh:mm:ss   :   Save at the time interval specified in hours, minutes and seconds.
dR xx.xxx Ω :   Save a value if its difference to the previous value exceeds dR.

Setting the X parameter:
Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to enter the required value.

Value range: 2 to 9999

The [BSP] key is used to delete the character entered last.
The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.
The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

Setting the time interval:
Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to enter the required value.

Value range: 00:00:01 to 99:59:59

The [BSP] key is used to delete the character entered last.
The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.
The [F1] key (s), [F2] key (m) or [F3] key (h) is used to save the input value - provided that it is valid - and exit the input mode.

Specifying the dR parameter:
Pressing the [F1] key (INPUT) invokes the input mode.

The function keys are redefined in this case. | **mOHM** | **OHM** | **kOHM** | |

Numeric keys [0] to [9] and the [.] key are used to enter the dR value.
(5 digits plus the decimal point)

Value range: 0.01 mΩ to 200 kΩ

The [BSP] key is used to delete the character entered last.
The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.
The [F1] key (mOHM), [F2] key(OHM) or [F3] key(kOHM) is used to save the input value - provided that it is valid - and exit the input mode.

DELETE datalogger:
If this parameter is selected, the [F1] key (DEL1) and [F2] key
(DEL2) are also activated.

The [→] and [←] cursor keys are used to set the following values:

ALL   The entire datalogger is deleted.
BLOCK   The selected block is deleted.

Pressing the [F1] key (DEL1) and the [F2] key (DEL2) in turn deletes the datalogger or the selected block. The (DEL2) key serves for acknowledgement here.

4.4.4.3 Comparator setting menu

```
┌─────────────────────────────────┬───────┐
│        COMPARATOR               │  S 1  │
├─────────────────────────────────┴───────┤
│                                          │
│ █COMPARATOR:  OFF█                       │
│  COUNT OF LIMITS :  2                    │
│  RELAYS:          ON                     │
│  ON ERROR:        NONE                    │
│                                          │
├───────────┬────────┬─────────┬───────────┤
│  INPUT    │        │  HOME   │  RETU     │
└───────────┴────────┴─────────┴───────────┘
```

Comparator-
setting menu
page 1

The comparator is configured in this menu.

The following entries are possible:

[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn):   This effects a return to the parameter selection menu or the comparator evaluation
                      menu, depending on where the present menu was invoked from.

The [↑] and [↓] cursor keys are used to select the various parameters in the menu. The selected parameter is displayed inversely. Only the selected parameter can be changed.

The [POS1] key   is used to select the 1st parameter in the window.
The [END] key   is used to select the last parameter in the window.

The [←] and [→] cursor keys are used to turn the
COMPARATOR
ON and
OFF.

Note: When the comparator is on, the comparator evaluation

               <<   **<**   **=**   **>**   **>>**

               appears in the large measurement display, depending on the selected display menu (page 49).
               If "OHM" has been selected, a small display of the evaluation appears in the error window.

The [←] and [→] cursor keys are used to set the
COUNT OF LIMITERS to
2 or
4.

Note: This determines the number of selection stages.
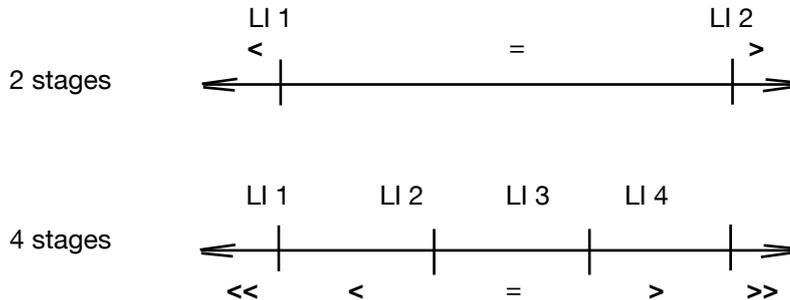
The [←] and [→] cursor keys are used to turn the **RELAY** ON and OFF.

Note: The PLC outputs should be used for rapid measurements, to prevent the relay contacts from being subjected to unnecessary wear.
The relay contacts have a service life of approximately 10^9 switching operations in the no-load state, and approximately 10^6 switching operations at a load of 30 W.
Irrespective of this setting, the PLC outputs are always active.

The [←] and [→] cursor keys are used to define the comparator's response
ON ERROR:
NONE   :   No response in the event of an error
> With 2 limiting values: The object under test is evaluated as being too large.
>> With 4 limiting values: The object under test is evaluated as being too large.

The [▼] key is used to display page 2 of the list of parameters in the comparator menu.

Note: An error is indicated if the connections to the object under test are disrupted, a measurement line is interrupted, an incorrect measuring range has been set, or if any other reason prevents the object under test from being measured.

COMPARATOR	S 2
LLI : **12.34 OHM**	
ULI : 125.67 OHM	
INPUT HOME RETU	

Comparator setting menu page 2
(if 2 limiting values have been set)

COMPARATOR	S 2
LI 1 : **12.34 OHM**	
LI 2 : 18.56 OHM	
LI 3 : 73.30 OHM	
LI 4 : 123.50 OHM	
INPUT HOME RETU	

Comparator- setting menu page 2
(if 4 limiting values have been set)

The comparator limits can be specified here.

The following entries are possible:

F3] key (HOME):   This effects a return to the main menu.

[F4] key (RETUrn):   This effects a return to the parameter selection menu or the comparator evaluation menu, depending on where the present menu was invoked from.

The [↑] and [↓] cursor keys are used to select the various parameters in the menu. The selected parameter is displayed inversely. Only the selected parameter can be changed.

The [POS1] key is used to select the 1st parameter in the window.
The [END] key is used to select the last parameter in the window.

Pressing the [F1] key (INPUT) invokes the input mode.
The function keys are redefined in this case.

mOHM	OHM	kOHM	

Numeric keys [0] to [9] and the decimal key [.] are used to modify the selected parameter value.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

Pressing the [F1] key (mOHM), [F2] key (OHM) or [F3] key (kOHM) completes the current entry. If valid, the entered value is saved and the input mode is exited.

Pressing the [▲] key invokes page 1 of the list of parameters in the comparator menu.
This does not apply if the present menu (comparator setting menu, page 2) has been invoked using the [F2] key (LIM).

4.4.4.4 Temperature compensation menu

TEMP. COMP. :	**OFF**
MEASUREMENT :	MAN
REF. TEMP. :	20.0 C
TEMPERATURE :	27.2 C
COEFFIC. :	3980 ppm/K

INPUT	COEF	HOME	RETU
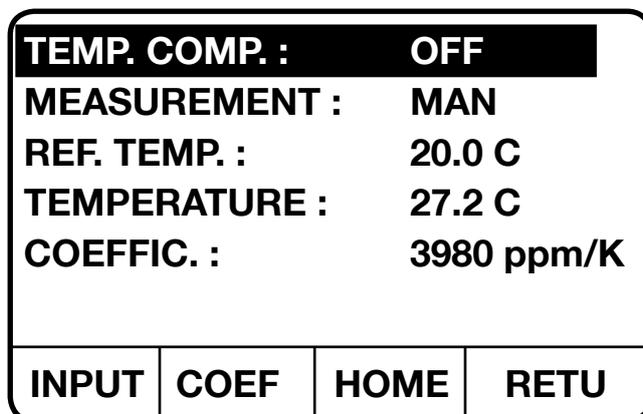
Display of the temperature compensation menu

The temperature compensation parameters are set in this menu.

The following entries are possible:

F3] key (HOME):   This effect a return to the main menu.

[F4] key (RETUrn):   This effects a return to the parameter selection menu or the comparator evaluation menu, depending on where the present menu was invoked from.

The [↑] and [↓] cursor keys are used to select the various parameters in the menu. The selected parameter is displayed inversely. Only the selected parameter can be changed.
The [POS1] key is used to select the 1st parameter in the window.
The [END] key   is used to select the last parameter in the window.

Activation/deactivation of **TEMP. COMP.**
The [→] and [←] cursor keys are used to set the following parameters:
ON   Temperature compensation is on.
OFF   Temperature compensation is off.

Activation of **MEASUREMENT**
The [→] and [←] cursor keys are used to set the following parameters:
Pt100   Temperature recording with a Pt100
U_IN   Temperature recording via the voltage input
I_IN   Temperature recording via the current input
MAN   Manual entry of the temperature

Entry and display of the **TEMPERATURE**
During RECORDING with a Pt100 or a transmitter, the measured temperature is displayed here.
During manual temperature compensation, the temperature is entered here manually.

Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] and the [**.**] key are used to enter the temperature in ° C .
The [BSP] is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.
The [ESC] key is used to cancel the current entry, and exit the input mode.
The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

COEFficient
The selected temperature coefficient is displayed in ppm/K (parts per million/Kelvin).

Specifying the **REFERENCE TEMPERATURE**
Pressing the [F1] key (INPUT) invokes the input mode.
Numeric keys [0] to [9] and the [**.**] key are used to enter the temperature in ° C.
The [BSP] key is used to delete the character entered last.
The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.
The [ESC] key is used to cancel the current entry, and exit the input mode.
The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

Note: The reference temperature is used to standardize the measured values. A temperature of 20 °C is recommended by the Association of German Electrical Engineers for this purpose. In other words, the temperature coefficient (TC) is used to convert the resistance of a test object at a temperature of x °C to a value corresponding to the reference temperature of 20 °C, and this value is then displayed. A reference temperature of 25 °C is also used in certain cases (e.g. by manufacturers in the USA).

TC 1 :	1600	TC 6 :	4030
TC 2 :	1700	TC 7 :	4500
TC 3 :	2400	TC 8 :	4800
TC 4 :	3100	TC 9 :	6000
TC 5 :	3980	TC10 :	6500
INPUT		**HOME**	**RETU**

**Display of the menu
for selecting the
temperature coefficient**

The [↑] and [↓], [→] and [←] cursor keys are used to select the required coefficient. The selected coefficient is displayed inversely.

The [POS1] key is used to select TC1.

The [END] key is used to select TC10.

A selected coefficient can also be changed.

Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] and the [.] key are used to enter a new coefficient in ppm/K.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

The [ENT] key is used to save the input value - provided that it is valid - and exit the input mode.

Note: The temperature coefficient (TC) indicates the rate at which the resistance of a material changes with
the temperature: e.g.   Copper   3980 ppm/$_K$ $\widehat{=}$ 0.398 %/$_K$
    Brass 63   1600 ppm/$_K$ $\widehat{=}$ 0.160 %/$_K$
The TC of metals and metal alloys is positive and approximately linear.

The [F4] key (RETUrn) saves the selected coefficient and effects a return to the temperature compensation menu.

The [F3] key (HOME) saves the selected coefficient and effects a return to the main menu.

4.4.4.5 Display menu

```
┌─────────────────────────────────┐
│   DISPLAY MENU                   │
│─────────────────────────────────│
│ ▐DISPLAY :       d%         ▌    │
│  SP. VAL :       134.56 mOHM     │
│                                  │
│─────────────────────────────────│
│  INPUT  │     │ HOME │ RETU      │
└─────────────────────────────────┘
```
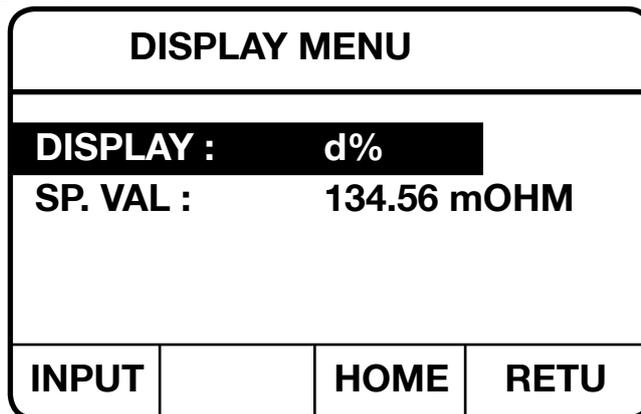
Display menu
(DISPLAY parameter has been selected)

The type of measurement display is selected in this menu.

The setpoint value needs to be entered for the d% (Delta%) display. The setpoint value is only indicated if d% has been selected.

The following entries are possible:

[F3] key (HOME): This effects a return to the main menu.

[F4] key (RETUrn): This effects a return to the parameter selection menu.

The [↑] and [↓] cursor keys are used to select the various parameters in the menu. The selected parameter is displayed inversely. Only the selected parameter can be changed.

The [POS1] key is used to select the 1st parameter in the window.

The [END] key is used to select the last parameter in the window.

Selecting the **DISPLAY**

The [←] and [→] cursor keys are used to select one of the following options:

OHM   Measurement display in ohms
           (When the comparator is on, the evaluation >>, >, =, <, << is displayed in the error window.)

d%   Display of the measured value as Delta% of a setpoint value

EVALUATION   When the comparator function is active, a large display can be selected for the evaluation
            (>>, >, =, <, <<).

Specifying a **SETPOINT VALUE**:
Pressing the [F1] key (INPUT) invokes the input mode, where a new value can be entered.
The [F] keys are redefined as follows:

```
┌─────────────────────────────────┐
│        DISPLAY MENU             │
├─────────────────────────────────┤
│  DISPLAY :        d%            │
│ ▐ SP. VAL.:     134.56 mOHM ▌   │
│                                 │
├──────────┬────────┬────────┬────┤
│  mOHM    │  OHM   │ kOHM   │    │
└──────────┴────────┴────────┴────┘
```

Display menu (SETPOINT VALUE input has been selected)

Numeric keys [0] to [9] and the [.] key are used to enter a new setpoint value.

The [BSP] key is used to delete the character entered last.

The [ESC] key is used to cancel the current entry, and exit the input mode. The original value is retained in this case.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

Pressing the [F1] key (mOHM), [F2] key (OHM) or [F3] key (kOHM) completes the entry, saves the new value if it is valid, and exits the input mode.

4.4.4.6 Interface menu

```
┌─────────────────────────────────┐
│       INTERFACE MENU            │
├─────────────────────────────────┤
│  INTERFACE:     IEEE488         │
│                                 │
│                                 │
├──────────┬────────┬────────┬────┤
│  CONF    │        │ HOME   │RETU│
└──────────┴────────┴────────┴────┘
```

Selection of the interface

The following entries are possible:
[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn):   This effects a return to the parameter selection menu.

The [←] and [→] cursor keys are used to select one of the following options:
IEEE 488   The device can be operated via the IEEE488 interface, provided that an IEC-bus board has been installed (optional).
RS232   The device can be operated via the RS232 interface.

The [F1] key (CONF) invokes the configuration menu for the currently selected interface.

IEEE488 Configuration menu

```
┌─────────────────────────────────┐
│      CONFIG.   IEEE488          │
├─────────────────────────────────┤
│                                 │
│  ADRESS :        9              │
│  TRIGGER :      PASSIVE         │
│                                 │
│                                 │
│  ┌──────┬──────┬──────┬──────┐  │
│  INPUT  │      HOME  │ RETU     │
└─────────────────────────────────┘
```
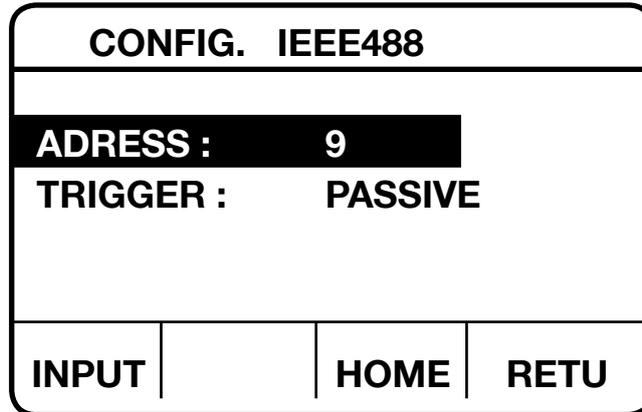
Display of the IEEE488
configuration menu

The IEEE488 interface is configured in this menu.

The following entries are possible:

[F1] key (INPUT):   This effects a return to the input mode.
[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn): This effects a return to the interface selection menu.

The [↑] and [↓] cursor keys are used to select the various parameters in the menu. The selected parameter is displayed inversely. Only the selected parameter can be changed.

The [POS1] key is used to select the 1st parameter in the window.

The [END] key is used to select the last parameter in the window.

Setting the **ADDRESS**:
Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to enter a new address having a value of between 1 and 31.

The [BSP] key is used to delete the character entered last.

The [ESC] key is used to cancel the current entry, and exit the input mode. The original value is retained in this case.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

Pressing the [ENT] key completes the entry, saves the new value if it is valid, and exits the input mode.

Selecting a **TRIGGGER** :
The [←] and [→] cursor keys are used to select one of the following options:
ACTIVE
PASSIVE

RS232 Configuration menu

```
┌─────────────────────────────────────┐
│     CONFIG.  RS 232                  │
├─────────────────────────────────────┤
│                                      │
│  FORMAT :      8DA 1PA 1ST           │
│  BAUD RATE :   9600                  │
│  PARITY :      ODD                   │
│  CHAR. DELAY:  OFF                   │
│                                      │
├──────────┬──────────┬───────┬───────┤
│          │          │ HOME  │ RETU  │
└──────────┴──────────┴───────┴───────┘
```
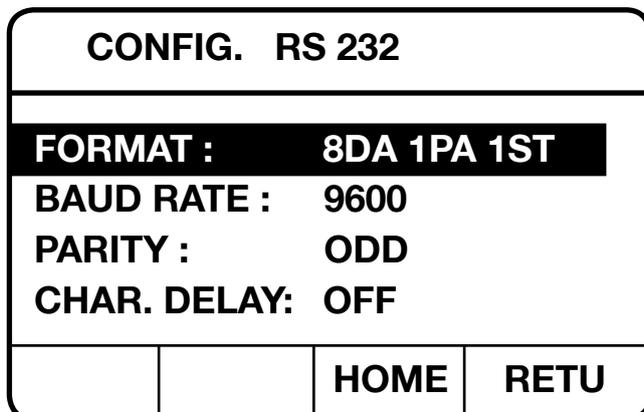
Display of the RS232 configuration menu

The RS232 interface is configured in this menu.

The following entries are possible:
[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn):   This effects a return to the interface selection menu.

The [↑] and [↓] cursor keys are used to select the various parameters in the menu. The selected parameter is displayed inversely. Only the selected parameter can be changed.

The [POS1] key is used to select the 1st parameter in the window.

The [END] key is used to select the last parameter in the window.

Selecting a **FORMAT**:
The [←] and [→] cursor keys are used to select one of the following options:
8 DAta bits   0 PArity bits   1 STop bit
7 DAta bits   0 PArity bits   2 STop bit
7 DAta bits   1 PArity bits   1 STop bit
8 DAta bits   0 PArity bits   2 STop bit
8 DAta bits   1 PArity bits   1 STop bit

Setting the **BAUD RATE**:
The [←] and [→] cursor keys are used to select one of the following values:
38400
19200
 9600
 4800
 2400
 1200
  600
  300

Setting the **PARITY**:
The [←] and [→] cursor keys are used to select one of the following options:
EVEN
ODD

Setting the **CHAR**acter **DELAY**:
The [←] and [→] cursor keys are used to select one of the following options:
ON
OFF

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4.4.4.7 Device setting menu

```
┌─────────────────────────────────┐
│      STORE/LOAD CONFIG.          │
├─────────────────────────────────┤
│                                  │
│   STORE NUMBER:  12              │
│   LOAD NUMBER:    8              │
│   LABEL ST.:      1234567890     │
│   LABEL LD:       0987654321     │
├────────┬────────┬────────┬───────┤
│ INPUT  │ STOR   │ LOAD   │ HOME  │
└────────┴────────┴────────┴───────┘
```
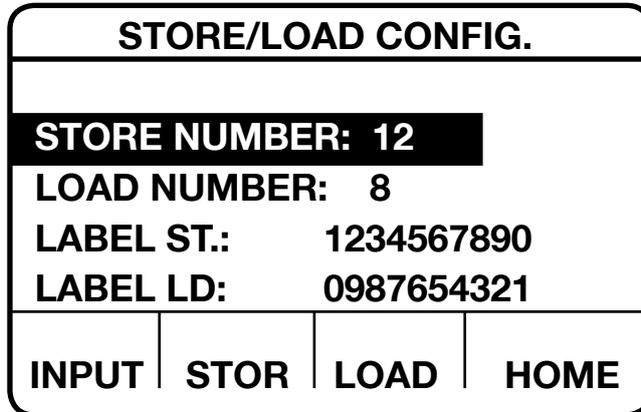
Display for saving and loading device settings

Note

If the changeover is made by the PLC inputs, the datalogger block will be changed as well.
If the changeover is made by the keypad, the datalogger block will not be changed.

The device settings can be saved and loaded from this menu.

The following entries are possible:

[F4] key (HOME):　　　This effects a return to the main menu.

The [↑] and [↓] cursor keys are used to select the various parameters in the menu. The selected parameter is displayed inversely. Only the selected parameter can be changed.

The [POS1] key is used to select the 1st parameter in the window.

The [END] key is used to select the last parameter in the window.

STORE NUMBER.　Here, you can enter a number between 0 and 31 under which the device setting is to be saved (the number can also be set with the [→] and [←] cursor keys).

Pressing the [F1] key (INPUT) invokes the input mode, where you can enter a new number.

Numeric keys [0] to [9] are used to enter a new value.

The [BSP] key is used to delete the character entered last.

The [ESC] key is used to cancel the current entry, and exit the input mode. The original value is retained in this case.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

Pressing the [ENT] key completes the entry, saves the new value if it is valid, and exits the input mode.

LOAD NUMBER.　A number between 0 and 31 is entered here to load the corresponding device setting (the [→] and [←] cursor keys can also be used for this purpose). The default settings are stored under number 32 (which is labelled accordingly).

Pressing the [F1] key (INPUT) invokes the input mode, where a new number can be entered.

Numeric keys [0] to [9] are used to enter a new value.

The [BSP] key is used to delete the character entered last.
The [ESC] key is used to cancel the current entry, and exit the input mode.
The original value is retained in this case.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

Pressing the [ENT] key completes the entry, saves the new value if it is valid, and exits the input mode.

LABEL ST. An ID assigned to SAVE NO. and having a maximum length of 10 characters is displayed here. This ID can be modified. Different SAVE NOS. cannot be assigned the same ID.

Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] and the [.] key are used to enter a new ID.

The [BSP] key is used to delete the character entered last.

The [ESC] key is used to cancel the current entry, and exit the input mode. The original value is retained in this case.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

Pressing the [ENT] key completes the entry, saves the new value if it is valid, and exits the input mode.

LABEL LD.   An ID assigned to LOAD NO. and having a maximum length of 10 characters is displayed here. This ID can be modified. Different LOAD NOS. cannot be assigned the same ID.

Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] and the [.] key are used to enter a new ID.

