



# OPERATION MANUAL

## DIGIFORCE® 9307 EtherCAT Manual

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Manufacturer:

burster  
praezisionsmesstechnik gmbh & co kg  
Talstr. 1 - 5                                    P.O.Box 1432  
76593 Gernsbach                              76593 Gernsbach  
Germany    Germany

Valid from: **06.02.2020**  
Applies to: **DIGIFORCE® 9307 V0x01**

Tel.: +49-7224-645-0  
Fax.: +49-07224-645-88  
Email: [info@burster.com](mailto:info@burster.com)  
[www.burster.com](http://www.burster.com)

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## 1 Revision history

Changes from March 2017 to Revision A

| Chapter   | Changes                                       |
|---|---|
| Front page  | Date, device and firmware version             |
| 4 Parameters                                      | Device ID added for EtherCAT Firmware V201900 |
| 5.1 General information on EtherCAT data transfer | New section 'Device ID' added                 |
| 6 EtherCAT PDO – Process Data Objects             | New update rate for sensor live values        |
| 7 EtherCAT SDO – Service Data Objects             | Note for EtherCAT-Firmware V201900            |
| 7.1 Instrumentation configuration                 | Changed values for EtherCAT-Firmware V201900  |
| 7.2 Measurement results                           | Changed values for EtherCAT-Firmware V201900  |
| 8.2 Error codes                                   | New chapter added                             |

**Note:** To use the corresponding EtherCAT ESI file (available on burster website).

## 2 Introduction

### 2.1 General safety instructions



#### Warning concerning installation of the device and software

- Installation of the device and the interface must be carried out by qualified personnel only.  
Qualified personnel meets the following requirements:
  - You are familiar with the safety designs used in automation engineering, and understand how to deal with them in your capacity as configuration engineer.
  - You are an operator of automation systems and have been instructed in how to handle the system. You are familiar with the operation of the equipment described in this documentation.
  - You are a commissioning or service engineer and have successfully completed a training course qualifying you to repair automation systems. In addition you are authorized to commission, ground and label circuits and equipment in accordance with safety engineering standards.
- Always observe the current safety and accident prevention regulations when commissioning the equipment.
- Install automation engineering equipment and installations with sufficient protection against accidental actuation.



#### Warning concerning use of the device

- Take suitable precautions in both the hardware and software to prevent any undefined states of the automation installation in the event of an open circuit.
- In installations where major damage to property or even personal injury may be caused by a malfunction, take suitable precautions to establish a safe operating state in the event of a fault. This may be achieved using limit switches, mechanical interlocks etc. for example.
- Do not make unauthorized modifications to the device or to the EtherCAT interface.



#### Notice

- Install the power, signal and sensor cables so as to prevent electromagnetic interference from impairing operation of the equipment.
- Proper transportation, storage, installation and assembly plus careful operation and maintenance are essential for trouble-free and safe operation of the equipment.
- Have non-functional instruments inspected by the manufacturer.

## 2.2 Intended use

The DIGIFORCE® 9307 is an instrument for monitoring repetitive production processes. Its core function is to record and analyze signals from processes in which physical variables, such as force, pressure or torque, vary as a function of displacement, angle or time according to a defined curve. The resultant measurement curve is analyzed using graphical evaluation elements such as windows, envelopes and thresholds. The result of the analysis is indexified as "OK" or "NOT OK" (NOK) and can be retrieved from various interfaces.

The instrument is not a substitute for a safety device; for instance it cannot be used as an emergency stop device in a press for when the pressure exceeds a set limit.

### 3 Trademarks and Patents

EtherCat® is a registered trademark and patented technology of Beckhoff Automation GmbH, Germany

#### Patents:

The EtherCAT Technology is covered, including but not limited to the following patent applications and patents: EP1590927, EP1789857, DE102004044764, DE102007017835 with corresponding applications or registrations in various other countries.