The [BSP] key is used to delete the character entered last.

The [ESC] key is used to cancel the current entry, and exit the input mode. The original value is retained in this case.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

Pressing the [ENT] key completes the entry, saves the new value if it is valid, and exits the input mode.

Note: If a PC keyboard is used for input, alphanumeric values up to 10 characters long can be used as IDs for the various device settings.
If the device keypad is used for input, only numerical values can be entered as IDs.

Pressing the [F2] key (SAVE) saves the device setting currently selected under the number indicated by SAVE NO.

Pressing the [F3] key (LOAD) loads the device setting indicated by LOAD NO. and invokes the main menu.

4.4.4.8 Printer menu

```
┌─────────────────────────────────────┐
│ PRINT:   OFF │ TC:       OFF        │
│ NUM.:    ON  │ LAB.:     ON         │
│ DATE:    OFF │ TIME:     OFF        │
│ MV/HEAD:    1000                     │
│ LABEL:      0123456789               │
│ INTERVAL:   hh:mm:ss                 │
├────────┬────────┬────────┬──────────┤
│ INPUT  │  RES   │ HOME   │  RETU    │
└────────┴────────┴────────┴──────────┘
```

Display of the printer menu

The printing parameters are set in this menu.

The following entries are possible:

[F3] key (HOME): This effects a return to the main menu.
[F4] key (RETUrn): This effects a return to the parameter selection menu.

The [↑] and [↓] cursor keys are used to select the various parameters in the menu. The selected parameter is displayed inversely. Only the selected parameter can be changed.

The [POS1] key is used to select the 1st parameter in the window.
The [END] key is used to select the last parameter in the window.

Activating/deactivating the **PRINT**ING functinon
The [→] and [←] cursor keys are used to set the following parameters:
ON   The printing function is active.
OFF   The printing function is inactive.

Activating/deactivating the **NUM**ERATOR
The [→] and [←] cursor keys are used to set the following parameters:
ON   The numerator is printed out.
OFF   The numerator is not printed out

Activating/deactivating the **TC**
The [→] and [←] cursor keys are used to set the following parameters:
ON   The temperature coefficient is printed out (if temperature compensation is active).
OFF   The temperature coefficient is not printed out.

Activating/deactivating the **LABEL**
The [→] and [←] cursor keys are used to set the following parameters:
ON   The LABEL is printed out.
OFF   The LABEL is not printed out.

Activating/deactivating the **DATE**
The [→] and [←] cursor keys are used to set the following parameters:
ON   The date is printed out.
OFF   The date is not printed out.

Activating/deactivating the **TIME**
The [→] and [←] cursor keys are used to set the following parameters:
ON   The time is printed out.
OFF   The time is not printed out.

Specifying the **MV/HEAD**er
Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to specify the number of measured values after which a header is to be printed out.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

Pressing the [ENT] key saves the new value if it is valid, and exits the input mode.

Entering the **LABEL**
Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] and the [.] key are used to enter an ID having a maximum length of 10 characters.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

Pressing the [ENT] key saves the new value if it is valid, and exits the input mode.

Specifying the time **INTERVAL** for the printout.

Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to enter the required values.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

Pressing the [ENT] key saves the new value if it is valid, and exits the input mode.

Pressing the [F2] key (RES) resets the numerator to 0.

4.4.4.9 Status selection menu

```
┌─────────────────────────────┬──────┐
│   SEL. STATUS DISP.         │ S 1  │
├─────────────────────────────┴──────┤
│ ▐MEAS. RANGR:         ON▌          │
│  MEAS. CURRENT/20mV :  OFF         │
│  TEMP. / SP. VAL.:     ON          │
│                                    │
│       ┌──────┬──────┐              │
│       │ HOME │ RETU │              │
└───────┴──────┴──────┴──────────────┘
```

Display of the status selection menu (page 1)

```
┌─────────────────────────────┬──────┐
│   SEL. STATUS DISP.         │ S 2  │
├─────────────────────────────┴──────┤
│ ▐SAMPLE SIGN:        ON▌           │
│  SINGLE / CONT.:     OFF           │
│  MAN. / AUTO:        ON            │
│  LOAD:               OFF           │
│       ┌──────┬──────┐              │
│       │ HOME │ RETU │              │
└───────┴──────┴──────┴──────────────┘
```

Display of the status selection menu (page 2)

This menu is used to select the status messages to be displayed in the main menu. Except for error messages, all other status messages can be activated/deactivated here.

The following entries are possible:
[F3] key (HOME): This effects a return to the main menu.
[F4] key (RETUrn): This effects a return to the parameter selection menu.

The [↑] and [↓] cursor keys are used to select the various parameters in this menu. The selected parameter is displayed inversely. Only the selected parameter can be changed.

The [POS1] key is used to select the 1st parameter in the window.

The [END] key is used to select the last parameter in the window.

The menu display consists of 2 pages.

The [▲] and [▼] keys are used to change from one page to the other.

Parameters on page 1:

Activating/deactivating the **MEAS**urement **RANGE** display
The [→] and [←] cursor keys are used to set the following parameters:
ON   The measurement range is indicated.
OFF   The measurement range is not indicated.

Activating/deactivating the **MEAS**urement **CURRENT / 20mV** display
The [→] and [←] cursor keys are used to set the following parameters:
ON   The measurement current or 20mV is indicated.
OFF   The measurement current or 20mV is not indicated.

Note: During dry-circuit measurements, 20mV is indicated instead of the measurement current

Activating/deactivating the **TEMP. / SP. VAL.** display
The [→] and [←] cursor keys are used to set the following parameters:
ON   The temperature or setpoint value is indicated.
OFF   The temperature or setpoint value is not indicated.

Note: If the temperature compensation as well as the display of delta % are active, the temperature is indicated instead of the setpoint value.

Parameters on page 2:

Activating/deactivating the **SAMPLE SIGN** display
The [→] and [←] cursor keys are used to set the following parameters:
ON   The sample signal is indicated.
OFF   The sample signal is not indicated.

Activating/deactivating the **SINGLE**-frame **/ CONT**inuous measurement display
The [→] and [←] cursor keys are used to set the following parameters:
ON   Single-frame / continuous measurement is indicated.
OFF   Single-frame / continuous measurement is not indicated.

Activating/deactivating the **MAN**ual **/ AUTO**matic range display
The [→] and [←] cursor keys are used to set the following parameters:
ON   Manual/automatic range selection is indicated.
OFF   Manual/automatic range selection is not indicated.

Activating/deactivating the **LOAD** (R or Z) display
The [→] and [←] cursor keys are used to set the following parameters:
ON   The measurement process (R or Z) is indicated.
OFF   The measurement process (R or Z) is not indicated.

4.4.4.10 Additional PLC input/output bits

```
┌─────────────────────────────────┐
│     AUX. INPUT/OUTPUT            │
├─────────────────────────────────┤
│                                 │
│  BIT NUMBER:    3 2 1 0         │
│  INPUT:         1 0 0 1         │
│  OUTPUT:          1 1 0         │
│                                 │
├────────┬────────┬────────┬──────┤
│  SET   │  RES   │ HOME   │ RETU │
└────────┴────────┴────────┴──────┘
```

Display of the input/output menu

BIT NUMBER: Bit enumeration (0 to 3)

INPUT: The status of the spare inputs is indicated bitwise.

OUTPUT: The [→] and [←] cursor keys are used to select individual bits of the output. The selected bit is marked by a dash "-".

Pressing the [F1] key (SET) sets the selected bit.

Pressing the [F2] key (RESet) resets the selected bit.

Note: The set output bits **cannot** be stored as part of the device setting.

[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn):   This effects a return to the parameter selection menu.

4.4.4.11 Scaling menu

```
┌─────────────────────────────────────┐
│   SCALED INPUTS                      │
├─────────────────────────────────────┤
│                                      │
│  Pt100  INPUT                        │
│  VOLTAGE INPUT                       │
│  CURRENT INPUT                       │
│                                      │
│                                      │
├───────┬───────┬─────────┬───────────┤
│ SEL   │       │ HOME    │ RETU      │
└───────┴───────┴─────────┴───────────┘
```
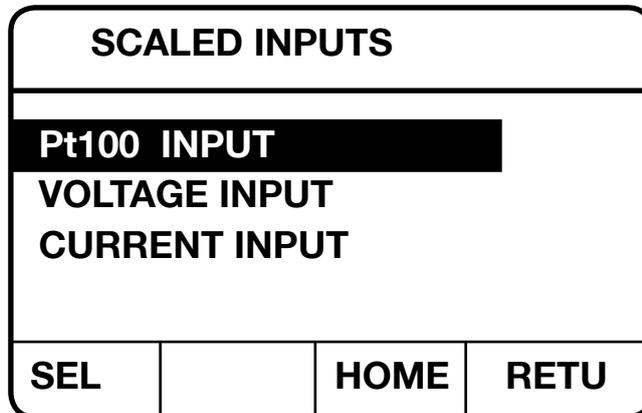
Display of the scaling menu

The various inputs for temperature measurement are scaled in this menu.
A Pt100 input for directly connecting a Pt100 sensor (e.g. type 2392-V001) is available in addition to a linear voltage/current input for connecting a temperature transmitter (e.g. pyrometer).

The following entries are possible:
[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn):   This effects a return to the parameter menu.

The [↑] and [↓] cursor keys are used to select the various inputs.
The selected parameter is displayed inversely.

The [POS1] key is used to select the 1st parameter in the window.
The [END] key is used to select the last parameter in the window.

Pressing the [F 1] key (SEL) invokes the menu for scaling the selected input.

Scaling Pt100 input

```
┌─────────────────────────────────────┐
│      Pt100 INPUT                     │
├─────────────────────────────────────┤
│                                      │
│  Rt  =    Ro* (1+A*t+B*t*t)          │
│  Ro =     100                        │
│  A  =     0.0039083                  │
│  B  =     -5.77e-07                  │
│                                      │
├───────┬───────┬─────────┬───────────┤
│ INPUT │       │ HOME    │ RETU      │
└───────┴───────┴─────────┴───────────┘
```
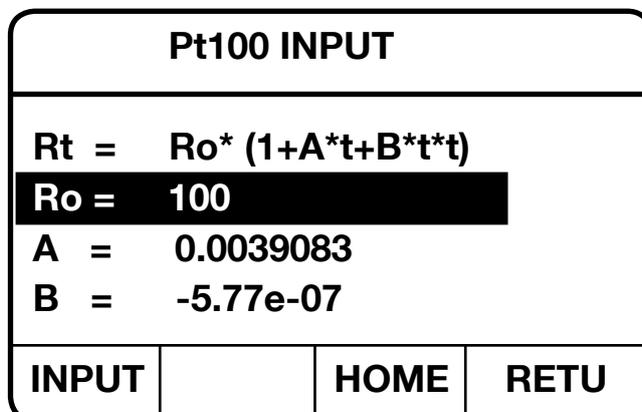
Display of the menu
for scaling the Pt100 input

This menu is used to enter the coefficients for the Pt100 curve in the range $\geq 100\ \Omega$ (i.e. only positive temperatures).

[F3] key (HOME): This effects a return to the main menu.
[F4] key (RETUrn): This effects a return to the scaling main menu.

The [↑] and [↓] cursor keys are used to select the various coefficients. The selected parameter is displayed inversely.

The [POS1] key is used to select the 1st parameter in the window.
The [END] key is used to select the last parameter in the window.

The required coefficient can now be entered:
Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] , the decimal key [**.**] and the sign key are used to enter the coefficient.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

Pressing the [ENT] key saves the new value if it is valid, and exits the input mode.

Note: The coefficients entered by the manufacturer comply with DIN EN 60751 for positive temperatures.
The C coefficient cannot be entered (only positive temperatures).
DIN EN 60751 values are always used for negative temperatures (< 100 Ω).

Scaling the current input

```
        CURRENT INPUT

  I1   =   2 mA
  t1   =   20 °C
  I2   =   20 mA
  t2   =   100 °C
 ┌──────────┬────────┬────────┐
 │ INPUT    │  HOME  │  RETU  │
```

**Display of the menu for scaling
the current input**

The (linear) current input is scaled in this menu.

Example: A temperature sensor indicates an output current of 2 mA at 20 °C and 20 mA at 100 °C.
The input current can have a value ranging from 0 ... 20 mA .

[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn):   This effects a return to the scaling menu.

The [↑] and [↓] cursor keys are used to select the various parameters. The selected parameter is displayed inversely.

The [POS1] key is used to select the 1st parameter in the window.
The [END] key is used to select the last parameter in the window.

The required parameters can now be entered.
Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] and the decimal key [.] are used to enter the parameters.
The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

Pressing the [ENT] key saves the new value if it is valid, and exits the input mode.
I1 and I2 or t1 and t2 must not be identical.

Scaling the voltage input

VOLTAGE INPUT

U1	=	1 V
t1	=	25 °C
U2	=	9 V
t2	=	450 °C

| INPUT | | HOME | RETU |

**Display of the menu
for scaling the voltage input**

The (linear) voltage input is scaled in this menu.

Example: A temperature sensor indicates an output voltage of 1 V at 25 °C and 9 V at 450 °C. The value of the input voltage can range from 0 ... 10 V.

[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn):   This effects a return to the scaling menu.

The [↑] and [↓] cursor keys are used to select the various parameters. The selected parameter is displayed inversely.

The [POS1] key is used to select the 1st parameter in the window.
The [END] key is used to select the last parameter in the window.

The required parameters can now be entered.
Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] and the decimal key [.] are used to enter the parameters.
The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

Pressing the [ENT] key saves the new value if it is valid, and exits the input mode.
U1 and U2 or t1 and t2 must not be identical.

4.4.4.12 Setting the contrast

```
          LCD CONTRAST

      CONTRAST :      5




  INPUT         HOME    RETU
```

Display of the menu for adjust the contrast

Pressing the [F1] key (INPUT) invokes the input mode.

Numeric keys [0] to [9] are used to adjust the contrast between 0 and 10.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

Pressing the [ENT] key saves the new value if it is valid, and exits the input mode.

The contrast can also be adjusted with the [→] and [←] cursor keys.

[F3] key (HOME): This effects a return to the main menu.

[F4] key (RETUrn): This effects a return to the parameter selection menu.

Note: Changes to the contrast setting correspondingly change the ideal viewing angle.

4.4.4.13 Calibration menu

```
    CALIBRATE MEAS. RANGES

    200  mOHM        2 kOHM
      2   OHM       20 kOHM
     20   OHM      200 kOHM
    200   OHM

    SEL           HOME    RETU
```

**Selection of a measurement range for calibration (figure 13-1)**

This menu is used to select a measurement range for calibration.

The [↑], [↓], [→] and [←] cursor keys are used to select the various menu parameters. The selected parameter is displayed inversely.

The [POS1] key   selects the 1st parameter in a column.
The [END] key   selects the last parameter in a column.

[F3] key (HOME):   This effects a return to the main menu.
[F4] key (RETUrn):   This effects a return to the parameter selection menu.

Pressing the [F1] key [SEL] acknowledges the inversely displayed measurement range for calibration. The following display appears on the LCD:

```
        CALIBRATION

   MEAS. RANGE:   200 mOHM
   Rext :    100.02  mOHM


  INPUT │ ABGL │ HOME │ RETU
```
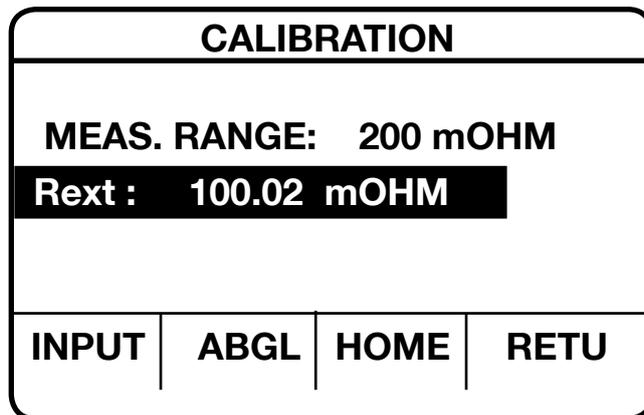
Acknowledgement of a measurement range for calibration
(figure 13-2)

[F3] key (HOME):   This effects a return to the main menu.

[F4] key (RETUrn):   This effects a return to the menu titled CALIBRATE MEAS. RANGES (figure 13-1).

Pressing the F1 key [INPUT] invokes the input mode, where the value of the externally connected calibration resistance can be entered.

In this case, the function keys are redefined as follows:

```
  mOHM │ OHM │ kOHM │
```

Display during the input of actual values
(figure 13-3)

Numeric keys [0] to [9] and the decimal [.] key are used to specify the value of the externally connected calibration resistance.

The [BSP] key is used to delete the character entered last.

The [C] key is used to delete all the entered characters and repeat the input procedure from the beginning, without exiting the input mode.

The [ESC] key is used to cancel the current entry, and exit the input mode.

The [F1] key [mOHM], [F2] key [OHM] or [F3] key [kOHM] is used to save the input value - provided that it is valid - and exit the input mode.

Pressing the F2 [BAL] key subsequently causes the selected resistance range to be calibrated.

The following display appears on the LCD:

```
┌─────────────────────────────────────┐
│            CALIBRATION               │
├─────────────────────────────────────┤
│  MEAS: RANGE:    200 mOHM            │
│  Rext :    100.02  mOHM             │
│  ███████████████████████████        │
│  CALIBRATION ACTIVE                 │
│                                     │
├───────┬───────┬───────┬─────────────┤
│ STOP  │       │       │             │
└───────┴───────┴───────┴─────────────┘
```
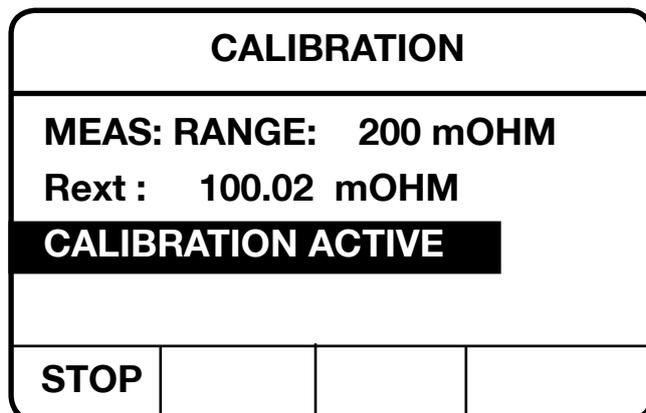
Display while calibration is in progress
(figure 13-4)

Once calibration has been performed successfully, the program returns to the menu titled CALIBRATE MEAS. RANGES (figure 13-1).

If an error occurs during calibration or this process is interrupted with the F1 key [STOP], a corresponding warning/error message is issued and the program returns to the menu displayed in figure 13-2.

Note: This menu can be used for digital calibration of the individual measurement ranges. The values of the reference resistances should lie in the middle of the respective measurement ranges. For this purpose, we recommend using the calibration resistances of the 1240 series with a DKD/DAkkS certificate (Deutscher Kalibrierdienst).
If the device is re-calibrated in any measurement range by a user, the corresponding calibration performed by the manufacturer is overwritten. For this reason, all changes made by the user should be carefully documented. The reading of the CAL counter (page 24) should be noted here.

Calibration instruments and their uncertainty factors:

Measuring range	100	mΩ	40 ppm
Measuring range	1	Ω	40 ppm
Measuring range	10	Ω	40 ppm
Measuring range	100	Ω	40 ppm
Measuring range	1	kΩ	40 ppm
Measuring range	10	kΩ	40 ppm
Measuring range	100	kΩ	40 ppm

Important: **The housings of measuring resistors having values $\geq$ 1 kΩ must remain connected to the ground terminal of the 2329 while measurements are in progress. If not, the measurement results might be corrupted by interference from 50-Hz fields.**

If the entire device needs to be calibrated, including the Pt100 input, 0-10 V / 0-20 mA input, 20 mV operating mode etc., the device should be sent back to the manufacturer because additional calibration equipment is required in this case.

5. Remote Control of the Device

5.1 General information

The RESISTOMAT® model 2329 is is equipped with a PLC and RS232-C interface as standard features. Optionally, the device can also be fitted with an IEEE488 interface. The selection of the required interface and its parametrization are described in chapter 4.4.4.6 titled "Interface menu".

5.1.1 Terminal assignment of the RS232 interface

The 9 pole Submin-D socket is assigned as following

With an RS232 interface:

```
RESISTOMAT®         Computer
model 2329          9 connector

Pin                 Pin
2    TXD ————————— 2  RXD
3    RXD ————————— 3  TXD
8    -    ———      .8  CTS
7    Connected     7  RTS
     in the device
4    -             4  DTR
6    -    ———      6  DSR
5    GND ————————— 5  GND
```

Note: In the case of Basic programs, DTR, DSR and CTS must be bridged on the PC side.
This is achieved automatically by the internal bridges of the device if a 9-pole 1:1 type 9900-K333 cable is used.

5.1.2 Control via the RS232 interface

To allow control of the device via the RS232 interface, all the RS232 parameters in the interface menu (chapter 4.4.4.6) must be set.

Protocol

The following ANSI standard transmission protocol is used by the serial interface of the RESISTOMAT® model 2329:

ANSI X3.28-1976   **Subcategory 2.1, A3**

Command without query form
1.   The device waits for a command having the form: <STX>Command1<LF><ETX>
        <STX>:   ASCII value 02
        Command1:   SCPI command without query form
        <LF>:   ASCII value 10
        <ETX>:   ASCII value 03

2.   On the reception of a valid command, the device responds with <ACK>.
          On the reception of an invalid command, the device responds with <NAK>.

<ACK>:	ASCII value 06
<NAK>:	ASCII value 21

Command with query form

1.   The device waits for a command having the form : <STX>Command2<LF><ETX>

<STX>:	ASCII value 02
Command2:	SCPI command with query form
<LF>:	ASCII value 10
<ETX>:	ASCII value 03

2.   On the reception of a valid command, the device responds with <ACK>.
          On the reception of an invalid command, the device responds with <NAK>.

<ACK>:	ASCII value 06
<NAK>:	ASCII value 21

3.   To fetch the requested data, an <EOT> must be sent to the device.

<EOT>:	ASCII value 04

4.   The device then supplies the data in the following form:
          <STX>Data<CR><LF><ETX>

<CR>:	ASCII value 13

5.   The reception of the data must be acknowledged with <ACK>.

6.   Items 4 and 5 are repeated until no data are present any more. The device then responds with <EOT>. After that, the device assumes its initial state and is ready ready to receive a new command.

<u>**Timer functions**</u>

Timer A (response timer)

Timer A is used by the transmitting station as a safeguard against no response or an invalid one.

Start: Timer A is started once data transmission has been completed with ETX as described previously under item 4.

Stop: Timer A is stopped once a valid response has been received <ACK>.