### 3.1 Model 9307 device data

|               |                  |
|---------------|------------------|
| Bus connector | RJ45             |
| ESI file      | burster_9307.xml |

### 3.2 Electrical safety

|                             |   |
|-----------------------------|---|
| Reverse voltage protection  | Yes                                       |
| Air clearance/leakage paths | To DIN EN 61010-1                         |
| Electrical isolation        | Between fieldbus and internal electronics |
| Withstand voltage           | DC 500 V                                  |

### **3.3 Electromagnetic compatibility**

#### **3.3.1 Interference immunity**

Interference immunity to EN 61326-1:2006

Industrial locations

#### **3.3.2 Emitted interference**

Emitted interference to EN 61326-1:2006

Index A

EN 61000-3-2:2000

EN 61000-3-3:1995+A1:2001

### **3.4 Notes on CE labeling**

burster equipment carrying the CE mark meets the requirements of the EU directives and the harmonized European standards (EN) cited therein.

The EU declarations of conformity are available to the relevant authorities as specified in the directives. A copy of the declaration of conformity is included in the relevant equipment documentation.

## 4 Installation

Please note that you can download various documents such as installation guidelines and specifications about EtherCAT at [www.beckhoff.com](http://www.beckhoff.com)

### 4.1 Connection of fieldbus lines

burster devices with a EtherCAT option have two **RJ 45** connectors for the fieldbus connection.

### 4.2 Meaning of LED states

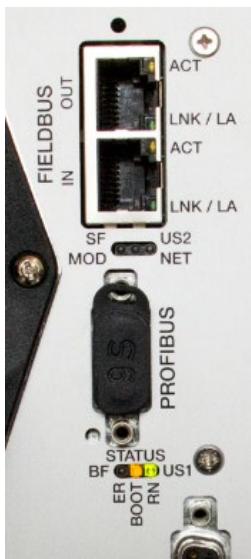
**Hardware up to December 2014**



| LED  | Status          | Description  |
|------|-----------------|--|
| LA   | OFF             | Port closed  |
|      | ON / Flickering | Port open  |
| RN   | OFF             | The device is in state INIT  |
|      | Blinking        | The device is in state PRE-OPERATIONAL   |
|      | Single flash    | The device is in state SAFE-OPERATIONAL  |
|      | ON              | The device is in state OPERATIONAL   |
| ER   | OFF             | No error   |
|      | Blinking        | Invalid configuration, general configuration error   |
|      | Single flash    | Local error  |
|      | Double flash    | Process data watchdog timeout / EtherCAT watchdog timeout  |
| BOOT | Blinking        | During boot process (internal communication between EtherCAT-fieldbus-processor and DIGIFORCE® main processing unit) |

The status of the LEDs is corresponding to EtherCAT specification (for detailed information please see <http://www.ethercat.de/default.htm> "EtherCAT Indicator and Labeling ETG.1300 S (R) V1.1.0").

Hardware from December 2014



| LED  | Status          | Description  |
|------|-----------------|--|
| LA   | OFF             | Port closed  |
|      | ON / Flickering | Port open  |
| RN   | OFF             | The device is in state INIT  |
|      | Blinking        | The device is in state PRE-OPERATIONAL   |
|      | Single flash    | The device is in state SAFE-OPERATIONAL  |
|      | ON              | The device is in state OPERATIONAL   |
| ER   | OFF             | No error   |
|      | Blinking        | Invalid configuration, general configuration error   |
|      | Single flash    | Local error  |
|      | Double flash    | Process data watchdog timeout / EtherCAT watchdog timeout  |
| BOOT | Blinking        | During boot process (internal communication between EtherCAT-fieldbus-processor and DIGIFORCE® main processing unit) |

All other LEDs are reserved for other fieldbus interfaces (e.g. PROFIBUS, PROFINET, EtherNet/IP).

## 4.3 Configuration menu in DIGIFORCE® 9307

### To access the menu

Start in measurement mode. After power on the measurement mode is always set. The display will look differently dependent on your settings or your last measurements.

You can go to "Main setup menu" in measurement mode by pressing the [F5] key twice.



This is how it works

1. In measurement mode, press the [F5] key twice.

| P 0 ProgName              | Menu 9   |
|---------------------------|----------|
| Main setup menu           |          |
| Basic setup menu          |          |
| Program number            | 0        |
| Program name              | ProgName |
| Channel settings          |          |
| Measurement mode          |          |
| Evaluation                |          |
| Realtime switchpoints     |          |
| Test operation simple     |          |
| Test operation complex    |          |
| Sensor test               |          |
| Setup user-defined values |          |
| Copy programs             |          |
| Enter                     |          |

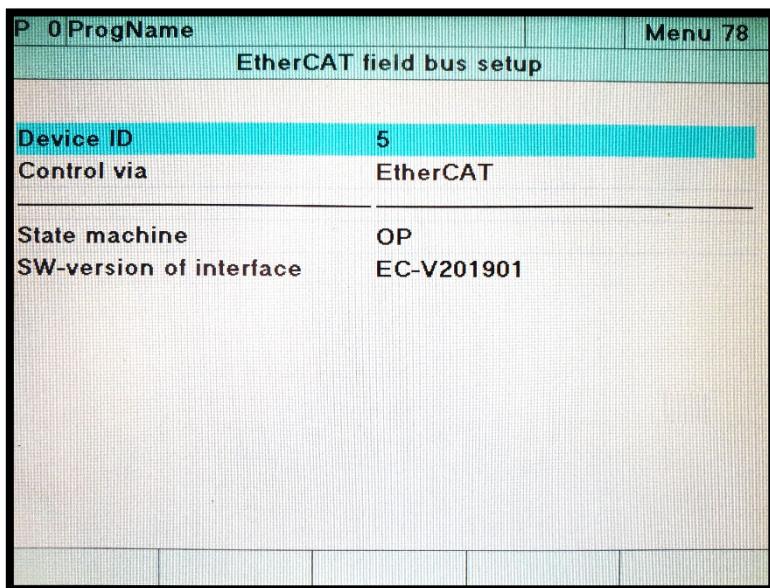
- 2.

3. Press [Enter] to open the "Basic setup menu".

| P 0 ProgName                             | Menu 19 |
|--|---------|
| Basic setup menu                         |         |
| Measurement menu function key definition |         |
| Assignment of the PLC outputs            |         |
| Access authorisation                     |         |
| Measurement menu display control         |         |
| Info menu                                |         |
| LCD setup                                |         |
| Date and time                            |         |
| Language                                 |         |
| Interface setup (RS232/USB/Ethernet)     |         |
| Acknowledgement function setup           |         |
| Order sheet setup                        |         |
| EtherCAT field bus setup                 |         |
| Enter                                    |         |

- 4.

5. Select "EtherCAT field bus setup" menu with ▼ or ▲ and press [Enter].



6.

## Parameters

|                                 |   |
|---------------------------------|---|
| <b>Device ID (from V201900)</b> | Device Identification Value (used for slave identification, 0 is not valid)   |
| <b>Control via</b>              | <b>EtherCAT:</b> DIGIFORCE® 9307 responds solely to control signals (inputs) on the EtherCAT interface<br><b>PLC:</b> DIGIFORCE® 9307 responds solely to control signals (inputs) on the PLC I/O interface.<br>When controlled via PLC I/O, data is still transferred in the cyclical EtherCAT Process Data Objects (PDO) |
| <b>State machine</b>            | Status of the EtherCAT fieldbus state machine<br>INIT            The device is in state INIT<br>PRE-OP        The device is in state PRE-OPERATIONAL<br>SAFE-OP      The device is in state SAFE-OPERATIONAL<br>OP             The device is in state OPERATIONAL   |
| <b>SW version of Interface</b>  | Version of the field bus card software  |

## 5 EtherCAT – General information

### 5.1 General information on EtherCAT data transfer

The DIGIFORCE 9307 with EtherCAT uses for the data transfer the EtherCAT technology CoE (CANopen over EtherCAT). There are two types of data – data which are transferred with each cycle (PDO – Process Data Objects) and data which are transferred on demand only (SDO – Service Data Objects). The SDO-Data are addressed via a combination of Index and Subindex which you will find in the tables below.

The device (Slave) is controlled using the data transferred from Master to Slave. This data always consists of four bytes for the DIGIFORCE® 9307 unit. The function of these four bytes is explained in chapter 5.1 Overview of the PDO packet content page 18.

The DIGIFORCE® 9307 sends cyclic 140 bytes to Master. This packet contains PLC status, evaluation information and 30 measurement values which are user selectable within the 9307 configuration and the live values of max. 3 active measurement channels.