Timeout: When a timeout occurs, the RESISTOMAT® 2329 sends an <EOT> and assumes its initial state (ready for a new command).

The timeout value of timer A is set firmly to 15 seconds.

Timer B (receive timer)

Timer B is used by the receiving station as protection against failure to identify an <ETX> signal.

Start: Timer B is started on the reception of the <STX> signal as described previously under item 1.

Restart: Timer B is restarted during data transfer to allow the reception of data blocks of variable lengths.

Stop: Timer B is stopped on the reception of the <ETX> signal.

Timeout: When a timeout occurs, the received data (command) are discarded. The device then assumes its initial state and is ready to receive a new command.

**The timeout value of timer B is set firmly to 15 seconds.**

5.1.3 Terminal assignment of the optional IEEE488 interface

The 24-pole IEEE488 bus connection plug is standardized and has the indicated pin asignment.

To comply with applicable interference protection guidelines (e.g. VDE 0871B), all interface cables and plugs must be shielded and grounded at both ends.
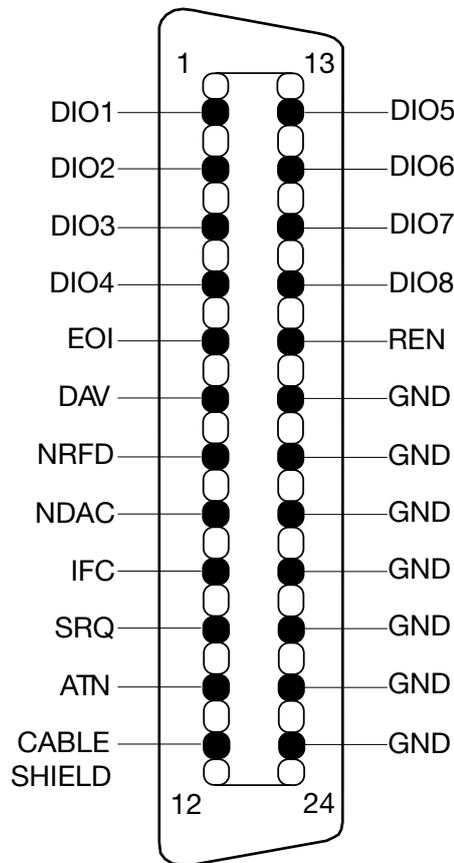
These are "Open Collector" outputs.
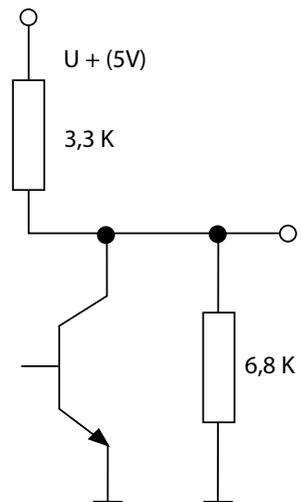
5.1.4 Control via the optional IEEE488 interface of the RESISTOMAT® 2329

For the device to be controlled via the IEEE488 interface, the IEEE488 option must be selected in the interface menu (chapter 4.4.4.6). However, this is only possible if the IEEE488 card has been installed.

Setting the device address
The device address of the 2329 for control via the IEEE488 is set in the corresponding interface menu. A number in the range 0...30 can be selected for the address. The default setting 9 is used in all the examples here. Every device connected to the IEEE488 must have its own address. If the address of a device is changed on the front panel, the new address becomes effective immediately.

Input/output commands

For control of the 2329 by an IEEE488 controller, the corresponding input/output commands must be known. The command syntax is provided in the operating manual of the IEEE488 controller. The following input/output commands are used in the Basic language of the HP series 200/300:

OUTPUT and **ENTER**.

If a National-PC card has been installed, the commands are:

IBWRT and **IBRD**.

The examples in this manual are written in Q Basic.

Sending a command

Commands sent to the 2329 must comply with the SCPI format. For example, the following command is sent to adjust the display contrast:

1. in HP Basic: OUTPUT 709;":DISPLAY:CONTRAST 0.5"

                Output   SCPI command
                command

                    HP-IB select
                    code+device address

2. with National:IBWRT":DISPLAY:CONTRAST 0.5 \n"

             Output   SCPI command   Line Feed as
             command   end of command
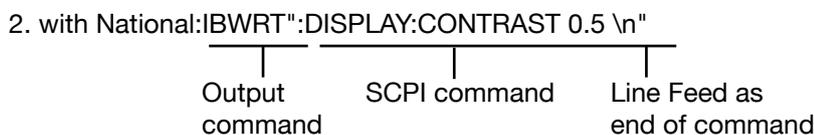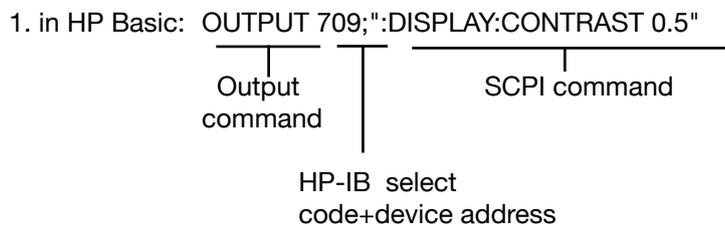
Reception of data from the 2329

The 2329 sends data requested via an SCPI query command. For example, on receiving the following query:

OUTPUT709;":DISP:CONT?"

the 2329 writes the current setting of the display contrast to its output buffer. This response can be fetched with the input command of the IEEE488 controller.

Remote/local

On receiving a command addressed to it, the 2329 switches into the remote state. In this state, function key F4 is designated LOCAL, and except for this key, all other keys are disabled.

A switchover to the local mode can be performed by pressing the local key or sending a Go-to-local command via the IEEE488.1.

If a LocalLockout command was sent via the IEEE488.1, the 2329 can only be switched to the local mode using the Go-to-local command, because the local key is also disabled in this case. This corresponds to the command SYSTem:CLOCK ON (e.g. with an RS232 interface).

5.1.5 Terminal assignment of the PLC interface

**Digital I/O**
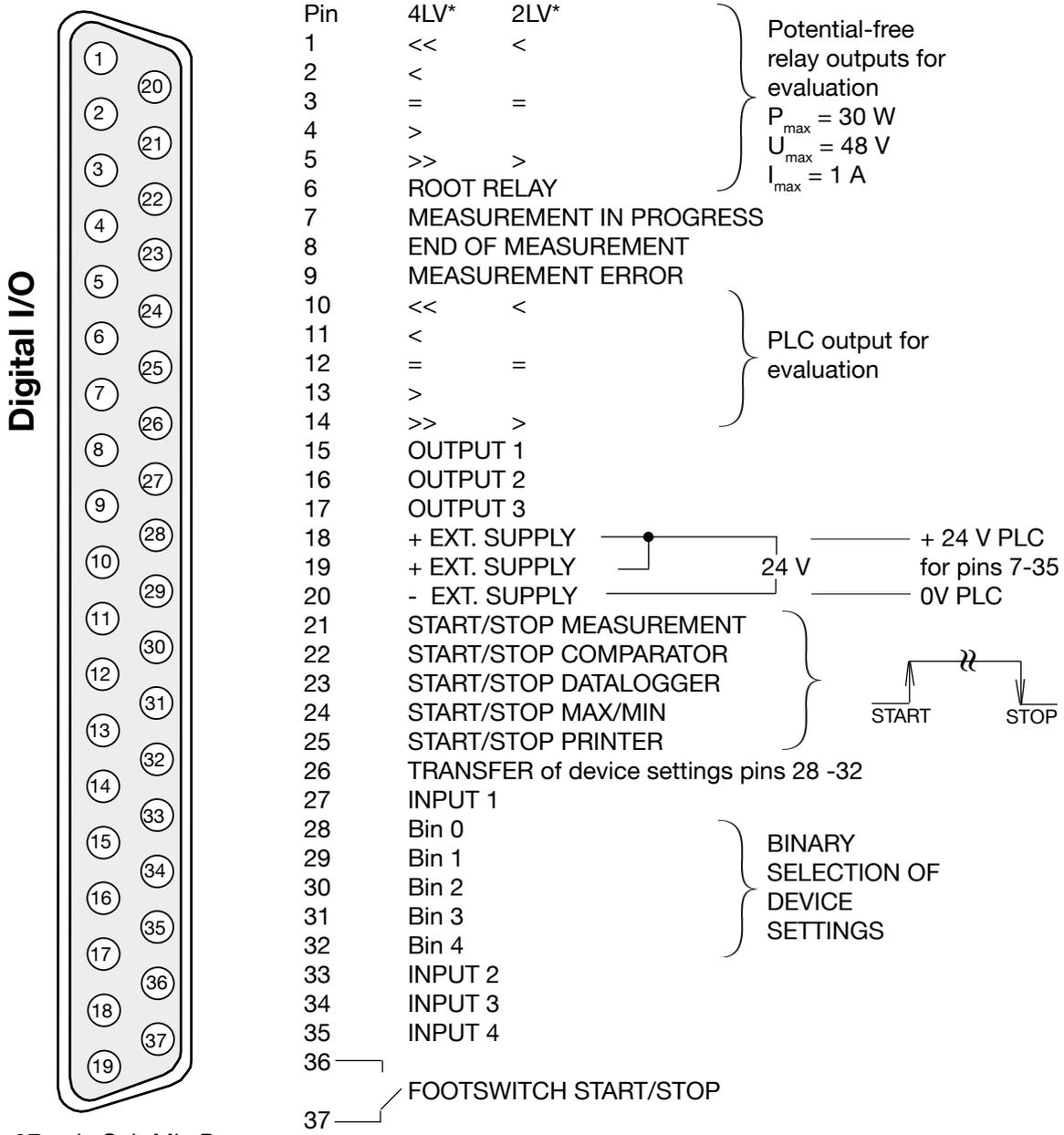
37 pole Sub Min D
View of socket

Plug housing: Potential PE
Mating connector: Type 9900-V165

Pin	4LV*	2LV*	
1	<<	<	Potential-free relay outputs for evaluation $P_{max} = 30$ W $U_{max} = 48$ V $I_{max} = 1$ A
2	<		
3	=	=	
4	>		
5	>>	>	
6	ROOT RELAY		
7	MEASUREMENT IN PROGRESS		
8	END OF MEASUREMENT		
9	MEASUREMENT ERROR		
10	<<	<	PLC output for evaluation
11	<		
12	=	=	
13	>		
14	>>	>	
15	OUTPUT 1		
16	OUTPUT 2		
17	OUTPUT 3		
18	+ EXT. SUPPLY		+ 24 V PLC
19	+ EXT. SUPPLY	24 V	for pins 7-35
20	- EXT. SUPPLY		0V PLC
21	START/STOP MEASUREMENT		
22	START/STOP COMPARATOR		
23	START/STOP DATALOGGER		
24	START/STOP MAX/MIN		
25	START/STOP PRINTER		
26	TRANSFER of device settings pins 28 -32		
27	INPUT 1		
28	Bin 0		BINARY SELECTION OF DEVICE SETTINGS
29	Bin 1		
30	Bin 2		
31	Bin 3		
32	Bin 4		
33	INPUT 2		
34	INPUT 3		
35	INPUT 4		
36			FOOTSWITCH START/STOP
37			

START   STOP

*LV = Limit value

PLC output (schematic)

Pin 18   +24 V from PLC
(20 V ... 24 V ... 30 V)

$I_{max} \leq 150$ mA

Pin xx

I_{max} of all outputs together ≤ 600 mA

ext. pull down resistor

Pin 20
0 V from PLC

internal schematic diagram

PLC input (schematic)

1,8 kΩ

Pin xx
U= 20 V ... 24 V ... 30 V

Pin 20
0 V from PLC

internal schematic diagram

5.1.6 Control via the PLC interface

The PLC interface of the RESISTOMAT® 2329 was developed in accordance with the DIN EN 61131-2 standard. The circuitry is designed for a feed voltage of 24 V DC -15 % / +20 %. The PLC outputs of the 2329 were developed for current-consuming PLC inputs. The 2329 has current-consuming PLC inputs.

The logic system is positive. The low level is -3 V to +5 V, the high level is +15 V to +30 V.

If high-impedance inputs are connected to the PLC outputs of the 2329, a resistor might need to be connected to ground to prevent the output leakage current (Low < 0,2 mA) from giving rise to undesirable high levels. Be careful that the leakage current at the ext. pull down resistor gives a voltage less than 5 V because only a voltage up to 5 V is for the PLC "Low".

A prerequisite for use of the PLC interface is the connection of an external DC power supply to the 37 pole D-Sub socket ("+" to 18 or 19 and "-" to 20). The PLC interface is isolated from all internal circuit components by means of optocouplers. The voltage between protective earth (PE) and "-" must not exceed 30 V.

Available inputs:
l   Start / stop measurement
l   Start / stop (reset) comparator
l   Start / stop datalogger
l   Start / stop max. / min.
l   Start / stop printer
l   Transfer of device settings
l   5 inputs for binary selection of the device settings (e.g. input $0 = 2^0$)
l   4 inputs which can be read out via the interface (only with the measurement stopped).

Available outputs:
l   End of measurement
l   Previous measurement faulty
l   Measurement in progress
l   Output for evaluation (comparator)   >> or > with 2 limiting values
l   Output for evaluation (comparator)   >
l   Output for evaluation (comparator)   =
l   Output for evaluation (comparator)   <
l   Output for evaluation (comparator)   << or < with 2 limiting values
l   3 outputs which can be controlled via the interface (only with the measurement stopped).

The device is also equipped with 2 terminals for starting and stopping measurements, as well as 5 relay contacts (NO) with a common root on this socket.

Measurements can be triggered by closing a simple mechanical contact (e.g. footswitch). This contact should have a low bounce factor. Renewed closure (after opening) stops the measurement or, in the case of a single measurement, starts one again after the measurement time has elapsed.

The relays allow easy evaluation with the comparator function if only a few measurements need to be performed. Caution: In the continuous mode, proper operation of the relays cannot be guaranteed beyond the specified number of cycles. If many measurements need to be performed, the PLC evaluation output **must** be used.

If PLC-control is involved, manual range selection and single measurements are usually necessary, as only this can ensure reliable operation. This is because if an error occurs in the automatic range selection mode, other measuring ranges need to be checked before the cause of the error can be determined. In such cases, the time-pulse of the system can often be exceeded (measuring time **=** (number of measuring ranges to be checked) * single measurement time).

In the continuous measurement mode, the results obtained with an active comparator or datalogger cannot be assigned to an individual test object, thus leading to diffuse statistics.

Important: Before commencing a measurement, ensure that proper bonding has taken place.
        The measurement starts just a few microseconds after reception of the command.

Function of the PLC interface:

When the device is turned on, all output levels are low.

All functions are activated by a rising edge (low - high) and deactivated by a falling edge (high - low). Deactivating a function already in progress causes it to be terminated immediately.

The outputs are static; they retain their state until another state is introduced.

The outputs are set as quickly as possible following the occurrence and identification of an event.

For an evaluation of the outputs, the end-of-measurement line needs to be monitored. A rising edge at this output indicates that the remaining outputs are now valid.

After power-on, the end-of-measurement output is low just like all the other outputs.

After a measurement result or error has been identified internally, the outputs are set and the end-of-measurement line is set to a high level roughly 1 ms later. This indicates to the connected PLC that the other outputs have valid states which can be transferred and read.

Roughly 0.1 ms - 0.3 ms after the resumption of a single measurement, the end-of-measurement line is reset to a low level. In the case of continuous measurements, this takes places after a few milliseconds (the precise time depends on the configuration and the test object).

A rising edge at the end-of-measurement line indicates that the outputs are now valid.

This applies to evaluations and measurement errors.

"Measurement in progress" is set to high roughly 0.1 ms - 0.3 ms following commencement of the measurement. In the case of single measurements, the line is set to low roughly 0.2 ms after the rising edge of the end-of-measurement signal. In the case of continuous measurements, this takes place roughly 0.2 ms after the end of measurement.

Following transmission through an interface, the outputs which are controlled via this interface require about 0.1 s to change levels (this is only possible in the stopped state).

Inputs can be read out roughly 0.1 seconds after the occurrence of an event, if interfaces are being used exclusively to read these inputs (this is only possible in the stopped state).

Example of control via a PLC:

Configuration of the device via a keypad or an interface (e.g. single measurement, manual ange selection, entry of limiting values, selection of temperature compensation, disabling of keyboard operation etc.), **or** loading of a device configuration by applying the binary address to the 5 inputs (28 - 32). After a waiting period of roughly 5 ms, the selected setting is transferred by a rising edge (low - high) at the transfer input (26). After that, the line is reset to low and a waiting period of roughly 10 ms elapses until the settings have been transferred.

The comparator, datalogger or any other required function is set by applying a high level to the corresponding input **in case of a deviation from the invoked setting** (low - high edge for activation, high - low edge for deactivation).

Scanning if MEASUREMENT IN PROGRESS (7) is low. If yes, then start, else stop and check beforehand.

Triggering of the measurement by a low - high edge at the Start/Stop measurement input (21). Important: A high - low edge stops (aborts) the measurement.

Scanning the end-of-measurement line (8) for a positive edge (low - high). This must take place within a certain time period (depending on the configuration, measuring range and test object), otherwise the setup needs to be examined.

Important: Following the start command, this line needs to be scanned for the edge. Reasons:

From the second start following activation of the device, the end-of-measurement level remains high for roughly 0.1 ms - 0.3 ms. After that, the line is set to low until an error is detected or a measurement result is available. This low period can vary, depending on the type of the error and the configuration (automatic range selection, average-value formation, R / Z, conversion, measurement procedure, temperature recording etc.). It can range from a few milliseconds to several seconds, but is rarely longer than the standard measuring time, except if automatic range selection is active.

Following identification of a positive edge, the start line is reset to low and the evaluation/error lines are read in. If a measurement error has occurred, it was not possible to measure the test object (incorrect bonding, measuring range, temperature recording etc.). Otherwise evaluation is performed and the measurement procedure is resumed for the next test object.

Timing of the PLC interface

Settings: Manual 200 mΩ, display 20000,
comparator 2 limiting values,
on error >, R, average = 1,
standard conversion,
standard measurement procedure,
single measurement

Stop   Start

roughly 250 - 300 µs

Start/Stop meas.

End of meas. (no error)

130 - 140 ms

Set new evaluation roughly 1ms

Evaluation, e.g. >, = <
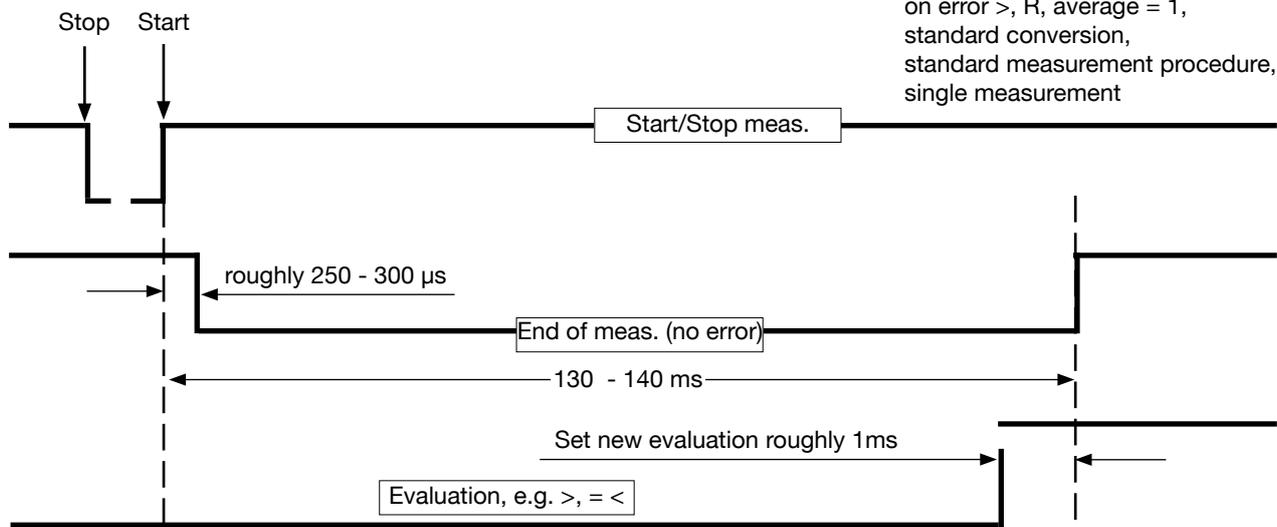
Deviations in timing in the event of an error
Different errors are detected at different times and output as quickly as possible. Excessively large measurement values can only be identified at the end (given a slight transgression of the measuring range), or when the measuring current is turned on (given an excessively low driving current for the connected resistor) or during a cable-breakage test.

Low overdrive: (e.g. 208 mΩ in the 200 mΩ range)

roughly 250 - 300 µs

End of meas. (R=208 mΩ)

130 - 140 ms

roughly 350 µs

Meas. error (if prev. good)

Meas. error (if prev. bad)- always high
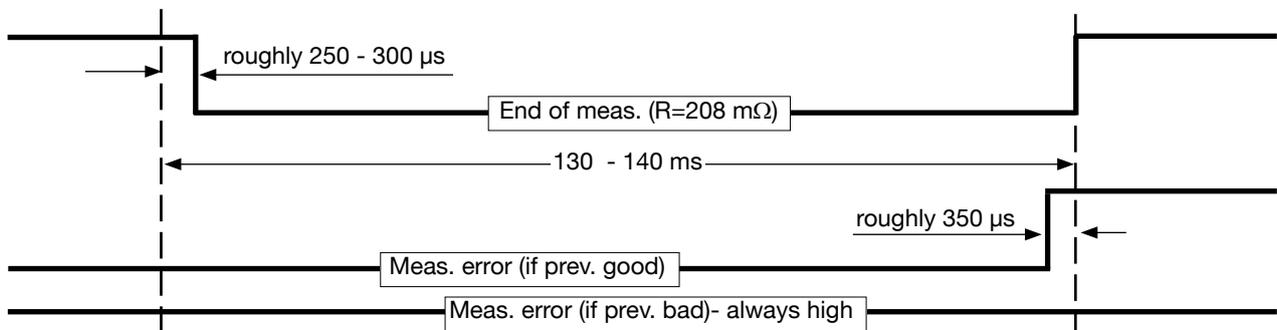
Medium overdrive: (e.g. 300 mΩ in the 200 mΩ range)

roughly 250 - 300 µs

End of meas. (R=300 mΩ)

roughly 70 - 75 ms

roughly 350 µs

Meas. error (if prev. good)

Meas. error (if prev. bad)- always high
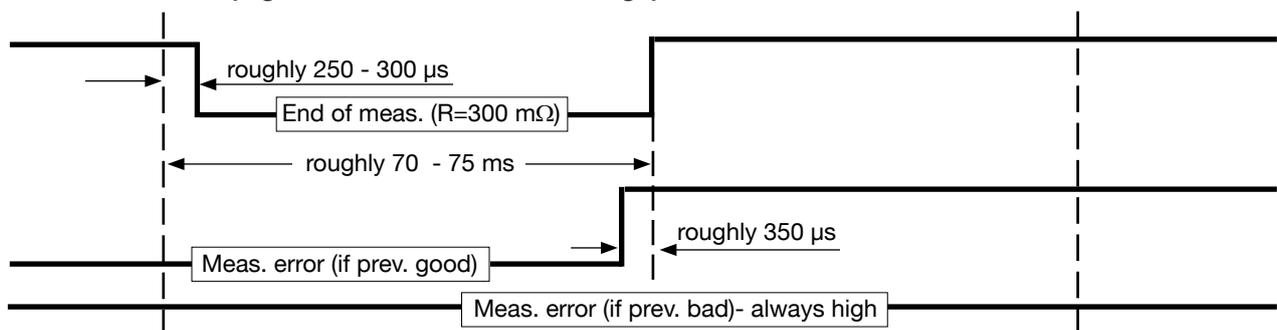
Important:
A falling edge at 'Start/Stop measurement' stops the single or continuous measurement in progress.