The DIGIFORCE® 9307 supports both types of Explicit Device Identification: **SII Configured Station Alias** and **Device Identification Value (ID Value)**. The SII configured station alias can be set by a master or a configuration tool. This value is stored in the device and is loaded at power-on into the register 0x0012:0x0013. The Device Identification Value (**ID Value**) can be set directly in the device EtherCAT menu (please refer to *Configuration menu in DIGIFORCE® 9307*). This value is loaded into the register 0x0134 on the master request.

Strings should be transferred with String-Ende (null terminated string)!

You will find further information about EtherCAT at: [www.beckhoff.com](http://www.beckhoff.com).

## 5.2 Data conversion

### **5.2.1 Description of the data formats in this manual**

The terms PLC inputs and PLC outputs refer to the DIGIFORCE® 9307 unit. These terms are reversed when referred to the Master.

The function of the PLC-In / PLC-Out bits is identical to the parallel PLC I/O ports on the unit itself and can be found within the DIGIFORCE® 9307 operating manual.

The floating-point numbers ("float") mentioned are four bytes long (32 bits) and are based on the IEEE-754 standard.

Numbers that are not specifically labeled or are labeled with "d" or "dec" are decimal numbers. (Example: 1234, 1234dec, dec1234, 1234d)

Numbers that are labeled with "0x" or "hex" are hexadecimal numbers. (Example: 0x1234, hex1234, 1234hex, 1234h)

Numbers that are labeled with "b" or "bin" are binary numbers. (Example: b1100, bin1100, 1100b, 1100bin)

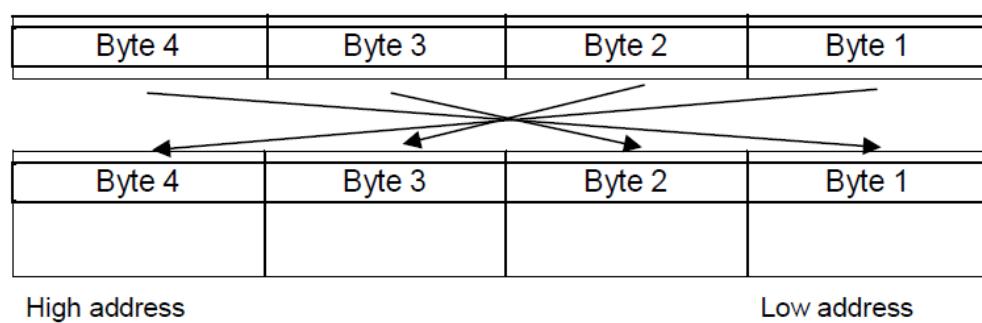
### 5.2.2 Handling problems that arise when reading floating-point numbers

This only concerns cases in which floating-point numbers need to be read from the DIGIFORCE 9307 unit.

Floating-point numbers (data type REAL), according to IEEE 754, are encoded as four bytes for transfer. This may create problems depending on the type of PLC used.

## Cause

In the DIGIFORCE® 9307-EtherCat, the sign byte is transferred first. Some PLCs expect this byte in the highest of the four addresses not in the lowest address. This inevitably leads to misinterpretation of the numeric value. In this case the order of the four bytes has to be changed by the PLC as shown in the figure.



**Diagram 1:** Exchange of the order of bytes caused by misinterpretation of the numeric value

## 6 EtherCAT PDO – Process Data Objects

### 6.1 Overview of the PDO packet content

#### Transfer from Master to Slave

| Content    | Length/Bytes | Bytes |
|------------|--------------|-------|
| PLC inputs | 4            | 4     |

#### Transfer from Slave to Master

| Content  | Length/Bytes | Bytes |
|--|--------------|-------|
| PLC output status                                    | 4            |       |
| Evaluation info                                      | 4            |       |
| 12 evaluation values (float) , selectable list M5-1* | 12x4         |       |
| 12 evaluation values (float) , selectable list M5-2* | 12x4         |       |
| 6 evaluation values (float), selectable list curve*  | 6x4          |       |
| 3 life values (X, Y1, Y2) *1                         | 3x4          |       |

Σ 140 bytes

\* The selectable list contains values which are defined within the DIGIFORCE® 9307 device. The following values are available:

- General curve data Y1
- General curve data Y2
- Evaluation results of mathematical functions
- Evaluation results of each evaluation element (e.g. window entry/exit window extended evaluation results like Min/Max window limits Xmin, Xmax, Ymin, Ymax threshold crossing point.)

\*1 The live values of the sensor channels are updated at a rate of 500 ... 1000 Hz. The values are only updated when the DIGIFORCE® 9307 is ready to record measurements or is actively taking a measurement (after a measurement and during evaluation the values are not updated for a period of typ. 30 msec).

**How to define the selectable list:** The parameterization of the selectable lists is done in the main setup menu "Setup user defined values" (Note that this setting is specific for each measurement program. For details refer to the DIGIFORCE® 9307 operation manual, section 5.13 User defined values.)

## 6.2 PDO – Process Data Objects – Transfer from Master to Slave

Four bytes of PLC-In data for the DIGIFORCE® 9307 are always transferred from the EtherCAT Master to the DIGIFORCE® 9307. These bits have the same function as the parallel PLC inputs to the DIGIFORCE® 9307 unit. (See detailed documentation of these signals within the DIGIFORCE® 9307 operation manual, section 5.3.9 Assigning PLC outputs). Also the signal timing is available within the DIGIFORCE® 9307 operation manual.

### 6.2.1 PLC inputs byte 1 (Master to Slave)

| PLC inputs Byte 1 (Master → Slave) |   |           |
|------------------------------------|---|-----------|
| Valid values:                      | <b>IN_PROG0</b><br>Measurement program number Bit 0 | Bit 0 LSB |
|                                    | <b>IN_PROG1</b><br>Measurement program number Bit 1 | Bit 1     |
| Set reserved bits to '0'           | <b>IN_PROG2</b><br>Measurement program number Bit 2 | Bit 2     |
|                                    | <b>IN_PROG3</b><br>Measurement program number Bit 3 | Bit 3     |
|                                    | <b>IN_PROG4</b><br>Measurement program number Bit4  | Bit 4     |
|                                    | <b>IN_RES1</b><br>reserved input 1                  | Bit 5     |
|                                    | -   | Bit 6     |
|                                    | -   | Bit 7 MSB |

### 6.2.2 PLC inputs byte 2 (Master to Slave)

| PLC inputs Byte 2 (Master → Slave) |   |           |
|------------------------------------|---|-----------|
| Valid values:                      | <b>IN_STROBE</b><br>Apply program number  | Bit 0 LSB |
|                                    | <b>IN_ACK_OK</b><br>IO Acknowledgement  | Bit 1     |
| Set reserved bits to '0'           | <b>IN_ACK_NOK</b><br>NIO Acknowledgement  | Bit 2     |
|                                    | <b>IN_TEST_OP</b><br>Setup mode (evaluation without counter)                        | Bit 3     |
|                                    | <b>IN_TEST_OPC</b><br>Setup mode (recording a set of curves)                        | Bit 4     |
|                                    | <b>IN_AUTO</b><br>Instrument is kept in measurement mode (AUTO mode)                | Bit 5     |
|                                    | <b>IN_RES2</b><br>reserved input 2  | Bit 6     |
|                                    | <b>IN_REF_MEAS</b><br>Reference travel for incremental sensors with distance coding | Bit 7 MSB |

### 6.2.3 PLC inputs byte 3 (Master to Slave)

| PLC inputs Byte 3 (Master → Slave) |  |           |
|------------------------------------|--|-----------|
| Valid values:                      | <b>IN_RESET</b><br>Reset all statistical data                    | Bit 0 LSB |
|                                    | <b>IN_PROG6*</b><br>Measurement program no. bit 6 (binary coded) | Bit 1     |
| Set reserved bits to '0'           | <b>IN_STEST</b><br>Sensor test                                   | Bit 2     |
|                                    | <b>IN_PROG5*</b><br>Measurement program no. bit 5 (binary coded) | Bit 3     |
|                                    | <b>IN_LTEST</b><br>Line test, all PLC-Outputs are set to high    | Bit 4     |
|                                    | <b>IN_TAREX</b><br>Tare the X-channel                            | Bit 5     |
|                                    | <b>IN_TAREY1</b><br>Tare Y-channel 1                             | Bit 6     |
|                                    | <b>IN_TAREY2</b><br>Tare Y-channel 2                             | Bit 7 MSB |

\* IN\_PROG[6..5] necessary with 9307 firmware for 128 measurement programs. If not used set this bits to "0".