RESISTOMAT®

burster

Timing of the PLC interface

Settings: Manual 200 mΩ, display 20000, comparator 2 limiting values, on error >, R, average value = 1, standard conversion, standard measurement procedure, single measurement

Stop   Start
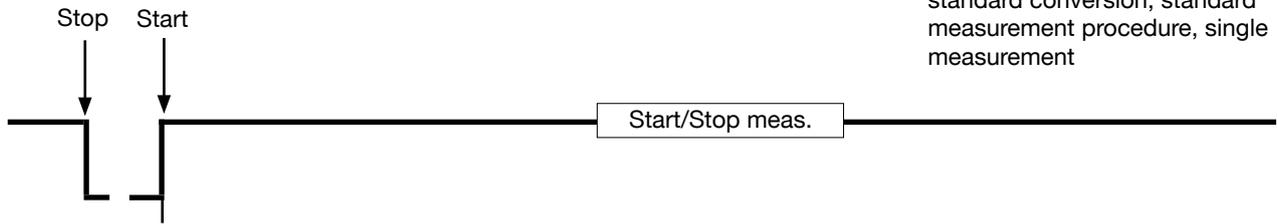
Start/Stop meas.

High overage: (e.g. 1 MΩ in the 200 mΩ range or test object interrupted)

roughly 300 µs

End of meas. (R ∞)

2.5 -10 ms

Meas. error (if prev. good)

roughly 350 µs

Meas. error (if prev. bad - always high
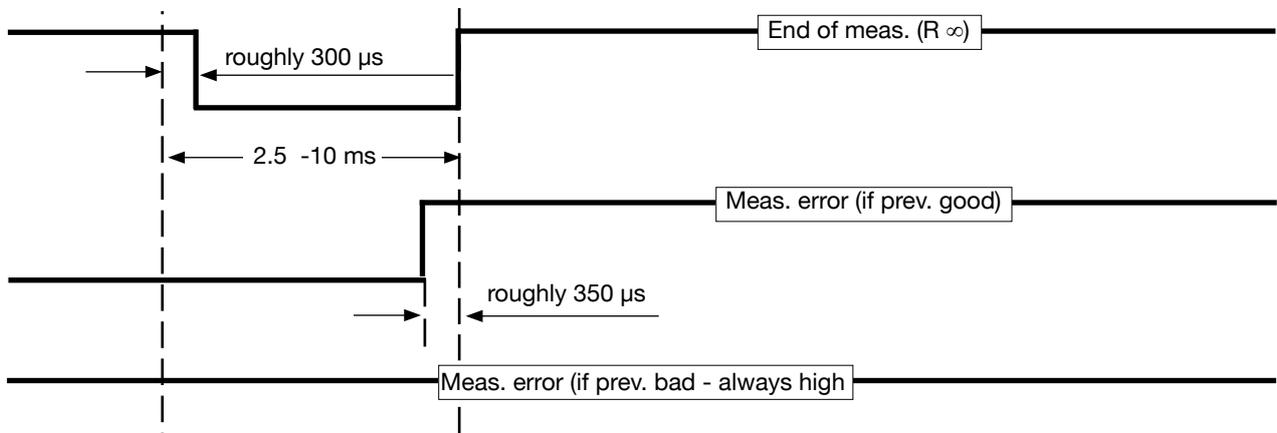
Test object is measurable after measurement error:

roughly 300 µs

End of meas.

130 - 140 ms

Meas. error (prev. error)

roughly 1.1 ms

Evaluation > (if = or < afterwards)

roughly 1 ms
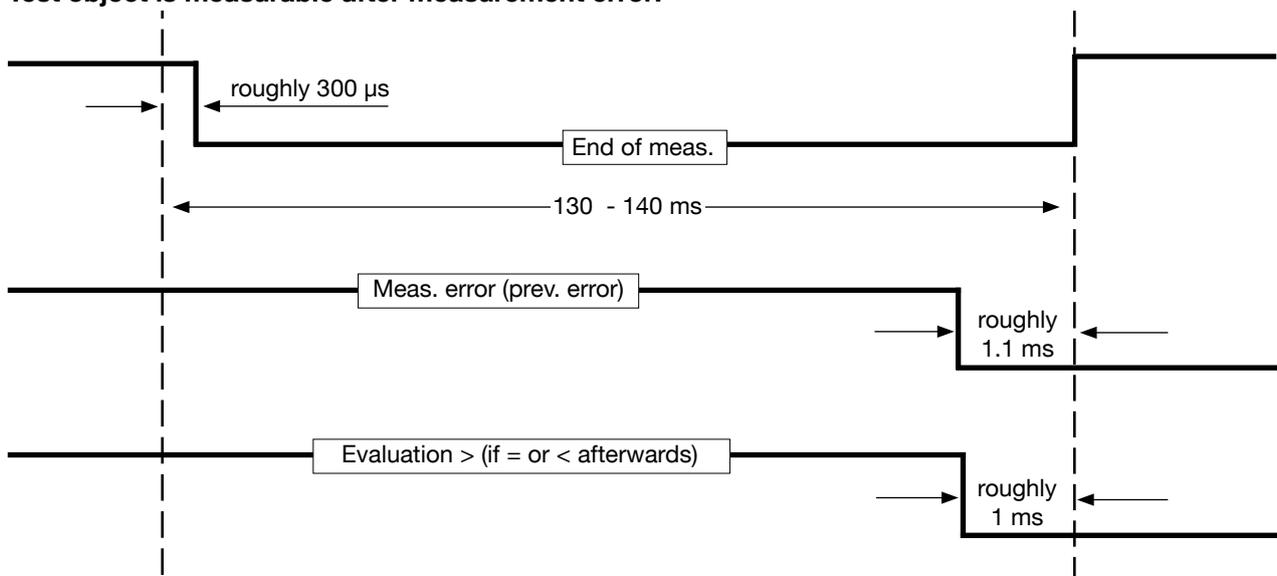
Roughly 300 µs following the application of a positive edge to "Start/stop measurement", the measurement is commenced internally. By then, proper bonding must have been ensured.

Immediately after starting, the end-of-measurement output should be scanned for a positive edge (or at least for a positive level 1 ms later).

Following identification, the measurement error and evaluation must be read in. Different values (usually smaller ones) apply to other measuring ranges (≥ 20 Ω) and other settings.

5.2 RESISTOMAT® command language

5.2.1 Introduction

The command language of the 2329 is called **SCPI** (**S**tandard **C**ommands for **P**rogrammable **I**nstruments). SCPI is a universal language with standardized commands agreed by the leading manufacturers of electrical equipment. SCPI not only provides a standardized set of commands but also allows manufacturers to define their own commands in accordance with specific rules.

In addition to these commands, all SCPI devices should implement the following **IEEE488.2 common commands**:

*CLS   Clear Status Command
*ESE   Standard Event Status Enable Command
*ESE? Standard Event Status Enable Query
*ESR? Standard Event Status Register Query
*IDN? Identification Query
*OPC   Operation Complete Command
*OPC? Operation Complete Query
*RST   Reset Command
*SRE   Service Request Enable Command
*SRE? Service Request Enable Query
*STB? Read Status Byte Query
*TST? Self-Test Query
*WAI   Wait to Continue Command

5.2.2 Befehlskopf

e.g. DISPlay

Every SCPI command header has a long and a short form, and every SCPI device should just accept precisely this long and short form. The IEEE488.2 limits the length of a command header to 12 characters.

The long form either comprises one single word or abbreviations of several words. The short form is an abbreviation of the long form.

If a command consists of a single word, this word is the long form of the command (e.g. DISPLAY). If a command consists of several words, it is formed from the first letters of each word and the entire last word. For example, the words 'line frequency' are shortened to the command 'LFREQUENCY'.

The short form of the command header normally comprises the first four letters of the long form (e.g. DISP). An exception is when the long form consists of more than four letters, the fourth one being a vowel. In this case, the vowel is left out. The short form then only contains the first three letters of the long form. For example, the short form of the calibration command is CAL.

The command list shows commands in their long form, with the short form in upper case and the remainder of the command in lower case.

Commands can be transmitted in lower and upper case.

5.2.3 Command tree

The SCPI command tree has a hierarchical structure. This allows the same command header to be used for several different functions on different levels of the hierarchy.

e.g.

MEMory	**:STATE**	**:NAME**	
HCOPY	**:ITEM**	**:TIME**	:STATE
Level 1	Level 2	Level 3	Level 4

The different command levels are separated by a ":". Some commands have optional headers. For example, the command INITiate:IMMediate has an optional header "IMMediate" on level 2. Optional headers need not be transmitted with their related commands.

The command list shows optional command sections enclosed in square brackets, e.g. INITiate[:IMMediate]. The brackets are not part of the command, and must not be transmitted with it.

5.2.4 Query form

All commands have a related query form, if not specified otherwise. As defined in IEEE488.2, the query form of a command is created by appending a question mark to the command header (e.g. DISPlay:CONTrast?). A query form can, but need not, be sent with a parameter. When the 2329 receives the query form of a command, the current setting related to the command is written to the output buffer. The response to a query command does not contain the command header. If the response to a query command consists of one word, the short form is always used.

5.2.5 Navigating the command tree

A command message to the 2329 can comprise several commands. The first command always refers to the root directory. A subsequent command always refers to the same tree level as the previous command. The individual commands in a command message are separated by a semicolon. Commands sent with a leading colon always refer to the root directory. Command messages are concluded with a "Line Feed" (<nl>).

Example: If a device has the following command tree:

INITiate   :CONTinuous
                    [:IMMediate]

ABORT
then the following command messages have the described effect:

INIT:CONT ON;IMM<nl>
switches the device to continuous measurement and starts the measurement.

INIT:CONT ON;:INIT:IMM<nl>
switches the device to continuous measurement and starts the measurement.

INIT:IMM;ABOR<nl>
starts the measurement and generates an error, because ABOR is not a command on the current interpreter level.

INIT:CONT ON;:INIT;:ABOR<nl>
switches the device to continuous measurement, starts the measurement and stops it again.

5.2.6 Parameter

The valid parameters for each command, together with the related syntax, are described in the following chapter. The parameters are separated from the command by a blank character.

Format of a resistance parameter:
A parameter which sets a resistance value or resistance measuring range can be entered in several different formats and units.
Resistance values can be entered in integer, floating-point or exponential form. Valid units for a resistance parameter are:

UOHM -> Microohm
MOHM -> Milliohm
OHM -> Ohm
KOHM -> Kiloohm
MAOHM-> Megaohm

If the unit is omitted, the parameter is assumed to have ohm as the unit.
Examples of valid parameters for a resistance of 123.45 ohm are:

123.45, 123.45OHM, 0,12345KOHM, 123450MOHM, 123.45E-6MAOHM.

Format of the ON/OFF parameters
The ON/OFF parameters can be replaced by numeric parameters. The 2329 always responds with numeric values to a query form.
OFF -> 0
ON -> 1
If only an instantaneous setting is requested, this parameter can be omitted from the query form of a command.

5.2.7 End-of-command character

A line feed (nl), semicolon (;) or EOI (IEEE488.1 end or identify), together with the character sent last (EOI only in the case of IEC bus control) indicate the end of a command.
For example, if the HP200/300 Basic "OUTPUT709;":INIT" is sent, the controller automatically appends a <cr><nl> to the command. With other IEC bus controllers such as a National PC card, the <nl> character might need to be entered explicitly (e.g.: ibwrt":init\n").

5.2.8 Special features of the RESISTOMAT®

Settings cannot be modified or read while a measurement is in progress. This means that the 2329 ignores all commands until the measurement is stopped. Exceptions here are the "ABORt" command for stopping a measurement, the commands for status-register control ("STATus") and the IEEE488.2 commands.

## 5.2.9 Effects of the "FETCh?" command while a continuous measurement is in progress

On the transmission of this command, the next available measurement value is written to the output buffer, from where it can be fetched (see „Command with query form" auf Seite 66). After the value has been fetched, a new one is only written again to the output buffer the next time a "FETCH?" command is issued.

5.2.10 Status messages

Every SCPI device requires the status mechanism described in Chapter 11 of IEEE488.2, including the full implementation of the Event Status Register structure.

The following diagram shows the basic SCPI data structure with the related registers.

Error/Event Queue

QUEStionable Status

VOLTage	0
CURRent	1
TIME	2
POWer	3
* TEMPerature	4
FREQuenc	5
PHASe	6
MODulation	7
* CALIbration	8
* RESistor	9
Available to designer	10
Available to designer	11
Available to designer	12
INSTrument Summary	13
* Command Warning	14
NOT USED	15

OPERationStatus

* CALIbrating	0
SETTling	1
* RANGing	2
SWEeping	3
* MEASuring	4
Waiting for TRIGger Summary	5
Waiting for ARM Summary	6
CORRecting	7
* Resistance value available (EOC)	8
PON	9
Available to designer	10
Available to designer	11
Available to designer	12
INSTrument Summary	13
PROGram Running	14
NOT USED*	15

Standard Event Status Register

* Operation Complete	0
Request Control	1
* Query Error	2
* Device Dependent.Error	3
* Execution Error	4
* Command Error	5
User Request	6
Power on	7

Status Byte

Available to designer	0
Available to designer	1
Error/Event Queue or Available to designer	2
	3
MAV	4
	5
RQS	6
	7

Summary of IEEE488.2 Status Structure Registers

The events/functions marked with * are implemented inside the device.

5.2.11 Operation Status Register

The Operation Status Register indicates states which are part of the standard functions of the 2329.
When a bit in the Operation Status Enable Register is enabled, the Operation Status Summary Bit (bit 7) in the Status Register is set. When bit 7 in the Service Request Enable Register is enabled, a Service Request is sent to the System Controller if the 2329 is being controlled via the IEC bus. The bits used by the 2329 are:

0 - Calibrating - The 2329 is performing a calibration.

2 - Ranging - The 2329 is changing measurement ranges.

4 - Measuring - The 2329 is performing a measurement.

8 - EOC - End of Conversion: This bit indicates that the 2329 has obtained a valid measurement value.

9 - PON - The 2329 has been switched on again. This bit will be deleted while reading out the register or ✳CLS.

The commands for controlling the Operation Status structure are:
STATus:OPERation:EVENt?
STATus:OPERation:ENABle
STATus:OPERation:CONDition?

5.2.12 Questionable Status Register

The Questionable Status Register indicates that the data presently being recorded are invalid for some reason.

When a bit in the Questionable Status Register is set and the corresponding bit in the Questionable Status Enable Register enabled, the Questionable Status Summary bit (bit 3) in the Status Register is set. When bit 3 in the Service Request Enable Register is enabled, a Service Request is sent to the System Controller if the 2329 is being controlled via the IEEE488.

Bit 14 is the Command Warning bit which indicates that a parameter has been ignored during the processing of a command.

The commands for controlling the Questionable Status structure are:
STATus:QUEStionable:EVENt?
STATus:QUEStionable:ENABle
STATus:QUEStionable:CONDition?

5.2.13 Standard Event Register

The Standard Event Register indicates various states of the 2329. When a bit in the Standard Event Register is set and the corresponding bit in the Standard Event Enable Register is enabled, bit 5 in the Status Register is set. When bit 5 in the Service Request Enable Register is enabled, a Service Request is sent to the System Controller if the 2329 is being controlled via the IEEE488.

The bits used in the 2329 have the following meanings:

Bit 0 Operation Complete   This bit is set in response to the *OPC command. It indicates that the device has finished executing the selected operation.

Bit 2 Query Error   A query error was detected. This bit indicates that either:
(1)   data were requested although none are available,
(2)   or data in the output buffer were lost.

Bit 3 Device Dep. Error   The Device Dependent Error bit indicates that an error occurred during a measurement.

Bit 4 Execution Error   The Execution Error bit is set on the transmission of an incorrect parameter.

Bit 5 Command Error   The Command Error Bit is set when the SCPI interpreter fails to recognize a command.

The IEEE488.2 commands for controlling the Standard Event data structure are:
*ESR?
*ESE
*ESE?

5.2.14 Status Byte

The Status byte is used to summarize several Event Registers in a Status Register. The Status byte of every Event Register contains an Event Register Summary bit which indicates whether an event has occurred in the related Event Register. The Summary bit is only set if the corresponding bit in the Event Enable Register is set. When the Summary bit is set and bit in the Service Request Enable Register is enabled, a Service Request is sent to the System Controller if the 2329 is being controlled via the IEEE488.

The bits in the Status byte are:

Bits 0-2 Not used

Bit 3   Questionable Status Summary bit. This bit is set if an enabled bit has been set in the Questionable Event Enable Register of the Questionable Event Register.

Bit 4   MAV - Message Available.The MAV bit is set if data are available in the output buffer of the 2329.

Bit 5   ESB - Event Status Summary Bit. This bit indicates whether an enabled event has occurred in the Event Status Register of the 2329.

Bit 7   Operation Status Summary Bit. This bit is set if an enabled event has occurred in the   Operation Status Register.

The IEEE488.2 commands for setting the Status data structure are:
*STB?
*SRE
*SRE?

5.3 SCPI-Befehle

The SCPI commands are displayed in long and short form. The long form contains the entire command, while the short form consists of the sections indicated in upper case. Command sections enclosed in square brackets need not be transmitted.

Related parameters are appended with a blank character.
The commands can be entered in upper or lower case, long or short form.

The query form of a command is created by appending a question mark directly to the command.
If a command is sent with a parameter, although no parameter is expected, the Command Warning bit (bit 14) in the Questionable Status Register is set. The parameter is ignored and no error is indicated.

On the occurrence of an error, the 2329 issues <NAK> instead of <ACK>. The cause of the error can be determined with the command ":SYSTem:ERRor?" (also described subsequently). In addition , the corresponding error bits are set in the Status Registers (refer to chapter 5.2.14, Status Register).

The SCPI version can be requested with the command SYSTem:VERSion?.

5.3.1 STATus Subsystem

STATus:OPERation:CONDition? (short form -> S:O:C?)

DESCRIPTION:	The Operation Status Condition Register is read out
SYNTAX:	**STATus:OPERation:CONDition? or S:O:C?**
PARAMETERS:	None
QUERY FORM:	Only query form. The contents of the 16 bit register are returned as a decimal value
RESTRICTIONS:	None

STATus:OPERation:ENABle

DESCRIPTION:	The Operation Status Enable Register is set.
SYNTAX:	**STATus:OPERation:ENABle <parameter>**
PARAMETERS:	Decimal value (value range: 0 to 32767)
QUERY FORM:	**STATus:OPERation:ENABle?** The contents of the 16 bit register are returned as a decimal value.
RESTRICTIONS:	None

STATus:OPERation[:EVENt]? (short form -> S:O:E?)

DESCRIPTION:	The Operation Status Event Register is read out.
SYNTAX:	**STATus:OPERation[:EVENt]? or S:O:E?**
PARAMETERS:	None
QUERY FORM:	Only query form. The contents of the 16 bit register are returned as a decimal value.
RESTRICTION:	None

STATus:QUEStionable:CONDition? (short form -> S:Q:C?)

DESCRIPTION:	The Questionable Status Condition Register is read out.
SYNTAX:	**STATus:QUEStionable:CONDition? oder S:Q:C?**
PARAMETERS:	None
QUERY FORM:	Only query form. The contents of the 16 bit register are returned as a decimal value.
RESTRICTION:	None

STATus:QUEStionable:ENABle

DESCRIPTION:	The Questionable Enable Register is set.
SYNTAX:	**STATus:QUEStionable:ENABle <parameter>**
PARAMETERS:	Decimal value (value range: 0 to 32767).
QUERY FORM:	STATus:QUEStionable:ENABle? The contents of the 16 bit register are returned as a decimal value.
RESTRICTION:	None

STATus:QUEStionable:[:EVENt]? (short form -> S:Q:E?)

DESCRIPTION:	The Questionable Status Event Register is read out.
SYNTAX:	**STATus:QUEStionable[:EVENt]? or S:Q:E?**
PARAMETERS:	None
QUERY FORM:	Only query form. The contents of the 16 bit register are returned as a decimal value.
RESTRICTION:	None

STATus:QUEStionable:FRESistance? (short form -> S:Q:F?)

DESCRIPTION:	The status of the resistance measurement is returned.
SYNTAX:	**STATus:QUEStionable:FRESistance? or S:Q:F?**
PARAMETERS:	None
QUERY FORM:	Only query form. The contents of the 8 bit register are returned as a hexadecimal value. If an error occurs, the corresponding bit is set to 1.
RESTRICTIONS:	None

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Temperature compensation	U cable breakage	Current not settled	Underdrive limits of the A/D converter fallen short of	Overdrive limits of the A/D converter exceeded	I over resistance of the test object or line too high	MU over measurement amplifier of the potential taps overdriven	MI over resistance of the test object or line too high

STATus:QUEStionable:TEMPerature? (short form -> S:Q:T?)

DESCRIPTION:	The status of the temperature measurement is returned.
SYNTAX:	**STATus:QUEStionable:TEMPerature? oder S:Q:T?**
PARAMETERS:	None
QUERY FORM:	Only query form. The contents of the 8 bit register are returned as a hexadecimal value. In the event of an error, the corresponding bit is set to 1
RESTRICTIONS:	None

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
-	Voltage supply in measurement section not OK	Invalid temperature	Invalid resistance Pt100 might be reverse connected	I cable breakage or no Pt100	U cable breakage	I cable breakage	I cable breakage or high impedance

STATus:PRESet

DESCRIPTION:	The Operation Status Enable Register and the Questionable Status Enable Register are reset.
SYNTAX:	**STATus:PRESet**
PARAMETERS:	None
QUERY FORM:	None
RESTRICTIONS:	None

5.3.2 SYSTem Subsystem

SYSTem:ERRor?

DESCRIPTION:	The contents of the error buffer are requested.
SYNTAX:	**SYSTem:ERRor?**
PARAMETERS:	None
QUERY FORM:	Only query form
RESTRICTIONS:	None

List of error messages

-0, NO ERROR:	No error is present.
-100, COMMAND ERROR:	An invalid command was sent.
-101, INVALID CHARACTER:	The command contains an invalid character.
-105, GET NOT ALLOWED:	GET was sent within another command.
-109, MISSING PARAMETER:	A parameter is missing.
-110, COMMAND HEADER ERROR:	The command has an invalid header.
-120, NUMERIC DATA ERROR:	A numerical value is invalid.
-200, EXECUTION ERROR:	Due to a particular device state, the command could not be executed.
-204, ILLEGAL DEVICE STATE:	The command is valid but cannot be executed in the present state of the device.
-213, INIT IGNORED:	The INITialize command was ignored.
-220, PARAMETER ERROR:	The command has an invalid parameter.
-221, SETTING CONFLICT:	Due to particular setting, the command with the related parameter cannot be executed.
-222, DATA OUT OF RANGE:	A parameter lies outside the valid limits.
-224, ILLEGAL PARAMETER VALUE:	The parameter is valid but not used by the device.
-231, DATA QUESTIONABLE:	The value of a parameter is questionable.
-350, QUEUE OVERFLOW:	The error buffer has overflowed.
-400, QUERY ERROR:	A query was sent although no data are present.
-410, QUERY INTERRUTED:	The device was interrupted before it could send a complete response.
-420, QUERY UNTERMINATED:	A response could not be terminated properly.

SYSTem:KLOCk

DESCRIPTION:	This locks the keypad of the device.
SYNTAX:	**SYSTem:KLOCk <parameter>**
PARAMETERS:	1 or ON -> The keypad is locked. 0 or OFF -> The keypad is released.
QUERY FORM:	**SYSTem:KLOCk?**
RESPONSE:	1, if the keypad is locked. 0, if the keypad is released.
RESTRICTION:	None

SYSTem:VERSion?

DESCRIPTION:	The SCPI version is requested.
SYNTAX:	**SYSTem:VERSion?**
PARAMETERS:	None
QUERY FORM:	Only query form
RESPONSE:	1995.0
RESTRICTION:	Keine

SYSTem:DATE

DESCRIPTION:	The date can be requested and adjusted here.
SYNTAX:	**SYSTem:DATE <parameter>**
PARAMETERS:	yyyy, mm, dd (year, month, day)
QUERY FORM:	**SYSTem:DATE?**
RESPONSE:	dd.mm.yy (day, month, year)
RESTRICTION:	None

SYSTem:TIME

DESCRIPTION:	The time can be requested and adjusted here
SYNTAX:	**SYSTem:TIME <parameter>**
PARAMETERS:	hh, mm, ss (hours, minutes, seconds)
QUERY FORM:	**SYSTem:TIME?**
RESPONSE:	hh:mm:ss (hours, minutes, seconds)
RESTRICTION:	None

5.3.3 DISPlay Subsystem

DISPlay:CONTrast

DESCRIPTION:	The LCD contrast is adjusted here.
SYNTAX:	**DISPlay:CONTrast <parameter>**
PARAMETERS:	A value between 0 and 1. 1 -> maximum contrast, 0 -> minimum contrast
QUERY FORM:	**DISPlay:CONTrast?**
RESPONSE:	A value between 0 and 1.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DISPlay:RANGe

DESCRIPTION:	This activates/deactivates the measurement range display in the main menu.
SYNTAX:	**DISPlay:RANGe <parameter>**
PARAMETERS:	1 or ON -> The measurement range is displayed. 0 or OFF -> The measurement range is not displayed
QUERY FORM:	**DISPlay:RANGe?**
RESPONSE:	1 -> If the measurement range display is active. 0 -> If the measurement range display is inactive.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DISPlay:CURRent

DESCRIPTION:	This activates/deactivates the measurement current display in the main menu.
SYNTAX:	**DISPlay:CURRent <parameter>**
PARAMETERS:	1 or ON -> The measurement current is displayed. 0 or OFF -> The measurement current is not displayed
QUERY FORM:	**DISPLay:CURRent?**
RESPONSE:	1 -> If the measurement current display is active. 0 -> If the measurement current display is inactive.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DISPlay:TEMPerature

DESCRIPTION:	This activates/inactivates the display of the temperature or setpoint value in the main menu.
SYNTAX:	**DISPlay:TEMPerature <parameter>**
PARAMETERS:	1 or ON -> Temperature or setpoint value display is on. 0 or OFF -> Temperature or setpoint value display is off.
QUERY FORM:	**DISPlay:TEMPerature?**
RESPONSE:	1 -> If the temperature or setpoint value display is on. 0 -> If the temperature or setpoint value display is off.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DISPlay:SAMPle

DESCRIPTION:	This activates/inactivates the sample display in the main menu.
SYNTAX:	**DISPlay:SAMPle <parameter>**
PARAMETERS:	1 or ON -> A sample signal is displayed. 0 or OFF -> A sample signal is not displayed.
QUERY FORM:	**DISPlay:SAMPle?**
RESPONSE:	1 -> If a sample signal is displayed. 0 -> If a sample signal is not displayed.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DISPlay:TRIGger

DESCRIPTION:	The activates/deactivates the display of single and continuous measurement in the main menu.
SYNTAX:	**DISPlay:TRIGger <parameter>**
PARAMETERS:	1 or ON -> The display of single and continuous measurements is on. 0 or OFF-> The display of single and continuous measurements is off.
QUERY FORM:	**DISPlay:TRIGger?**
RESPONSE:	1 -> If single/continuous measurement display is on. 0 -> If single/continuous measurement display is off.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DISPlay:AUTO

DESCRIPTION:	The activates/deactivates the AUTO / display in the main menu.
SYNTAX:	**DISPlay:AUTO <parameter>**
PARAMETERS:	1 or ON -> AUTO / MAN display on. 0 or OFF -> AUTO / MAN display off.
QUERY FORM:	**DISPlay:AUTO?**
RESPONSE:	1 -> If AUTO / MAN display is on. 0 -> If AUTO / MAN display is off.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DISPlay:LOAD

DESCRIPTION:	This activates/deactivates the R/Z display in the main menu.
SYNTAX:	**DISPlay:LOAD <parameter>**
PARAMETERS:	1 or ON -> R/Z display is on. 0 or OFF -> R/Z display is off.
QUERY FORM:	**DISPlay:LOAD?**
RESPONSE:	1 -> If R/Z display is on 0 -> If R/Z display is off.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DISPlay:MEASure

DESCRIPTION:	The activates/deactivates the measured value display.
SYNTAX:	**DISPlay:MEASure <parameter>**
PARAMETERS:	1 or ON -> Measured value display is on. 0 or OFF -> Measured value display is off.
QUERY FORM:	**DISPlay:MEASure?**
RESPONSE:	1 -> If measured value display is on. 0 -> If measured value display is off.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode. The measured value display is re-activated automatically in the local mode and when the device is turned on/off.

5.3.4. SOURce Subsystem

SOURce:VOLTage:LIMit:STATe

DESCRIPTION:	This activates/deactivates the 20 mV limiter.
SYNTAX:	**SOURce:VOLTage:LIMit:STATe <parameter>**
PARAMETERS:	1 or ON -> The 20mV limiter is on. 0 or OFF -> The 20mV limiter is off.
QUERY FORM:	**SOURce:VOLTage:LIMit:STATe?**
RESPONSE:	1 -> If the 20mV limiter is on. 0 -> If the 20mV limiter is off.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

5.3.5 TRIGger Subsystem

INITiate:CONTinuous

DESCRIPTION:	This effects a switchover between single and continuous measurement.
SYNTAX:	**INITiate:CONTinuous <parameter>**
PARAMETERS:	1 or ON -> Continuous measurements is set. 0 or OFF -> Single measurements is set.
QUERY FORM:	**INITiate:CONTinuous?**
RESPONSE:	1 -> If continuous measurement is set. 0 -> If single measurement is set.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

INITiate[:IMMediate] (Kurzform -> IN)

DESCRIPTION:	This commences a resistance measurement.
SYNTAX:	**INITiate[:IMMediate]**
PARAMETERS:	None
QUERY FORM:	None
RESPONSE:	—
REMARKS:	This command also exists in a special short form: **IN**
RESTRICTION:	This command is not permissible in the calibration mode.

ABORt   (short form -> AB)

DESCRIPTION:	This stops a measurement.
SYNTAX:	**ABORt**
PARAMETERS:	None
QUERY FORM:	None
RESPONSE:	—
REMARKS:	This command also exists in a special short form: **AB**
RESTRICTION:	This command is not permissible in the calibration mode.

5.3.6 Measurement Instructions

FETCh? (Kurzform -> FE?)

DESCRIPTION:	This requests a measured resistance value, which is subsequently written to the output buffer.
SYNTAX:	**FETCh?**
PARAMETERS:	None
QUERY FORM:	Only query form
RESPONSE:	The measured resistance value with a unit. and valuation For example: 134.75OHM
REMARKS:	This command also exists in a special short form: **FE?**
RESTRICTION:	This command is not permissible in the calibration mode or if a measurement has been stopped in the absence of any measured values.

5.3.7 MEMory Subsystem

MEMory:STATe:DEFine

DESCRIPTION:	This assigns an ID to a memory number (device setting).
SYNTAX:	**MEMory:STATe:DEFine <ID>,<number>**
PARAMETERS:	Identification: 10-character ASCII string Number: Memory number from 0 to 32
QUERY FORM:	**MEMory:STATe:DEFine? <ID>**
RESPONSE:	The memory number (0 to 32) related to the ID is returned.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

MEMory:STATe:NAME

DESCRIPTION:	This supplies the ID related to a memory number (device setting).
SYNTAX:	**MEMory:STATe:NAME? <number>**
PARAMETERS:	A memory number between 0 and 32
QUERY FORM:	Only query form.
RESPONSE:	An ID with a maximum length of 10 characters related to the memory number.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

5.3.8 REGister Subsystem

REGister:OUTPut

DESCRIPTION:	This sets/resets the 3 spare outputs.		
	Bit 2	Bit 1	Bit 0
	SPARE OUTPUT 3	SPARE OUTPUT 2	SPARE OUTPUT 1
SYNTAX:	**REGister:OUTPut <parameter>**		
PARAMETERS:	A value between 0 and 7. The 3 spare outputs are set/reset in accordance with this value.		
QUERY FORM:	**REGister:OUTPut?**		
RESPONSE:	A value between 0 and 7, in accordance with the states of the spare outputs.		
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.		

REGister:INPut?

DESCRIPTION:	This reads in the 4 spare inputs.			
SYNTAX:	**REGister:INPut?**			
PARAMETERS:	None			
QUERY FORM:	Only query form			
RESPONSE:	A value between 0 and 15, depending on the states of the spare inputs.			
	BIT 3	BIT 2	BIT 1	BIT 0
	SPARE INPUT 4	SPARE INPUT 3	SPARE INPUT 2	SPARE INPUT 1
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.			

5.3.9 HCOPy Subsystem

HCOPy:ABORt

DESCRIPTION:	This stops the printer.
SYNTAX:	**HCOPy:ABORt**
PARAMETERS:	None
QUERY FORM:	**HCOPy:ABORt?**
RESPONSE:	1 -> If the printer function is on. 0 -> If the printer function is off.
RESTRICTION:	This command is not permissible in the calibration mode.

HCOPy[:IMMediate]

DESCRIPTION:	This starts the printer.
SYNTAX:	**HCOPy[:IMMediate]**
PARAMETERS:	None
QUERY FORM:	**HCOPy[:IMMediate]?**
RESPONSE:	1 -> If the printer function is on. 0 -> If the printer function is off.
RESTRICTION:	This command is not permissible in the calibration mode.

HCOPy:ITEM:TEMPerature:STATe

DESCRIPTION:	This activates/deactivates temperature printout.
SYNTAX:	**HCOPy:ITEM:TEMPerarture:STATe <parameter>**
PARAMETERS:	1 or ON -> The temperature is printed out. 0 or OFF -> The temperature is not printed out.
QUERY FORM:	**HCOPy:ITEM:TEMPerarture:STATe?**
RESPONSE:	1 -> If temperature printout is active. 0 -> If temperature printout is inactive.
REMARKS:	The temperature is only printed out if temperature compensation is also active.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

HCOPy:ITEM:NUMerator:STATe

DESCRIPTION:	This activates/deactivates printing of the numerator.
SYNTAX:	**HCOPy:ITEM:NUMerator:STATe <parameter>**
PARAMETERS:	1 or ON -> The numerator is printed out. 0 or OFF -> The numerator is not printed out.
QUERY FORM:	**HCOPy:ITEM:NUMerator:STATe?**
RESPONSE:	1 -> If numerator printout is active. 0 -> If numerator printout is inactive.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

HCOPy:ITEM:LABel:STATe

DESCRIPTION:	This activates/deactivates labelling.
SYNTAX:	**HCOPy:ITEM:LABel:STATe <parameter>**
PARAMETERS:	1 or ON -> The label is printed out in the header. 0 or OFF -> The label is not printed out in the header.
QUERY FORM:	**HCOPy:ITEM:LABel:STATe?**
RESPONSE:	1 -> If label printout is active. 0 -> If label printout is inactive.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

HCOPy:ITEM:TIME:STATe

DESCRIPTION:	This activates/deactivates printing of the time.
SYNTAX:	**HCOPy:ITEM:TIME:STATe <parameter>**
PARAMETERS:	1 or ON -> The time is printed out. 0 or OFF -> The time is not printed out.
QUERY FORM:	**HCOPy:ITEM:TIME:STATe**?
RESPONSE:	1 -> If time printout is active. 0 -> If time printout is inactive.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

HCOPy:ITEM:Date:STATe

DESCRIPTION:	This activates/deactivates printing of the date.
SYNTAX:	**HCOPy:DATE:LABel:STATe <parameter>**
PARAMETERS:	1 or ON -> The date is printed out. 0 or OFF -> The date is not printed out.
QUERY FORM:	**HCOPy:DATE:LABel:STATe?**
RESPONSE:	1 -> If date printout is active. 0 -> If date printout is inactive.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

HCOPy:NUMerator:RESet

DESCRIPTION:	This resets the numerator to 0.
SYNTAX:	**HCOPy:NUMerator:RESet**
PARAMETERS:	None
QUERY FORM:	No query form
RESPONSE:	—
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

HCOPy:ITEM:LABel:TEXT

DESCRIPTION:	This requests the label for printout.
SYNTAX:	**HCOPy:ITEM:LABel:TEXT <label>**
PARAMETERS:	Label (ASCII string) with a maxmium length of 10 characters.
QUERY FORM:	**HCOPy:ITEM:LABel:TEXT?**
RESPONSE:	The selected label with a maxmium length of 10 characters.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

HCOPy:TDSTam

DESCRIPTION:	This sets the printing time interval.
SYNTAX:	**HCOPy:TDSTamp <hh>,<mm>,<ss>**
PARAMETERS:	The printing time interval: hh,mm,ss. The hours, minutes and seconds are separated from each other with commas.
QUERY FORM:	**HCOPy:TDSTamp?**
RESPONSE:	The selected printing time interval: hh,mm,ss. The hours, minutes and seconds are separated from each other with commas:
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

HCOPy:HEADer

DESCRIPTION:	This sets the number of measured values to be printed out per header.
SYNTAX:	**HCOPy:HEADer <parameter>**
PARAMETERS:	Measured values/header: A number between 1 and 1000.
QUERY FORM:	**HCOPy:HEADer?**
RESPONSE:	The selected number: Measured values/header.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

5.3.10 CALCulate Subsystem

CALCulate:LIMit:STATe

DESCRIPTION:	This activates/deactivates the comparator.
SYNTAX:	**CALCulate:LIMit:STATe <parameter>**
PARAMETERS:	1 or ON -> The comparator is on. 0 or OFF -> The comparator is off.
QUERY FORM:	**CALCulate:LIMit:STATe?**
RESPONSE:	1 -> If the comparator is on. 0 -> If the comparator is off.
RESTRICTION:	This command is not permissible in the calibration mode.

CALCulate:LIMit:COUNt

DESCRIPTION:	This sets the number of limiting values (2 or 4) for the comparator.
SYNTAX:	**CALCulate:LIMit:COUNt <parameter>**
PARAMETERS:	2 -> 2 limiting values are set. 4 -> 4 limiting values are set.
QUERY FORM:	**CALCulate:LIMit:COUNt?**
RESPONSE:	2 -> If 2 limiting values have been set. 4 -> If 4 limiting values have been set.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:LIMit:RELais

DESCRIPTION:	This activates/deactivates the comparator relay.
SYNTAX:	**CALCulate:LIMit:RELais <parameter>**
PARAMETERS:	1 or ON -> The relay is turned on. 0 or OFF-> The relay is turned off.
QUERY FORM:	**CALCulate:LIMit:RELais?**
RESPONSE:	1 -> The relay is on. 0 -> The relay is off.
RESTRICTION:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:LIMit:FAULt

DESCRIPTION:	This specifies the comparator's response in the event of a measurement error.
SYNTAX:	**CALCulate:LIMit:FAULt <parameter>**
PARAMETERS:	UPPer -> In the event of an error, the comparator indicates that the measured value is too high.
	NONE -> The comparator does not respond in the event of an error.
QUERY FORM:	**CALCulate:LIMit:FAULt?**
RESPONSE:	UPPER -> If the comparator indicates that the measured value is too high in the event of an error.
	NONE -> If the comparator does not respond in the event of an error.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:MATH:EXPRession

DESCRIPTION:	This sets the measurement-value display mode.	
SYNTAX:	**CALCulate:MATH:EXPRession <parameter>**	
PARAMETERS:	OHM ->	Measured values are displayed in OHM.
	DELTa ->	Measured values are displayed as Δ % of a setpoint value.
	LIMit ->	The evaluation is displayed.
QUERY FORM:	**CALCulate:MATH:EXPRession?**	
RESPONSE:	OHM ->	If the OHM display has been selected.
	DELTA ->	If the Δ % display has been selected.
	LIMIT ->	If the evaluation display has been selected.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.	

CALCulate:LIMit:LOWer

DESCRIPTION:	This specifies the lower limit when 2 comparator limits are selected.
SYNTAX:	**CALCulate:LIMit:LOWer <parameter>**
PARAMETERS:	The lower limit with an optional unit. Valid units: UOHM, MOHM, OHM, KOHM, MAOHM. If no unit is specified, the unit of the value is interpreted as OHM.
QUERY FORM:	**CALCulate:LIMit:LOWer?**
RESPONSE:	The lower limit of 2 comparator limits (value with unit).
BEMERKUNGEN:	The value transferred with this command needs to be acknowledged with CALCulate:LIMit:ACKNowledge (page 103). The validity of this value is tested with respect to the remaining limits.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:LIMit:UPPer

DESCRIPTION	This specifies the upper limit when 2 comparator limits are selected.
SYNTAX	**CALCulate:LIMit:UPPer <parameter>**
PARAMETERS	The upper limit with an optional unit. Valid units: UOHM, MOHM, OHM, KOHM, MAOHM. If no unit is specified, the unit of the value is interpreted as OHM.
QUERY FORM	**CALCulate:LIMit:UPPer?**
RESPONSE	The upper limit of 2 comparator limits (value with unit).
BEMERKUNGEN	The value transferred with this command needs to be acknowledged with CALCulate:LIMit:ACKNowledge (page 103). The validity of this value is tested with respect to the remaining limits.
RESTRICTIONS	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:LIMit:GW1

DESCRIPTION:	This specifies limiting value 1 (smallest value GW1) when 4 comparator limits are selected.
SYNTAX:	**CALCulate:LIMit:GW1<parameter>**
PARAMETERS:	Limit 1 with an optional unit. Valid units: UOHM, MOHM, OHM, KOHM, MAOHM. If no unit is specified, the unit of the value is interpreted as OHM.
QUERY FORM:	**CALCulate:LIMit:GW1?**
RESPONSE:	Limit 1 of 4 selected comparator limits (value with unit).
BEMERKUNGEN:	The value transferred with this command needs to be acknowledged with CALCulate:LIMit:ACKNowledge (page 100). The validity of this value is tested with respect to the remaining limits.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:LIMit:GW2

DESCRIPTION:	This specifies limiting value 2 (third largest value GW2) when 4 comparator limits are selected.
SYNTAX:	**CALCulate:LIMit:GW2<parameter>**
PARAMETERS:	Limit 2 with an optional unit. Valid units: UOHM, MOHM, OHM, KOHM, MAOHM. If no unit is specified, the unit of the value is interpreted as OHM.
QUERY FORM:	**CALCulate:LIMit:GW2?**
RESPONSE:	Limit 2 of 4 selected comparator limits (value with unit).
BEMERKUNGEN:	The value transferred with this command needs to be acknowledged with CALCulate:LIMit:ACKNowledge (page 103). The validity of this value is tested with respect to the remaining limits.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:LIMit:GW3

DESCRIPTION:	This specifies limiting value 3 (second largest value GW3) when 4 comparator limits are selected.
SYNTAX:	**CALCulate:LIMit:GW3<parameter>**
PARAMETERS:	Limit 3 with an optional unit. Valid units: UOHM, MOHM, OHM, KOHM, MAOHM. If no unit is specified, the unit of the value is interpreted as OHM.
QUERY FORM:	**CALCulate:LIMit:GW3?**
RESPONSE:	Limit 3 of 4 selected comparator limits (value with unit).
BEMERKUNGEN:	The value transferred with this command needs to be acknowledged with CALCulate:LIMit:ACKNowledge (page 103). The validity of this value is tested with respect to the remaining limits.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:LIMit:GW4

DESCRIPTION:	This specifies limiting value 4 (largest value GW4) when 4 comparator limits are selected.
SYNTAX:	**CALCulate:LIMit:GW4<parameter>**
PARAMETERS:	Limit 4 with an optional unit. Valid units: UOHM, MOHM, OHM, KOHM, MAOHM. If no unit is specified, the unit of the value is interpreted as OHM.
QUERY FORM:	**CALCulate:LIMit:GW4?**
RESPONSE:	Limit 4 of 4 selected comparator limits (value with unit).
BEMERKUNGEN:	The value transferred with this command needs to be acknowledged with CALCulate:LIMit:ACKNowledge (page 103). The validity of this value is tested with respect to the remaining limits.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:LIMit:ACKNowledge?