#### 6.2.4 PLC inputs byte 4 (Master to Slave)

| PLC inputs Byte 4 (Master → Slave) |   |           |
|------------------------------------|---|-----------|
| Valid values:                      | <b>IN_START</b><br>Start / stop for measurement | Bit 0 LSB |
|                                    | -   | Bit 1     |
| Set reserved bits to '0'           | -   | Bit 2     |
|                                    | -   | Bit 3     |
|                                    | -   | Bit 4     |
|                                    | -   | Bit 5     |
|                                    | -   | Bit 6     |
|                                    | -   | Bit 7 MSB |

## 6.3 PLC outputs – Transfer from Slave to Master

The data refers to the PLC output of the DIGIFORCE® 9307. The data described here is the data transferred from the DIGIFORCE® 9307 to the EtherCAT Master.

The function of the PLC-In / PLC-Out bits is identical to the parallel PLC I/O ports on the unit itself and can be found within the DIGIFORCE® 9307 operation manual for the unit. Also the signal timing is available within the DIGIFORCE® 9307 operation manual PLC outputs byte 1

### 6.3.1 PLC outputs byte 1

| PLC outputs Byte 1 (Slave →Master) |  |           |
|------------------------------------|--|-----------|
| Valid values:                      | <b>OUT_READY</b><br>Ready for the measurement  | Bit 0 LSB |
|                                    | <b>OUT_ERROR</b><br>• Start measurement if READY = Ø<br>• Measurement-channel overdrive<br>• Device error during boot-up procedure | Bit 1     |
|                                    | <b>OUT_NOK_ONL1</b><br>Online- NOK 1, online signal for "Window" evaluation element  | Bit 2     |
|                                    | <b>OUT_NOK_ONL2</b><br>Online- NOK 2, online signal for "Window" evaluation element  | Bit 3     |
|                                    | <b>OUT_OK</b><br>Overall measurement result was OK   | Bit 4     |
|                                    | <b>OUT_NOK</b><br>Overall measurement result was NOK   | Bit 5     |
|                                    | <b>OUT_S1</b><br>Online switching signal 1   | Bit 6     |
|                                    | <b>OUT_S2</b><br>Online switching signal 2   | Bit 7 MSB |

### 6.3.2 PLC outputs byte 2 (9307 adjustable outputs)

| PLC outputs Byte 2 (Slave →Master) |          |           |
|------------------------------------|----------|-----------|
| Valid values:                      | PLC_OUT8 | Bit 0 LSB |
|                                    | PLC_OUT7 | Bit 1     |
|                                    | PLC_OUT6 | Bit 2     |
|                                    | PLC_OUT5 | Bit 3     |
|                                    | PLC_OUT4 | Bit 4     |
|                                    | PLC_OUT3 | Bit 5     |
|                                    | PLC_OUT2 | Bit 6     |
|                                    | PLC_OUT1 | Bit 7 MSB |

### 6.3.3 PLC outputs byte 3 (9307 adjustable outputs)

| PLC outputs Byte 3 (Slave → Master) |           |           |
|-------------------------------------|-----------|-----------|
| Valid values:                       | PLC_OUT9  | Bit 0 LSB |
|                                     | PLC_OUT10 | Bit 1     |
|                                     | PLC_OUT11 | Bit 2     |
|                                     | PLC_OUT12 | Bit 3     |
|                                     | PLC_OUT13 | Bit 4     |
|                                     | PLC_OUT14 | Bit 5     |
|                                     | PLC_OUT15 | Bit 6     |
|                                     | PLC_OUT16 | Bit 7 MSB |

### 6.3.4 PLC outputs byte 4 (9307 adjustable outputs)

| PLC outputs Byte 4 (Slave → Master) |           |           |
|-------------------------------------|-----------|-----------|
| Valid values:                       | reserved  | Bit 0 LSB |
|                                     | PLC_OUT23 | Bit 1     |
|                                     | PLC_OUT22 | Bit 2     |
|                                     | PLC_OUT21 | Bit 3     |
|                                     | PLC_OUT20 | Bit 4     |
|                                     | PLC_OUT19 | Bit 5     |
|                                     | PLC_OUT18 | Bit 6     |
|                                     | PLC_OUT17 | Bit 7 MSB |

|             |  |
|-------------|--|
| <b>NOTE</b> | <p>Note that PLC outputs PLC_OUT[23..1] could be assigned with different functions. The assignment could be changed within the DIGIFORCE® 9307 basic setup menu "Assignment of the PLC outputs"(see DIGIFORCE® 9307 operation manual chapter 5.3.9 Assigning PLC outputs).</p> |
|-------------|--|