DESCRIPTION:.	This tests and saves the comparator limits.
SYNTAX:	**CALCulate:LIMit:ACKNowledge?**
PARAMETERS:	None
QUERY FORM:	Only query form
RESPONSE:	1 -> If the limit test is OK, the values are saved. 0 -> If the limit test is not OK, the values are not saved.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:LIMit:CLEar

DESCRIPTION:	This deletes the statistical results provided by the comparator.
SYNTAX:	**CALCulate:LIMit:CLEar**
PARAMETERS:	None
QUERY FORM:	No query form
RESPONSE:	—
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

CALCulate:LIMit:REPort

DESCRIPTION:	This requests the statistical results provided by the comparator.
SYNTAX:	**CALCulate:LIMit:REPort?**
PARAMETERS:	None
QUERY FORM:	Only query form
RESPONSE:	If 2 limits are set: value1, value2, value3 value1: No. of meas. values < lower limit value2: Lower limit >=No. of meas. values<=upper limit value3: No. of meas. values > upper limit If 4 limits are set: value1, value2, value3, value4, value5 value1: No. of meas. values < limit1 value2: limit1 >= No. of meas. values < limit2 value3: limit2 >= No. of meas. values <= limit3 value4: limit3 > No. of meas. values <= limit4 value5: No. of meas. values > limit4.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

5.3.11 SENSe Subsystem

SENSe:TCOMpensate

DESCRIPTION:	This sets the type of temperature measurement for temperature compensation.
SYNTAX:	**SENSe:TCOMpensate <parameter>**
PARAMETERS:	MAN -> The temperature value entered via the interface or keypad is used. Pt100 -> Measurement via the Pt100 input. UINP -> Measurement via the external U-input. IINP -> Measurement via the external I-input.
QUERY FORM:	**SENSe:TCOMpensate?**
RESPONSE:	MAN -> If manual temperature entry is selected. Pt100 -> If temperature measurement via the Pt100 is selected. UINP -> If temperature measurement via the ext. U-input is selected. IINP -> If temperatu
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:FRESistance:REFerence

DESCRIPTION:	This select the reference value for Δ % display.
SYNTAX:	**SENSe:FRESistance:REFerence <parameter>**
PARAMETERS:	The reference value, optionally with a unit. Valid units: UOHM, MOHM, OHM, KOHM, MAOHM If no unit is specified, the unit of the value is interpreted as OHM.
QUERY FORM:	**SENSe:FRESistance:REFerence?**
RESPONSE:	The selected reference value and unit.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENse:ENVelope:STATe

DESCRIPTION:	This activates/deactivates the max./min. function
SYNTAX:	**SENSe:ENVelope:STATe <parameter>**
PARAMETERS:	1 or ON -> The max./min. function is on. 0 or OFF -> The max./min. function is off.
QUERY FORM:	**SENSe:ENVelope:STATe?**
RESPONSE:	1 -> If the max./min. function is on. 0 -> If the max./min. function is off.
RESTRICTIONS:	This command is not permissible if the device is in the calibration mode.

SENSe:TCOMpensate:STATe

DESCRIPTION:	This activates/deactivates temperature compensation.
SYNTAX:	**SENSe:TCOMpensate:STATe <parameter>**
PARAMETERS:	1 or ON -> Temperature compensation is on. 0 or OFF -> Temperature compensation is off.
QUERY FORM:	**SENSe:TCOMpensate:STATe?**
RESPONSE:	1 -> If temperature compensation is on. 0 -> If temperature compensation is off.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

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SENSe:ENVelope:CLEar

DESCRIPTION:	This deletes the minimum and maximum values.
SYNTAX:	**SENSe:ENVelope:CLEar**
PARAMETERS:	None
QUERY FORM:	No query form
RESPONSE:	—
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:TCOMpensate:TEMPerature

DESCRIPTION:	This sets the temperature for manual temperature compensation. In the query form you get the present temperature.
SYNTAX:	**SENSe:TCOMpensate:TEMPerature <parameter>**
PARAMETERS:	Temperature value, optionally with a unit (C or CEL)
QUERY FORM:	**SENSe:TCOMpensate:TEMPerature?**
RESPONSE:	The set temperature value and a corresponding unit (CEL) or the topical temperature at autom. temp. measurement.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:FRESistance:LOAD

DESCRIPTION:	This selects the type of test object (R or Z).
SYNTAX:	**SENSe:FRESistance:LOAD <parameter>**
PARAMETERS:	REAL -> R is set (purely ohmic load) COMPlex -> Z is set (inductive component)
QUERY FORM:	**SENSe:FRESistance:LOAD?**
RESPONSE:	REAL -> If R is set. COMP -> If Z is set.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:AVERage:COUNt

DESCRIPTION:	This sets the number of averaging operations.
SYNTAX:	**SENSe:AVERage:COUNt <parameter>**
PARAMETERS:	Number of averaging operations. Value range: 1 to 100
QUERY FORM:	**SENSe:AVERage:COUNt?**
RESPONSE:	The set number of averaging operations.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:AVERage:TCONtrol

DESCRIPTION:	The selects the type of averaging operation.
SYNTAX:	**SENSe:AVERage:TCONtrol <parameter>**
PARAMETERS:	MOVing -> A moving average value is formed. REPeat -> Average values are formed repeatedly.
QUERY FORM:	**SENSe:AVERage:TCONtrol?**
RESPONSE:	MOV -> If a moving average value is selected. REP -> If a refreshed average value is selected.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:FRESistance:RESolution

DESCRIPTION:	This sets the resolution for the measurement-value display.
SYNTAX:	**SENSe:FRESistance:RESolution <parameter>**
PARAMETERS:	0.0005 -> A low resolution (2000) is set. 0.00005 -> A high resolution (20000) is set.
QUERY FORM:	**SENSe:FRESistance:RESolution?**
RESPONSE:	0.0005 -> If a low resolution has been set. 0.00005 -> If a high resolution has been set.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:FRESistance:NPLCycles

DESCRIPTION:	This sets the number of conversions.
SYNTAX:	**SENSe:FRESistance:NPLCycles <parameter>**
PARAMETERS:	Number of conversions (4 stages). MAXimum, STANdard, MEDium or MINimum
QUERY FORM:	**SENSe:FRESistance:NPLCycles?**
RESPONSE:	Selected conversion stage. (MAXimum, STANdard, MEDium or MINimum)
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:FRESistance:MODE

DESCRIPTION:	This sets the type of measurement procedure.
SYNTAX:	**SENSe:FRESistance:MODE <parameter>**
PARAMETERS:	REFComp -> Zero measurement. NONComp -> No zero measurement. ONEComp -> Single zero measurement at the start. STANdard -> Alternate zero measurement and measurement with the power on. ITEST -> Measuring current monitoring (continuity tester)
QUERY FORM:	**SENSe:FRESistance:MODE?**
RESPONSE:	REFC -> If zero measurement is selected. NONC -> If no zero measurement is selected. ONEC -> If single zero measurement is selected. STAN -> If alternate zero measurement and power-on measurement are selected ITEST -> Measuring current monitoring (continuity tester)
	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:ENVelope:REPort:DATA

DESCRIPTION:	The maximum and minimum values can be fetched.
SYNTAX:	**SENSe:ENVelope:REPort:DATA?**
PARAMETERS:	None
QUERY FORM:	Only query form
RESPONSE:	Minimum value, maximum value, difference
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:TCOMpensate:TCOefficient:SELect

DESCRIPTION:	This selects one of 10 different temperature coefficients.
SYNTAX:	**SENSe:TCOMpensate:TCOefficient:SELect <parameter>**
PARAMETERS:	A value between 1 and 10 (number of the coefficient)
QUERY FORM:	**SENSe:TCOMpensate:TCOefficient:SELect?**
RESPONSE:	The value of the present temperature coefficient.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:TCOMpensate:TEMPerature:REFerence

DESCRIPTION:	This sets the reference temperature for temperature compensation.
SYNTAX:	**SENSe:TCOMpensate:TEMPerature:REFerence <parameter>**
PARAMETERS:	The reference temperature, optionally with a unit (C or CEL).
QUERY FORM:	**SENSe:TCOMpensate:TEMPerature:REFerence?**
RESPONSE:	The selected reference temperature and a corresponding unit (CEL).
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:TCOMpensate:TCOefficient

DESCRIPTION:	This selects one of 10 different temperature coefficients.
SYNTAX:	**SENSe:TCOMpensate:TCOefficient <number>, <value>**
PARAMETERS:	Number -> The number of the coefficient (1 to 10) Value -> The value of the temperature coefficient. (Value range: - 9999 to 9999)
QUERY FORM:	**SENSe:TCOMpensate:TCOefficient? <number>**
RESPONSE:	The temperature coefficient related to the number.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:FRESistance:RANGe:AUTO

DESCRIPTION:	This effects a switchover between automatic and manual range selection. With the query form the present range will send devide with a comma.
SYNTAX:	**SENSe:FRESistance:RANGe:AUTO <parameter>**
PARAMETERS:	1 or ON -> Automatic range selection is active. 0 or OFF -> Manual range selection is active.
QUERY FORM:	**SENSe:FRESistance:RANGe:AUTO?**
RESPONSE:	1.2 OHM -> If automatic range selection and range 2Ω is active. 0.2 OHM -> If manual range selection and range 2Ω is active.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:FRESistance:RANGe:UPPer

DESCRIPTION:	This sets the largest permissible measurement range for automatic range selection.
SYNTAX:	**SENSe:FRESistance:RANGe:UPPer <parameter>**
PARAMETERS:	2OHM -> largest range is 2 Ω. 20OHM -> largest range is 20 Ω. 200OHM -> largest range is 200 Ω. 2KOHM -> largest range is 2 kΩ. 20KOHM -> largest range is 20 kΩ. 200kOHM -> largest range is 200 kΩ.
QUERY FORM:	**SENSe:FRESistance:RANGe:UPPer?**
RESPONSE:	2OHM -> if largest range is 2 Ω. 20OHM -> if largest range is 20 Ω. 200OHM -> if largest range is 200 Ω. 2KOHM -> if largest range is 2 kΩ. 20KOHM -> if largest range is 20 kΩ. 200kOHM -> if largest range is 200 kΩ.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:FRESistance:RANGe:LOWer

DESCRIPTION:	This sets the smallest permissible measurement range for automatic range selection.
SYNTAX:	**SENSe:FRESistance:RANGe:LOWer <parameter>**
PARAMETERS:	200MOHM -> smallest range is 200 mΩ. 2OHM -> smallest range is 2 Ω. 20OHM -> smallest range is 20 Ω. 200OHM -> smallest range is 200 Ω. 2KOHM -> smallest range is 2 kΩ. 20kOHM -> smallest range is 20 kΩ.
QUERY FORM:	**SENSe:FRESistance:RANGe:LOWer?**
RESPONSE:	200MOHM -> if smallest range is 200 mΩ. 2OHM -> if smallest range is 2 Ω. 20OHM -> if smallest range is 20 Ω. 200OHM -> if smallest range is 200 Ω. 2KOHM -> if smallest range is 2 kΩ. 20kOHM -> if smallest range is 20 kΩ.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SENSe:FRESistance:RANGe:MANual

DESCRIPTION:	This sets the measuring range for manual range selection.
SYNTAX:	**SENSe:FRESistance:RANGe:MANual <parameter>**
PARAMETERS:	200MOHM -> manual range is 200 mΩ. 2OHM -> manual range is 2 Ω. 20OHM -> manual range is 20 Ω. 200OHM -> manual range is 200 Ω. 2KOHM -> manual range is 2 kΩ. 20KOHM -> manual range is 20 kΩ. 200KOHM -> manual range is 200 kΩ.
QUERY FORM:	**SENSe:FRESistance:RANGe:MANual?**
RESPONSE:	200MOHM -> if manual range is 200 mΩ. 2OHM -> if manual range is 2 Ω. 20OHM -> if manual range is 20 Ω. 200OHM -> if manual range is 200 Ω. 2KOHM -> if manual range is 2 kΩ. 20KOHM -> if manual range is 20 kΩ. 200KOHM -> if manual range is 200 kΩ.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

5.3.12 SCALe Subsystem

SCALe:Pt100

DESCRIPTION:	This specifies the coefficient for the Pt100 curve in the range >= 0 C°.
SYNTAX:	**SCALe:Pt100 <R$_o$>,<A>,<B**
PARAMETERS:	R$_o$, A, B : The 3 coefficients are represented in the following equation: $R_t = R_o * (1 + A * t + B * t^2)$
QUERY FORM:	**SCALe:Pt100?**
RESPONSE:	R$_o$, A, B : The actual constants.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SCALe:VOLTage

DESCRIPTION:	This scales the external U-input.
SYNTAX:	**SCALe:VOLTage <u1>,<u2>,<t1>,<t2>**
PARAMETERS:	u1: Current value 1 (related to t1) u2: Current value 2 (related to t2) t1: Temperature value 1 (related to u1) t2: Temperature value 2 (related to u2) Both pairs of values are used to calculate the linearization curve.
QUERY FORM:	**SCALe:VOLTage?**
RESPONSE:	u1,u2,t1,t2
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

SCALe:CURRent

DESCRIPTION:	This scales the external I-input.
SYNTAX:	**SCALe:CURRent <i1>,<i2>,<t1>,<t2>**
PARAMETERS:	i1: Current value 1 (related to t1) i2: Current value 2 (related to t2) t1: Temperature value 1 (related to u1) t2: Temperature value 2 (related to u2) Both pairs of values are used to calculate the linearization curve.
QUERY FORM:	**SCALe:CURRent?**
RESPONSE:	i1,i2,t1,t2
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

5.3.13 ACCess Subsystem

ACCess:MEASure

DESCRIPTION:	This enables/disables access to the measurement-parameter menu.
SYNTAX:	**ACCess : MEASure <parameter>**
PARAMETERS:	1 or ON -> Enables access to the measurement-parameter menu. 0 or OFF ->Disables access to the measurement-parameter menu.
QUERY FORM:	**ACCess:MEASure?**
RESPONSE:	1 ->If access to the measurement-parameter menu is enabled. 0 ->If access to the measurement-parameter menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:EXPRession

DESCRIPTION:	This enables/disables access to the display-mode menu.
SYNTAX:	**ACCess : EXPRession <parameter>**
PARAMETERS:	1 or ON -> Enables access to the display-mode menu. 0 or OFF ->Disables access to the display-mode menu.
QUERY FORM:	**ACCess:EXPression?**
RESPONSE:	1 ->If access to the display-mode menu is enabled. 0 ->If access to the display-mode menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:PRINter

DESCRIPTION:	This enables/disables access to the printer menu.
SYNTAX:	**ACCess:PRINter <parameter>**
PARAMETERS:	1 or ON -> Enables access to the printer menu. 0 or OFF -> Disables access to the printer menu.
QUERY FORM:	**ACCess:PRINter?**
RESPONSE:	1 -> If access to the printer menu is enabled. 0 ->If access to the printer menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:COMPensation

DESCRIPTION:	This enables/disables access to the temperature-compensation menu.
SYNTAX:	**ACCess:COMPensation <parameter>**
PARAMETERS:	1 or ON -> Enables access to the temperature-compensation menu. 0 or OFF -> Disables access to the temperature-compensation
QUERY FORM:	**ACCess:COMPensation?**
RESPONSE:	1 -> If access to the temperature-compensation menu is enabled. 0 -> If access to the temperature-compensation menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:COMMunicate

DESCRIPTION:	This enables/disables access to the interface menu.

SYNTAX:	**ACCess:COMMunicate <parameter>**
PARAMETERS:	1 or ON -> Enables access to the interface menu. 0 or OFF -> Disables access to the interface menu.
QUERY FORM:	**ACCess:COMMunicate?**
RESPONSE:	1 -> If access to the interface menu is enabled. 0 -> If access to the interface menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:MEMory

DESCRIPTION:	This enables/disables access to the device-setting menu (for saving and loading device settings).
SYNTAX:	**ACCess:MEMory <parameter>**
PARAMETERS:	1 or ON -> Enables access to the device-setting menu. 0 or OFF -> Disables access to the device-setting menu.
QUERY FORM:	**ACCess:MEMory?**
RESPONSE:	1 ->If access to the device-setting menu is enabled. 0 ->If access to the device-setting menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:CONTrast

DESCRIPTION:	This enables/disables access to the contrast-setting menu.
SYNTAX:	**ACCess:CONTrast <parameter>**
PARAMETERS:	1 or ON -> Enables access to the contrast-setting menu. 0 or OFF -> Disables access to the contrast-setting menu.
QUERY FORM:	**ACCess:CONTrast?**
RESPONSE:	1 -> If access to the contrast-setting menu is enabled. 0 -> If access to the contrast-setting menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:STATe

DESCRIPTION:	This enables/disables access to the status-display menu.
SYNTAX:	**ACCess:STATe <parameter>**
PARAMETERS:	1 or ON -> Enables access to the status-display menu. 0 or OFF -> Disables access to the status-display menu.
QUERY FORM:	**ACCess:STATe?**
RESPONSE:	1 -> If access to the status-display menu is enabled. 0 ->If access to the status-display menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:REGister

DESCRIPTION:	This enables/disables access to the spare input/output menu.
SYNTAX:	**ACCess:REGister <parameter>**
PARAMETERS:	1 or ON -> Enables access to the spare input/output menu. 0 or OFF -> Disables access to the spare input/output menu.
QUERY FORM:	**ACCess:REGister?**
RESPONSE:	1 -> If access to the spare input/output menu is enabled. 0 -> If access to the spare input/output menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:CALibration

DESCRIPTION:	This enables/disables access to the calibration menu.
SYNTAX:	**ACCess:CALibration <parameter>**
PARAMETERS:	1 or ON -> Enables access to the calibration menu. 0 or OFF -> Disables access to the calibration menu.
QUERY FORM:	**ACCess:CALibration?**
RESPONSE:	1 -> If access to the calibration menu is enabled. 0 -> If access to the calibration menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:DATalogger

DESCRIPTION:	This enables/disables access to the datalogger menu.
SYNTAX:	**ACCess:DATalogger <parameter>**
PARAMETERS:	1 or ON -> Enables access to the datalogger menu. 0 or OFF -> Disables access to the datalogger menu.
QUERY FORM:	**ACCess:DATalogger?**
RESPONSE:	1 -> If access to the datalogger menu is enabled. 0 -> If access to the datalogger menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:SCALe

DESCRIPTION:	This enables/disables access to the scaling menu.
SYNTAX:	**ACCess:SCALe <parameter>**
PARAMETERS:	1 or ON -> Enables access to the scaling menu. 0 or OFF -> Disables access to the scaling menu.
QUERY FORM:	**ACCess:SCALer?**
RESPONSE:	1 -> If access to the scaling menu is enabled. 0 -> If access to the scaling menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:DATE

DESCRIPTION:	This enables/disables access to the date/time menu.
SYNTAX:	**ACCess:DATE <parameter>**
PARAMETERS:	1 or ON -> Enables access to the date/time menu. 0 or OFF -> Disables access to the date/time menu.
QUERY FORM:	**ACCess:DATE?**
RESPONSE:	1 -> If access to the date/time menu is enabled. 0 -> If access to the date/time menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:FAST

DESCRIPTION:	This enables/disables access to the identification menu.
SYNTAX:	**ACCess:FAST <parameter>**
PARAMETERS:	1 or ON -> Enables access to the identification menu. 0 or OFF -> Disables access to the identification menu. (Quick-Start)
QUERY FORM:	**ACCess:FAST?**
RESPONSE:	1 -> If access to the identification menu is enabled. 0 -> If access to the identification menu is disabled. (Quick-Start)
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:LIMit:CONfigure

DESCRIPTION:	This enables/disables access to the comparator-configuration menu.
SYNTAX:	**ACCess:LIMit:CONfigure <parameter>**
PARAMETERS:	1 or ON -> Enables access to the comparator-configuration menu. 0 or OFF -> Disables access to the comparator-configuration menu.
QUERY FORM:	**ACCess:LIMit:CONfigure?**
RESPONSE:	1 -> If access to the comparator-configuration menu is enabled. 0 -> If access to the comparator-configuration is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:ENVelope:CONfigure

DESCRIPTION:	This enables/disables access to the max./min. measurement function.
SYNTAX:	**ACCess:ENVElope:CONfigure <parameter>**
PARAMETERS:	1 or ON -> Enables access to the max./min. measurement function. 0 or OFF -> Disables access to the max./min. measurement function.
QUERY FORM:	**ACCess:ENVelope:CONfigure?**
RESPONSE:	1 -> If access to the max./min. measurement function is enabled. 0 -> If access to the max./min. measurement function is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:LIMit:EVALuation

DESCRIPTION:	This enables/disables access to the comparator-evaluation menu.
SYNTAX:	**ACCess:LIMit:EVALuation <parameter>**
PARAMETERS:	1 or ON -> Enables access to the comparator-evaluation menu. 0 or OFF -> Disables access to the comparator-evaluation menu.
QUERY FORM:	**ACCess:LIMit:EVALuation?**
RESPONSE:	1 -> If access to the comparator-evaluation menu is enabled. 0 -> If access to the comparator-evaluation menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:ENVelope:EVALuation

DESCRIPTION	This enables/disables access to the max./min. evaluation menu.
SYNTAX:	**ACCess:ENVelope:EVALuation <parameter>**
PARAMETERS:	1 or ON -> Enables access to the max./min. evaluation menu. 0 or OFF -> Disables access to the max./min. evaluation menu.
QUERY FORM:	**ACCess:ENVelope:EVALuation?**
RESPONSE:	1 -> If access to the max./min. evaluation menu is enabled. 0 -> If access to the max./min. evaluation menu is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

ACCess:MANRange

DESCRIPTION:	This enables/disables access to manual range selection. (From the main menu: RGE [↑] and RGE [↓] keys)
SYNTAX:	**ACCess:MANRange <parameter>**
PARAMETERS:	1 or ON -> Enables access to manual range selection. 0 or OFF -> Disables access to manual range selection.
QUERY FORM:	**ACCess:MANRange?**
RESPONSE:	1 -> If access to manual range selection is enabled. 0 -> If access to manual range selection is disabled.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

5.3.14 DATalogger Subsystem

DATalogger:STATe

DESCRIPTION:	This starts/stops the datalogger.
SYNTAX:	**DATalogger:STATe <parameter>**
PARAMETERS:	1 or ON -> The datalogger is started. 0 or OFF -> The datalogger is stopped.
QUERY FORM:	**DATalogger:STATe?**
RESPONSE:	1 -> If the datalogger is active. 0 -> If the datalogger is inactive.
RESTRICTIONS:	This command is not permissible if the device is in the calibration mode.

DATalogger:MINimum?

DESCRIPTION:	This calculates and fetches the minimum value of a datalogger block.
SYNTAX:	**DATalogger:MINimum? <parameter>**
PARAMETERS:	The datalogger block number (0 to 31).
QUERY FORM:	Only query form
RESPONSE:	The minimum value in MOHM, OHM or KOHM.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:MAXimum?

DESCRIPTION:	This calculates and fetches the maximum value of a datalogger block.
SYNTAX:	**DATalogger:MAXimum? <parameter>**
PARAMETERS:	The datalogger block number (0 to 31).
QUERY FORM:	Only query form
RESPONSE:	The maximum value in MOHM, OHM or KOHM.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:AVERage?

DESCRIPTION:	This calculates and fetches the average value of a datalogger block.
SYNTAX:	**DATalogger:AVERage? <parameter>**
PARAMETERS:	The datalogger block number (0 to 31).
QUERY FORM:	Only query form
RESPONSE:	The average value in MOHM, OHM or KOHM.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:DEViation?

DESCRIPTION:	This calculates and fetches the standard deviation of a datalogger block.
SYNTAX:	**DATalogger:DEViation? <parameter>**
PARAMETERS:	The datalogger block number (0 to 31).
QUERY FORM:	Only query form
RESPONSE:	The standard deviation in MOHM, OHM or KOHM.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:COUNt?

DESCRIPTION:	This returns the number of memory locations occupied by a datalogger block and the whole datalogger.
SYNTAX:	**DATalogger:COUNt? <parameter>**
PARAMETERS:	The datalogger block number (0 to 31).
QUERY FORM:	Only query form
RESPONSE:	Number of memory locations occupied by the datalogger block in question. Without the parameter it returns the free memory Locations of the whole datalogger.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:CLEar

DESCRIPTION:	This deletes a datalogger block.
SYNTAX:	**DATalogger:CLEar <parameter>**
PARAMETERS:	The datalogger block number (0 to 31).
QUERY FORM:	None
RESPONSE:	—
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:SELect:BLOCk

DESCRIPTION:	This selects a datalogger block by its number.
SYNTAX:	**DATalogger:SELect:BLOCk <parameter>**
PARAMETERS:	The datalogger block number (0 to 31).
QUERY FORM:	**DATalogger:SELect:BLOCk? <parameter>**
RESPONSE:	The number (0 to 31) of the selected datalogger block.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:SELect:NAME

DESCRIPTION:	This selects a datalogger block by its name.
SYNTAX:	**DATalogger:SELect:NAME <parameter>**
PARAMETERS:	The ID (max. length of 10 characters) of a datalogger block.
QUERY FORM:	**DATalogger:SELect:NAME? <parameter>**
RESPONSE:	The number (0 to 31) of the selected datalogger block.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:FILTer

DESCRIPTION:	This selects a datalogger filter.
SYNTAX:	**DATalogger:FILTer <bl>, <fi>**
PARAMETERS:	bl,fi bl: Block number between 0 and 31 fi: One of the following types of filter ALL -> All measurement values are stored. FAIL -> Only invalid measurement values are stored. NOFail -> Only valid measurement values are stored. XVALue -> Every xth measurement value is stored. YTIMe -> Storage at a defined time interval. DELTa -> Storage takes place only if the difference to the previously stored value > ΔR.
QUERY FORM:	**DATalogger:FILTer?<bl>**
RESPONSE:	Filter type of the corresponding datalogger block <bl>. ALL -> All measurement values are stored. FAIL -> Only invalid measurement values are stored. NOFail -> Only valid measurement values are stored. XVALue -> Every xth measurement value is stored. YTIM -> Storage at a defined time interval. DELT -> Storage takes place only if the difference previously stored value > ΔR.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:FILTer:XVALue

DESCRIPTION:	This sets the XVALue filter parameter for a datalogger block. Every xth value is stored in this case.
SYNTAX:	**DATalogger:FILTer:XVALue <bl>, <x-Wert>**
PARAMETERS:	bl, x-value bl -> Block number between 0 and 31. x-value -> Value between 2 and 9999.
QUERY FORM:	**DATalogger:FILTer:XVALue? <bl>**
RESPONSE:	The currently selected x-value of the corresponding datalogger block <bl>.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:FILTer:YTIMe

DESCRIPTION:	This sets the YTIMe filter parameter for a datalogger block. This is the time interval at which measured values are stored.
SYNTAX:	**DATalogger:FILTer:YTIMe <bl>, <hh>, <mm>, <ss>**
PARAMETERS:	bl, hh, mm, ss bl : Block number between 0 and 31. hh: Hours 0 to 90 mm: Minutes 0 to 59 ss: Seconds 0 to 59
QUERY FORM:	**DATalogger:FILTer:YTIMe? <bl>**
RESPONSE:	The selected time interval hh, mm, ss for the corresponding datalogger block <bl>.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:FILTer:DELTa

DESCRIPTION:	This sets the DELTa filter parameter for a datalogger block. A measured value is only stored if the difference to the previous value is larger than DELTa.
SYNTAX:	**DATalogger:FILTer:DELTa <bl>, <delta>**
PARAMETERS:	bl, delta bl -> Block number between 0 and 31. delta: Delta value between 0.01 MOHM and 200 KOHM
QUERY FORM:	**DATalogger:FILTer:DELTa? <bl>**
RESPONSE:	The currently selected delta value for the corresponding datalogger block <bl>.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:STATe:NAME?

DESCRIPTION:	This returns the name/ID related to a datalogger block number.
SYNTAX:	**DATalogger:STATe.NAME? <bl>**
PARAMETERS:	bl: Block number between 0 and 31.
QUERY FORM:	Only query form
RESPONSE:	The ID (max. length of 10 characters) of datalogger block number <bl>.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:STATe:DEFine

DESCRIPTION:	This assigns a name/ID to the datalogger block with the selected number. The query form returns the name (ID) of the corresponding block number.
SYNTAX:	**DATalogger:STATe:DEFine <name>, <bl>**
PARAMETERS:	name: ID (max. length of 10 characters) of the datalogger block. bl: Number of the datalogger block, 0 to 31.
QUERY FORM:	**DATalogger:STATe:DEFine? <name>**
RESPONSE:	The number of the datalogger block with the corresponding name (ID).
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:DATA:FRESistance?

DESCRIPTION:	This retrieves a measured value stored in a datalogger block.
SYNTAX:	**DATalogger:DATA:FRESistance? <bl>, <num>**
PARAMETERS:	bl: Block number 0 to 31, num: Number of the measured value in the block (num >=1)
QUERY FORM:	Only query form
RESPONSE:	Stored resistance value
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DA? (short form)

DESCRIPTION:	This retrieves 20 measurement values stored in a datalogger block.
SYNTAX:	**DA? <bl>, <num>**
PARAMETERS:	bl: Block number 0 to 31 num: Number of the measurement value in the block (num >=1)
QUERY FORM:	Only query form
RESPONSE:	20 consecutive measurement values, starting with the value at memory location <num>.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:DATA:DATE?

DESCRIPTION:	This retrieves the storage date of a measurement value.
SYNTAX:	**DATalogger:DATA:DATE? <bl>, <num>**
PARAMETERS:	bl: Block number 0 to 31 num: Number of the measurement value in the block (num >=1)
QUERY FORM:	Only query form
RESPONSE:	The storage date of the selected resistance value (dd, mm, yyyy)
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:DATA:TIME?

DESCRIPTION:	This retrieves the storage time of a measurement value.
SYNTAX:	**DATalogger:DATA:TIME? <bl>, <num>**
PARAMETERS:	bl: Block number 0 to 31 num: Number of the measurement value in the block (num >=1)
QUERY FORM:	Only query form
RESPONSE:	The storage time of the selected resistance value. (hh, mm, ss, xx) xx -> 1/100 seconds
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:DATA:ALL?

DESCRIPTION:	This retrieves a stored measurement value together with the corrseponding date and time.
SYNTAX:	**DATalogger:DATA:ALL? <bl>, <num>**
PARAMETERS:	bl: Block number 0 to 31 num: Number of the measurement value in the block (num >=1)
QUERY FORM:	Only query form
RESPONSE:	The stored measurement value together with the corrseponding date and time. Measurement value, date, time. Meas. value: Resistance value with unit Date: dd, mm, yyyy Time: hh, mm, ss, xx (xx -> 1/100 seconds)
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DV? (short form)

DESCRIPTION:	This retrieves 7 stored measurement values together with the corrseponding dates and times.
SYNTAX:	**DV? <bl>, <num>**
PARAMETERS:	bl: Block number 0 to 31 num: Number of the measurement value in the block (num >=1)
QUERY FORM:	Only query form
RESPONSE:	7 consecutive measurement values together with the corrseponding dates and times of storage. The first value refers to the memory location. Measurement value, date, time. Meas. value: Resistance value with unit Date: dd, mm, yyyy Time: hh, mm, ss, xx (xx -> 1/100 seconds)
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

DATalogger:SIZE

DESCRIPTION:	This specifies the size of a datalogger block.
SYNTAX:	**DATalogger:SIZE <bl>, <size>**
PARAMETERS:	bl: Block number 0 to 31 size: Size of the datalogger block
QUERY FORM:	**DATalogger:SIZE? <bl>**
RESPONSE:	The size of the datalogger block with the number <bl>.
RESTRICTIONS:	This command is not permissible if a measurement is in progress or the device is in the calibration mode.

5.3.15 IEEE488.2 commands

*CLS

DESCRIPTION:	The device is set to the Operation-Complete-Idle state. The device is set to the Operation-Query-Complete-Idle state. The error buffer is deleted. The Operation-Event-Status-Register is reset. The Questionable-Event-Status-Register is reset. The Status Byte is reset.
SYNTAX:	***CLS**
PARAMETERS:	None
QUERY FORM:	None
RESPONSE:	—
RESTRICTIONS:	None

*ESE

DESCRIPTION:	The Standard-Event-Status-Enable-Register is set.
SYNTAX:	***ESE <parameter>**
PARAMETERS:	A value between 0 and 255. The decimal value corresponds to the bit combination of the 8-bit register.
QUERY FORM:	**ESE?**
RESPONSE:	The current setting mask of the Standard-Event-Enable-Register is returned.
RESTRICTIONS:	None

**ESR

DESCRIPTION:	The Standard-Event-Status-Register is read out and then reset.
SYNTAX:	***ESR**
PARAMETERS:	None
QUERY FORM:	Only query form
RESPONSE:	A decimal value between 0 and 255 is returned, in accordance with the contents of the register.
RESTRICTIONS:	None

*IDN?

DESCRIPTION:	This requests the ID of the device. - Company name - Device name - Serial number - Device version (SW version) - Calibration status
SYNTAX:	***IDN?**
PARAMETERS:	None
QUERY FORM:	Only query form
RESPONSE:	BURSTER, RESISTOMAT 2329, SNsssssss, Vxxxx, Cyyyy
RESTRICTIONS:	None

*OPC

DESCRIPTION:	The device is set to the Operation-Complete-Active state (OCAS). In the OCAS, the Operation-Complete bit in the Standard-Event-Register is set when an operation is completed.
SYNTAX:	***OPC**
PARAMETERS:	None
QUERY FORM:	The query form of the command has a different function. For this reason, the query form is described separately.
RESPONSE:	—
RESTRICTIONS:	None

*OPC?

DESCRIPTION:	The device is set to the Operation-Complete-Active state (OCAS). In the OCAS, the device writes a 1 to the output buffer following the execution of a command.
SYNTAX:	***OPC?**
PARAMETERS:	None
QUERY FORM:	Only query form. The same command without a query form has a different function and is described separately.
RESPONSE:	1, following execution of the command.
RESTRICTIONS:	None

*RST

DESCRIPTION:	The device is set to a defined initial state. The interface settings remain unchanged, and the device stays in the remote mode.
SYNTAX:	***RST**
PARAMETERS:	None
QUERY FORM:	None
RESPONSE:	—
RESTRICTIONS:	None

*SRE

DESCRIPTION:	The Service-Request-Enable-Register is set.
SYNTAX:	***SRE <parameter>**
PARAMETERS:	A decimal value between 0 and 255, corresponding to the bit combination of the 8-bit register.
QUERY FORM:	*SRE?
RESPONSE:	The present setting mask of the Service-Request-Enable-Register.
RESTRICTIONS:	None

*STB?

DESCRIPTION:	The Status Byte is read out (a 488.2 register mit 8 summary bits)
SYNTAX:	***STB?**
PARAMETERS:	None
QUERY FORM:	Only query form
RESPONSE:	A decimal value between 0 and 255, corresponding to the present contents of the 8-bit register.
RESTRICTIONS:	None

*TST?

DESCRIPTION:	Self-test query command. This command is recognized by the device, but has no additional function.
SYNTAX:	***TST?**
PARAMETERS:	None
QUERY FORM:	None
RESPONSE:	A 1 is returned.
RESTRICTIONS:	None

*WAI

DESCRIPTION:	This command sets a device so that all other commands are processed sequentially. This command does not have a function in the case of the RESISTOMAT® 2329, as commands are always processed sequentially by this device. Thus, the command is simply recognized by the RESISTOMAT® 2329.
SYNTAX:	***WAI**
PARAMETERS:	None
QUERY FORM:	None
RESPONSE:	—
RESTRICTIONS:	None

*SAV

DESCRIPTION:	This stores a device setting. Up to 32 settings can be stored.
SYNTAX:	***SAV <parameter>**
PARAMETERS:	A number between 0 and 31.
QUERY FORM:	None
RESPONSE:	—
RESTRICTIONS:	None

*RCL

DESCRIPTION:	A stored device setting is loaded. 33 different settings can be loaded (0-32). 32 is the default setting.
SYNTAX:	***RCL <parameter>**
PARAMETERS:	A number between 0 and 32. 32 is the default setting.
QUERY FORM:	None
RESPONSE:	—
RESTRICTIONS:	None

5.4. Status Register

5.4.1 Standard Event Status Register

Bits used		Meaning
Bit 0	Operation Complete	This bit is set in response to the *OPC command. It indicates that the previous command has been executed.
Bit 2	Query Error	This bit indicates that either 1. Data were requested although none are present, or 2. Data in the output buffer were lost.
Bit 3	Device Dependent Error	If an internal device error has occurred.
Bit 4	Execution Error	An error has occurred during execution of an SCPI command.
Bit 5	Command Error	An SCPI command was not recognized by the interpreter.

5.4.2 Questionable Status Register

Bits used		Meaning
Bit 4	TEMPerature	Problem during temperature measurement
Bit 8	CALibration	Error during calibration
Bit 9	FRESistor	Error during resistance measurement

5.4.3 Operation Status Register

Bits used		Meaning
Bit 0	CALibration	The device is in the calibration mode
Bit 2	RANGing	The device is changing ranges
Bit 4	MEASuring	A measurement is in progress
Bit 8	VALue available	A measured value is available

5.5. Sample programs

The two sample programs for the RS232 interface (standard device) and the IEEE488 interface can also be called up on the Internet, at

www.burster.de

5.5.1 Sample program for the RS232 interface

```
'*     File Name:        2329_rs.bas                        Version: 1.0
'*
'*     Developed by:     C.Speck          on 03.12.1996
'*     Changed by:       M.Westermann     on 26.03.1997
'*
'*     Language:         QBASIC 4.5 Operating system:                MS-DOS 6.22
'*
'*     Description:      Sample program for 2329-RS232
'*
'*     Remarks:
'*
'*     Copyright by burster präzisionsmesstechnik, Gernsbach 07224-6450
'*************************************************************************************************************************
'Declaration of the functions used
DECLARE FUNCTION CmdSenden (cmd$)                    Send command
DECLARE SUB CmdEmpfangen (antwort$)                 'Receive response from device
DECLARE FUNCTION AbfrageSOC ()        'Request Status Operation Condition Register
DIM   antwort$(100)
DIM   befehl$(100)

OPEN    "COM1:9600,N,8,1" FOR RANDOM AS #3 'INITIALIZE RS232
CLS       'CLEAR SCREEN
PRINT    "DEMOPROGRAMM"
PRINT    burster RESISTOMAT® Typ 2329"
PRINT    "Control via the RS232 interface, COM1 9600 baud"
PRINT    "Transfer protocol: ANSI X3.28 A3"
PRINT
PRINT    "The measurement is started. Press the space bar to cancel it."
PRINT

befehl$ = "abort"          'Stop the device if a measurement is in progress
IF (CmdSenden(id2329%, befehl$) = 0) THEN
        SYSTEM
END IF

i = 0                     'Reset the counter
DO WHILE (INKEY$ = "") 'Request measurement values until the space bar is pressed
      befehl$ = "in"            'Start a measurement
      IF  (CmdSenden(befehl$) = 0) THEN
          SYSTEM
      END IF
'In the next loop, the device waits until a bit in the Operation-Status-Register
'is set to indicate that a meaasurement variable is available
done% = 0
```

```
DO WHILE (done% <> 1)
      done% = AbfrageSOC        'Scan the Status Operation Condition Register
      IF (done% = -1) THEN      'Abort in the event of an error
          SYSTEM
      END IF
      LOOP

      befehl$ = "fe?"                                 'Fetch a measurement value
      IF (CmdSenden(befehl$) = 0) THEN
          SYSTEM
      END IF

      CALL CmdEmpfangen(antwort$                      'Fetch a measurement value
      LOCATE 15, 3
      PRINT i, "Resistance value:", antwort$          'Display the measurement value
      i = i + 1
   LOOP
END


FUNCTION AbfrageSOC
'********************************************************************************************************************
'Scan the Status Operation Condition Register
'********************************************************************************************************************
      DIM befehl$(100)
      DIM stri$(100)
      REM   Special characters are defined here
      STX$ = CHR$(2)
      ETX$ = CHR$(3)
      EOT$ = CHR$(4)
      ENQ$ = CHR$(5)
      ACK$ = CHR$(6)
      NAK$ = CHR$(21)
      LF$ = CHR$(10)

      befehl$ = "s:o:c?"        'Scan the Status Operation Condition Register
      IF (CmdSenden(befehl$) = 0) THEN
          SYSTEM
      END IF
      CALL CmdEmpfangen(antwort$) 'Scan the Status Operation Condition Register
      stat = VAL(antwort$        'Convert to integer form
      stat = stat AND 256        'End of measurement, clear bit
      IF stat <> 256 THEN        'If not end of measurement
          AbfrageSOC = 0         'Continue waiting
      ELSE
          AbfrageSOC = 1         'Measurement value is present
      END IF
END FUNCTION


SUB CmdEmpfangen (antwort$)
'********************************************************************************************************************
'Receive response from 2329
'********************************************************************************************************************
      DIM stri$(100)
      DIM ant$(100)
      REM   Special characters are defined here
      STX$ = CHR$(2)
      ETX$ = CHR$(3)
```

```
EOT$ = CHR$(4)
ACK$ = CHR$(6)
NAK$ = CHR$(21)
LF$ = CHR$(10)

PRINT #3, EOT$                    'Switch device to master mode
StartEmpfang:
     ant$ = " "                   'Delete response string
     stri$ = " "                  'Delete measurement-value string
     ant$ = INPUT$(1, #3)
     WHILE (ant$ <> ETX$) AND (ant$ <> EOT$) 'While ETX or EOT is not received
     IF ant$ >= CHR$(32) THEN  'If no special characters are present
        stri$ = stri$ + ant$ 'Form Status String
     END IF
     ant$ = INPUT$(1, #3             'Read in character from RS232
     WEND
     IF (ant$ = EOT$) THEN                    'If EOT is received
          EXIT SUB            'End Sub
     ELSE
          antwort$ = stri$            'Save response
          PRINT #3, ACK$            'Acknowledge
          GOTO StartEmpfang        'Read in again until EOT is received
     END IF
END SUB

FUNCTION CmdSenden (cmd$)
'***************************************************************************************************************************
'Send command to 2329
'***************************************************************************************************************************
     DIM ant$(100)
     DIM msg$(100)
     REM      Special characters are defined here
     STX$ =   CHR$(2)
     ETX$ =   CHR$(3)
     EOT$ =   CHR$(4)
     ACK$ =   CHR$(6)
     NAK$ =   CHR$(21)
     LF$ =    CHR$(10)

     msg$ = STX$ + cmd$ + LF$ + ETX$   'Formulate command
     PRINT #3, msg$            'Send command
     'Wait for acknowledgement
     ant$ = " "                   'Delete response string
     ant$ = INPUT$(1, #3)        'Read in response
     IF (ant$ <> ACK$) THEN                    'If not ACK
          PRINT "Gerät antwortet mit NAK          "    'Display error message
          CmdSenden = 0      'Error during transmission
     ELSE
          CmdSenden = 1      'Transmission OK
     END IF                   'End of If statement
END FUNCTION
```

5.5.2 Sample program for the IEEE488 interface

```
'***********************************************************************************************************
'*   File Name:          2329_iec.bas    Version: 1.0
'*
'*   Developed by:       M.Westermann          on 26.03.1997
'*   Changed by:                               on dd.mm.yyyy
'*
'*   Language:           QBASIC 4.5 Operating system:              MS-DOS 6.22
'*
'*   Description: Sample program for the 2329-IEEE488
'*
'*   Note: To load the IEEE488 bus driver library, call up the
'*         QB45 basic in a Batch file as follows:
'*         "qb 2329_iec.bas /L c:\AT-GPIB\QBASIC\QBIB.QLB"
'*         The creation of the QBIB.QLB is described in the Readme file
'          accompanying the IEEE card.
'*         The AT-GPIB/TNT made by National Instruments is used
'*         in this example.
'*
'*   Copyright by burster präzisionsmesstechnik, Gernsbach 07224-6450
'***********************************************************************************************************

    'Declaration of the functions used
    DECLARE FUNCTION CmdSenden (id2329%, CMD$)         'Send command
    DECLARE FUNCTION CmdEmpfangen (id2329%, antwort$)
    DECLARE FUNCTION AbfrageSRQ (id2329%) "Request Status Operation Condition Register
    DECLARE FUNCTION LeseOperEventReg (id2329%)
    DECLARE FUNCTION LeseQuestReg (id2329%)
    DECLARE FUNCTION LeseQuestFresReg (id2329%)
    DECLARE SUB gpiberr (msg$)

    'Include file for the IEEE card
    '$INCLUDE: 'd:\at-gpib\qbasic\qbdecl.bas'

    'Definition of the masks for register scanning
    CONST EOC = &H100            'Bit 8 of the Operation Status Register
    CONST FRESError = &H200      'Bit 9 of the Questionable Status Register
    CONST TEMPError = &H10       'Bit 4 of the Questionable Status Register
    CONST SRQOperReg = &H80      'Bit 7 of the SRQ Register
    CONST SRQQuestReg = &H8      'Bit 3 of the SRQ Register

    CLS                          'Clear screen
    PRINT "DEMOPROGRAMM                "
    PRINT "burster RESISTOMAT® Model 2329        "
    PRINT "Control via IEC bus interface"
    PRINT
    INPUT "Enter the IEEE488 address of the RESISTOMAT® Model 2329:", adr
    PRINT
    PRINT "Measurement started. Press space bar to cancel"
    PRINT
```

```
'The next command is a 488.2 command. It receives the
'device address and the timeout as parameters.
'The device handle (id2329) returned.
CALL IBDEV (0, adr, 0, T10s, 1, 0, id2329%)
IF (id2329% < 0) THEN          'In the event of an error, invoke the error routine
        CALL gpiberr ("ibdev Error)
        SYSTEM
END IF


'The following commands are used to set the masks for the required
'SRQ function for the different registers
'Enable BIT8 = EOC as a mask in the Status-Operation-Enable-Register
befehl$ = "stat:oper:enab " + STR$(EOC)
IF (CmdSenden(id2329%, befehl$) = 0) THEN
        SYSTEM
END IF


'Enable temperature and resistance errors
'In the Status-Questionable-Enable-Register, enable BIT4 (= error) for
'temperature measurement and BIT9 (= error) for resistance measurement
befehl$ = "stat:ques:enab " + STR$(TEMPError OR FRESError)
IF (CmdSenden(id2329%, befehl$) = 0) THEN
        SYSTEM
END IF


'In the Service-Request-Enable-Register, enable BIT3 (= Questionable-Register
'input) and BIT7 (= Operation-Register input) for an SRQ
befehl$ = "*sre " + STR$(SRQOperReg OR SRQQuestReg)
IF (CmdSenden(id2329%, befehl$) = 0) THEN
        SYSTEM
END IF


befehl$ = "abort"              'Stop the device if a measurement is in progress
IF (CmdSenden(id2329%, befehl$) = 0) THEN
        SYSTEM
END IF


befehl$ = "init:cont 0"        'Switch the device to single measurement
IF (CmdSenden(id2329%, befehl$) = 0) THEN
        SYSTEM
END IF


i = 0            'Reset the counter
DO WHILE (INKEY$ = " ") 'Request the measurement values until the space bar is pressed
        befehl$ = "in"          'Start a measurement
IF (CmdSenden(id2329%, befehl$) = 0) THEN    'Send command
        SYSTEM
END IF
'In the next loop, the device waits until an SRQ is present
'After that, the measurement value is fetched
done% = 0
DO WHILE (done% <> 1)
    done% = AbfrageSRQ(id2329%)      'Scan the SRQ register
    IF (done% = -1) THEN'im          'Abort in the event of an error
        SYSTEM
    END IF
```

```
LOOP

    befehl$ = "fe?"                        'Fetch measurement value
    IF (CmdSenden(id2329%, befehl$) = 0) THEN    'Send command

    antwort$ = SPACE$(12)              'Pre-assign buffer
    IF (CmdEmpfangen(id2329%, antwort$) = 1) THEN 'Fetch measurement value
        REM LOCATE 15, 3
        PRINT i; " Widerstandswert: "; antwort$  'Display measurement value
        i = i + 1
    ELSE
        SYSTEM
    END IF
    LOOP
END


FUNCTION AbfrageSRQ (id2329%)
'*******************************************************************************************************************************
'This function waits for an SRQ on the IEC bus and then invokes
'the service function for the RESISTOMAT®
'*******************************************************************************************************************************
    DIM befehl$(100)
    DIM stri$(100)

    MASK% = &H4800                'set RQS+TIMO as ibwait mask
    CALL IBWAIT(id2329%, MASK)
    IF (IBSTA% AND EERR) THEN
        CALL gpiberr("ibwait Error")
        EXIT FUNCTION
    END IF
    CALL IBRSP(id2329%, SPR%)          'Spoll request byte
    IF (IBSTA% AND EERR) THEN          'Invoke error routine in the event of an error
        AbfrageSRQ = -1          'Note error
        CALL gpiberr("ibwait Error")
        EXIT FUNCTION
    END IF

    SELECT CASE SPR%            'Branch after Spoll Byte
        CASE 192
            AbfrageSRQ = 1                'Everything OK
            'Scan and delete the Operation Event Register
            status = LeseOperEventReg(id2329%)
        CASE 72, 200            'An error has occurred
            AbfrageSRQ = -1            'Note the error
            'The following registers must be read out and deleted
            status = LeseOperEventReg(id2329%)
            IF (status > 0) THEN
                PRINT "Device error: Operation Event Register = "; status
            END IF
            status = LeseQuestReg(id2329%)
            IF (status > 0) THEN
                PRINT "Device error: Questionable Register = "; status
            END IF

            status = LeseQuestFresReg(id2329%)
            IF (status > 0) THEN
                PRINT "Device error: Questionable FRes Register = "; status
            END IF
```

```
    CASE ELSE
                            AbfrageSRQ = 0              'Continue waiting for SRQ
        END SELECT

END FUNCTION


FUNCTION CmdEmpfangen (id2329%, antwort$)
'*******************************************************************************************************
'Receive response from 2329
'*******************************************************************************************************

    DIM help$(100)

    CALL IBRD(id2329%, antwort$)                 'Fetch string from IEC-BUS
    IF (IBSTA% AND EERR) THEN
        CALL gpiberr("ibrd Error")
        antwort$ = " "
        CmdEmpfangen = 0                         'An error has occurred
    ELSE
        L = LEN(antwort$)
        help$ = MID$(antwort$, 1, L - 1)         'Discard LF character
        antwort$ = help$
        CmdEmpfangen = 1                         'Everything OK
    END IF
END FUNCTION


FUNCTION CmdSenden (id2329%, CMD$)
'*******************************************************************************************************
'Send command to 2329
'*******************************************************************************************************


    DIM msg$(100)

    REM LF$ = CHR$(10)

    msg$ = CMD$ + CHR$(10)                       'Formulate command

    CALL IBWRT(id2329%, msg$)                    'Send command via IEC bus
    IF (IBSTA% AND EERR) THEN
        CALL gpiberr("ibwrt Error")
        CmdSenden = 0                            'Error during transmission
    ELSE
        CmdSenden = 1                            'Transmission OK
    END IF
END FUNCTION


REM DEFDBL A-Z
SUB gpiberr (msg$) STATIC
'This function is taken from the Basic example accompanying the National Instruments card
'================================================================================
            Subroutine GPIBERR
'This subroutine will notify you that a NI-488 function failed by printing
'an error message.  The status variable IBSTA% will also be printed
'in hexadecimal along with the mnemonic meaning of the bit position.
'The status variable IBERR% will be printed in decimal along with the
'mnemonic meaning of the decimal value.  The status variable IBCNT% will
'be printed in decimal.
'The NI-488 function IBONL is called to disable the hardware and software.
'
'The STOP command will terminate this program.
'================================================================================
```

```
'
    PRINT msg$
    PRINT "ibsta = &H"; HEX$(IBSTA%); " <";
    IF IBSTA% AND EERR THEN PRINT " ERR";
    IF IBSTA% AND TIMO THEN PRINT " TIMO";
    IF IBSTA% AND EEND THEN PRINT " END";
    IF IBSTA% AND SRQI THEN PRINT " SRQI";
    IF IBSTA% AND RQS THEN PRINT " RQS";
    IF IBSTA% AND SPOLL THEN PRINT " SPOLL";
    IF IBSTA% AND EEVENT THEN PRINT " EVENT";
    IF IBSTA% AND CMPL THEN PRINT " CMPL";
    IF IBSTA% AND LOK THEN PRINT " LOK";
    IF IBSTA% AND RREM THEN PRINT " REM";
    IF IBSTA% AND CIC THEN PRINT " CIC";
    IF IBSTA% AND AATN THEN PRINT " ATN";
    IF IBSTA% AND TACS THEN PRINT " TACS";
    IF IBSTA% AND LACS THEN PRINT " LACS";
    IF IBSTA% AND DTAS THEN PRINT " DTAS";
    IF IBSTA% AND DCAS THEN PRINT " DCAS";
    PRINT " >"

    PRINT "iberr = "; IBERR%;
    IF IBERR% = EDVR THEN PRINT " EDVR <DOS Error>"
    IF IBERR% = ECIC THEN PRINT " ECIC <Not CIC>"
    IF IBERR% = ENOL THEN PRINT " ENOL <No Listener>"
    IF IBERR% = EADR THEN PRINT " EADR <Address error>"
    IF IBERR% = EARG THEN PRINT " EARG <Invalid argument>"
    IF IBERR% = ESAC THEN PRINT " ESAC <Not Sys Ctrlr>"
    IF IBERR% = EABO THEN PRINT " EABO <Op. aborted>"
    IF IBERR% = ENEB THEN PRINT " ENEB <No GPIB board>"
    IF IBERR% = EOIP THEN PRINT " EOIP <Async I/O in prg>"
    IF IBERR% = ECAP THEN PRINT " ECAP <No capability>"
    IF IBERR% = EFSO THEN PRINT " EFSO <File sys. error>"
    IF IBERR% = EBUS THEN PRINT " EBUS <Command error>"
    IF IBERR% = ESTB THEN PRINT " ESTB <Status byte lost>"
    IF IBERR% = ESRQ THEN PRINT " ESRQ <SRQ stuck on>"
    IF IBERR% = ETAB THEN PRINT " ETAB <Table Overflow>"

    PRINT "ibcnt = "; IBCNT%

END SUB

FUNCTION LeseOperEventReg (id2329%)
'*********************************************************************************************************************
'Read out Operation Event Register
'*********************************************************************************************************************
        DIM befehl$(50)

        befehl$ = "stat:oper?"                          'Scan register
        IF (CmdSenden(id2329%, befehl$) = 0) THEN
                SYSTEM
        END IF

        antwort$ = SPACE$(5)                    'Pre-assign buffer
        IF (CmdEmpfangen(id2329%, antwort$) = 0) THEN   'Fetch register contents
        SYSTEM
        END IF
        LeseOperEventReg = VAL(antwort$)        'Return value
END FUNCTION
```

```
antwort$ = SPACE$(5                    'Pre-assign buffer
    IF (CmdEmpfangen(id2329%, antwort$) = 0) THEN        'Fetch register contents
        SYSTEM
    END IF
    LeseOperEventReg = VAL(antwort$)    'Return value
END FUNCTION


FUNCTION LeseQuestFresReg (id2329%)
'***********************************************************************************************************
'Read out Questionable Fres Register
'***********************************************************************************************************
    DIM befehl$(50)

  befehl$ = "stat:ques:fres?"                           'Scan register
    IF (CmdSenden(id2329%, befehl$) = 0) THEN
        SYSTEM
    END IF
    antwort$ = SPACE$(4)            'Pre-assign buffer
  IF (CmdEmpfangen(id2329%, antwort$) = 0) THEN         'Fetch register contents
        SYSTEM
  END IF

    LeseQuestFresReg = VAL(antwort$)  'Return value
END FUNCTION

FUNCTION LeseQuestReg (id2329%)
'***********************************************************************************************************
'Read out Questionable Fres Register
'***********************************************************************************************************
    DIM befehl$(50)

    befehl$ = "stat:ques?"                              'Scan register
    IF (CmdSenden(id2329%, befehl$) = 0) THEN
        SYSTEM
    END IF

    antwort$ = SPACE$(4)            'Pre-assign buffer
    IF (CmdEmpfangen(id2329%, antwort$) = 0) THEN   'Fetch register contents
        SYSTEM
    END IF

    LeseQuestReg = VAL(antwort$)            'Return value
END FUNCTION
```

5.6. Error status display

5.6.1 Error status display in the error status field

In the event of an error, a corresponding error status appears in status line 2 (page „4.3.1 Measurement stopped"
auf Seite 26) of the display field S. 2.2.

Hexadecimal display

1 -	MI-Over:	Measurement current too high (in the 20-mV mode) or test-object resistance / line resistance too high.	
2 -	MU-Over:	Measuring amplifier for the potential taps is (+U, -U) overdriven.	
4 -	I-Over: I-cable breakage	Test-object resistance / line resistance too high. e.g. I-cable breakage, or resistance too high in the 20-mV mode.	
8 -	Overdrive:	Drive limits of the internal A/D converter have been exceeded.	18_{hex} The 15 V supply voltage is missing
10 -	Underdrive:	Drive limits of the internal A/D converter have been fallen short of.	
20 -	I not constant:	Measurement current has not settled; this can occur in the case of inductive test objects. The test object might not be measurable, due to an excessively high inductance or time constant $T = \frac{L}{R}$.	
40 -	U-cable breakage:	+ U, -U-line resistance too high, or no contact with the test object.	
80 -	Temperatur compensation:	Error in temperature compensation, check external sensor.	

Different combinations can appear in the hexadecimal display. For example:

22 -	(20+2)	Measurement current has not settled, as the inductance of the test object might be too high, and the measurement amplifier of the potential taps (+U,-U) is overdriven.
A -	(2+8)	The measurement amplifier for the potential taps is overdriven and the drive limits of the internal A/D converter have been exceeded.
18 -	(10+8)	In the case of overdrive or underdrive, the voltage supply in the measurement section is not OK.

5.6.2 Error status display in the temperature display field

If 80_{hex} appears in the error status field S. 2.2 (pageSeite 26), the temperature display field S. 1.3 (pageSeite 26) also indicates a hexadecimal number which can be used to evaluate the error.

The following errors can be displayed:

Hexadecimal display

1 -	Cable breakage: or no Pt100 connected	The measurement line for the Pt100 sensor is interrupted or has an excessively high impedance, or no Pt100 is connected.
2 -		
4 -	U-cable breakage:	The potential taps (+U, -U) are interrupted, or the line resistance is too high.
8 -	Cable breakage: or no Pt100 connected	The measurement line for the Pt100 sensor is interrupted or has an excessively high impedance, or no Pt100 is connected.
10 -	Invalid resistance:	The Pt100 might be reverse-connected.
20 -	Invalid temperature:	The temperature lies outside the defined range or cannot be calculated.
40 -	15 V power supply:	The ± 15 V power supply inside the device is not OK.

As in the error status field, different combinations can also appear in the temperature display field.

5.6.3 Calibration Error

> **RESISTOMAT® Model 2329**
>
> **CALIBRATION ERROR**

The announcement "Calibration Error" appears on the display when the calibration datas are lost (e.g. when the internal battery is defect).

You can not work with the device any longer because all functions are locked.

In this case please send the Ohmmeter to our service dept.

6. Maintenance and Customer Service

6.1 Maintenance

The RESISTOMAT® Model 2329 does not require any maintenance by the user.
Repairs which might be required must only be performed by the manufacturer.

6.2 Customer Service

Enquiries:

Please indicate the serial number of your device when sending technical enquiries to the manufacturer. This will make it possible to identify the hardware and software versions and allow rapid remedy. The serial number is indicated on the type plate.

Shipping notes:

When sending the RESISTOMAT® to the manufacturer for repair, please obeserve the following packaging and shipping guidelines:

Prepare a note briefly describing the fault and attach it to the housing of the device.

Adding your name and department as well as a phone and fax number to this information will help us process your complaint more quickly.

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6.3 Manufacturer's guarantee

burster garantees the reliable operation of the device for a period of 12 months following its delivery.

Repairs required within this period will be performed free-of-charge.

This guarantee does not cover damage arising from improper handling of the device.

Furthermore, the manufacturer cannot be held liable for any type of consequential damage.

Technical data are subject to change without notice.

6.4 Cleaning the device

To clean the front panel and housing of the device, only use water-soluble detergent, not benzene.

7. Technical Data

Only values with tolerances or limits can be taken as guaranteed. Values without tolerances serve purely as orientation and are not binding.

This device is easy to maintain and has a robust metal housing. The individual modules can be accessed and serviced with the greatest of ease.

All the control elements are clearly arranged clearly on the front panel. The connection socket for the test object, as well as the inputs and outputs for the interface, comparator, Pt100 sensor for temperature compensation and the control unit are located on the rear of the device.

Measuring range	Resolution	Measuring current
200.00 mΩ	10 $\mu\Omega$	100 mA
2.0000 Ω	100 $\mu\Omega$	10 mA
20.000 Ω	1 mΩ	10 mA
200.00 Ω	10 mΩ	1 mA
2.0000 kΩ	100 mΩ	1 mA
20.000 kΩ	1 Ω	100 μA
200.00 kΩ	10 Ω	10 μA

Measurement error (with temperature compensation inactive):   up to 0.03 % ± 2 digits
This error is valid for a load voltage up to 0.5 V.
At higher load voltages the error increase 0.02 %/V.

Starting time: < 10 min. to attain the error limits

Max. voltage across the open terminals: $\leq$ 16 V

Measurement connection: 4-wire technique for current-voltage measurement (Kelvin), ungrounded circuit, potential binding on the test object or the RESISTOMAT®, as required.

Max. load voltage: $\geq$ 5 V

Measurement time: Up to 50 measurements and evaluations per second,depending on the resolution and the measurement mode in the case of purely ohmic test objects.

Measurement types: Continuous and single measurement

Range selection: Manual, automatic or via interface

Dry-circuit measurement: According to DIN IEC 512 Part 2
20 mV load voltage limit up to 4 Ω

Temperature compensation: 10 different, individually adjustable temperature coefficients; individually adjustable reference temperature display (e.g. 20 °C).

Temperature recording: Via an external Pt100 sensor or transmitter (e.g. pyrometer) with a voltage (0...10 V) or current output (0...20 mA) or (4.... 20 mA)

Comparator: 2 or 4 limiting values

Relay outputs: One switching contact each for evaluation results << , < , = , > , >>
Switching power   30 W
Voltage capacity   max. 48 V
Current capacity   max. 1 A
or via PLC outputs for current-consuming inputs

PLC outputs: U_{min} = 15 V U_{max} = 30 V $I_{max.}$ = 150 mA per output
(max. 600 mA for all outputs together)

Datalogger: The datalogger has a memory capacity of 20 000 measured values which can be subdivided into blocks

General data

Display:	128 x 64 pixel, transflective LCD graphic display with individually adjustable contrast and background illumination.

Display of measurement values: 3 1/2 or 4 1/2 digit as required, 15 mm high, Indication: absolute, Δ% or evaluation >>, >, =, <, <<

Power supply: 230 V $\pm$ 10 % or 115 V $\pm$ 10 % via a mains voltage selector

Mains frequency: 47 - 63 Hz

Power consumption: max. 25 VA

Ambient temperature: Operation +5 ... **23** ... 50 °C, Storage -10 ... 60 °C

Potential binding: Internally grounded measurement section, switchable to external grounding

Time, datalogger and device settings: These data are backed up by an internal battery

Parameter entry: Via keypad or interface

Weight: Approx. 5 kg

Housing dimensions(HxWxD): 151 x 237 x 285 [mm] with handles T = 325 mm

Device safety: According to EN 61010

Protection type: IP 40

Terminals

Rx input (test object): 5-pole Tuchel socket, series C 70 B T 3015000, with a bayonet catch

Pt100-Sensor: 6-pole LEMO socket EGG. 1B. 306

Analog I/0: 9-pole, subminiature D plug
Temperature transmitter input 0 ... 10 V, 0 ... 20 mA, 4 ... 20 mA
Analog output 0 ... 10 V, scalling error $\leq$ 2,5%,

Digital I/0: 37-pole, subminiature D socket
(PLC) External DC supply 20 V ... **24 V** ... 30 V
5 relay contacts (NO) and 5 optocouplers for selection
5 bits for binary selection of device settings + transfer
4 bits for the control input
3 bits for the control output
START/STOP for measurements, comparator
Datalogger, min./max., printer
START/STOP for measurements with a footswitch

Interface terminals:
RS232C-Interface: Full-duplex
9-pole Subminiatur D socket
Baud rate 300 - 38 400
Protocol ANSI X 3.28-1976 Subcategory 2.1, A3
Command language SCPI, Version 1995.0

IEEE488 interface (optional): 24-pole standardized plug connection, open collector output
SH1, AH1, T6, TEØ, L4, LEØ, SR1, RL1, PPØ, DC1, DTØ, CØ
Command language: SCPI, Version 1995.0

Printer: Connection to an RS232 interface

8. Appendix - Control Example
for device settings

Example for device setting:

Test object:	Coil approx. 1.5 Ω	(set Z)

Evaluation:	2 Limits lower Limit 1.4 Ω upper Limit 1.6 Ω	(set 2LI)

Temperatur compensation: Material of the coil wire with Pt100 is copper (set TC 3980 ppm)

Meas. mode: Continuous measurement

Meas. range: 2 Ω manual range selection

Memory: All the mentioned settings should be stored in the measure program 1

Device ON

: Identification menu appears for 5 sec., after this time the device goes to the main menu.
Now press following keys:

F4 : Parameter selection menu appears, cursor pos. MEAS:PARAMETER

F1 : Range select MAN/AUTO., with key (→ 6) set MAN
(see manual pageSeite 36)

(↓ 2) : Meas. range

(→ 6) : Press this key as much as "RANGE 2 OHM" appears.

(↓ 2) : Test object

(→ 6) : Test object   :   set Z

(↓2)	:	Meas. mode			
(→6)	:	Meas. mode	:	set CONTINUOUS	
(F4)	:	Parameter selection menu			
(↓2)	:	Choose temperature compensation (see manual pageSeite 45)			
(F1)	:	Temp. Comp. menu			
(→6)	:	TEMP. COMP.	:	ON	
(↓2)	:	Activation of temp.-meas.			
(→6)	:	MEASUREMENT	:	Pt100	
(F2)	:	Choose the temp.-cofficient			
(↓2)	:	Choose TC5 3980			
(F4) (F4)	:	Press 2x F4, return to parameter selection menu.			
(↓2)	:	Comparator setting menu (see manual page 42)			
(F1)	:	Comparator menu			
(→6)	:	COMPARATOR	:	ON	
(↓2)	:	Limits			
(→6)	:	Count of limiters	:	2	
(↓2)	:	Relay: With key (→6) you can choose, whether only the PLC outputs are active, or PLC outputs and relays.			

(▲ 9)	:	Switch to page 2 (S2) and set the limits
(F1)	:	Set the lower limit LLI
(END 1) (RGE ↑) (← 4) (F2)		
(↓ 2) (F1)	:	Set the upper limit ULI
(END 1) (RGE ↑) (→ 6) (F2)		
(F4)	:	Parameter selection menu
(▼ 3)	:	Choose page 2 (S2) in the parameter selection menu.
(↓ 2)	:	Store the device setting
(F1)	:	Device setting menu (see manual pageSeite 50)
(F1)	:	Input the device setting number
e.g. (END 1) (ENT) (F2)		
(F4)	:	Return to the main menu

Load the stored device setting from the main menu (page Seite 50)

(F4)	:	Parameter selection menu
(▼ 3)	:	Go to page 2 (S2)
(↓ 2)	:	Setup the device
(F1)	:	Device setting
(↓ 2)	:	Choose the load number (END 1) (ENT)
(F1)	:	Set the load number
(F3)	:	Now the stored device settings with the store number 1 will load in the main menu.