### 6.3.5 Default assignment of output byte [4..2] adjustable outputs

| 9307 adjustable PLC outputs default assignment |           |                       |
|--|-----------|-----------------------|
|  | PLC_OUT1  | OUT_STROBE            |
|  | PLC_OUT2  | OUT_OK_SENSORTEST     |
|  | PLC_OUT3  | OUT_NOK_WINDOW_9      |
|  | PLC_OUT4  | OUT_PROG0             |
|  | PLC_OUT5  | OUT_PROG1             |
|  | PLC_OUT6  | OUT_PROG2             |
|  | PLC_OUT7  | OUT_PROG3             |
|  | PLC_OUT8  | OUT_PROG4             |
|  | PLC_OUT9  | OUT_S3                |
|  | PLC_OUT10 | OUT_S4                |
|  | PLC_OUT11 | OUT_NOK_WINDOW_8      |
|  | PLC_OUT12 | OUT_NOK_WINDOW_7      |
|  | PLC_OUT13 | OUT_NOK_WINDOW_6      |
|  | PLC_OUT14 | OUT_NOK_WINDOW_5      |
|  | PLC_OUT15 | OUT_NOK_WINDOW_4      |
|  | PLC_OUT16 | OUT_NOK_WINDOW_3      |
|  | PLC_OUT17 | OUT_NOK_WINDOW_2      |
|  | PLC_OUT18 | OUT_NOK_WINDOW_1      |
|  | PLC_OUT19 | OUT_WARNING_TARE      |
|  | PLC_OUT20 | OUT_WARNING_TOOLCOUNT |
|  | PLC_OUT21 | OUT_WARNING_TOTAL     |
|  | PLC_OUT22 | OUT_TEST_OP_SIMPLE    |
|  | PLC_OUT23 | OUT_TEST_OP_COMPLEX   |

## 6.4 Evaluation info – Transfer from Slave to Master

The evaluation info (4 byte) contains the evaluation result of each element.

### 6.4.1 Evaluation info byte 1

| Evaluation info byte 1 (Slave →Master) |              |           |
|--|--------------|-----------|
| Valid values:                          | Window_1_NOK | Bit 0 LSB |
|  | Window_2_NOK | Bit 1     |
|  | Window_3_NOK | Bit 2     |
|  | Window_4_NOK | Bit 3     |
|  | Window_5_NOK | Bit 4     |
|  | Window_6_NOK | Bit 5     |
|  | Window_7_NOK | Bit 6     |
|  | Window_8_NOK | Bit 7 MSB |

### 6.4.2 Evaluation info byte 2

| Evaluation info byte 2 (Slave →Master) |                  |           |
|--|------------------|-----------|
| Valid values:                          | Window_9_NOK     | Bit 0 LSB |
|  | Window_10_NOK    | Bit 1     |
|  | Trapezoid_X1_NOK | Bit 2     |
|  | Trapezoid_X2_NOK | Bit 3     |
|  | Trapezoid_Y1_NOK | Bit 4     |
|  | Trapezoid_Y2_NOK | Bit 5     |
|  | Threshold_1_NOK  | Bit 6     |
|  | Threshold_2_NOK  | Bit 7 MSB |

#### 6.4.3 Evaluation info byte 3

| Evaluation info byte 3 (Slave →Master) |                       |           |
|--|-----------------------|-----------|
| Valid values:                          | Threshold_3_NOK       | Bit 0 LSB |
|  | Threshold_4_NOK       | Bit 1     |
|  | Envelope_1_NOK        | Bit 2     |
|  | Envelope_2_NOK        | Bit 3     |
|  | Math_Evaluation_1_NOK | Bit 4     |
|  | Math_Evaluation_2_NOK | Bit 5     |
|  | Math_Evaluation_3_NOK | Bit 6     |
|  | Math_Evaluation_4_NOK | Bit 7 MSB |

#### 6.4.4 Evaluation info byte 4

| Evaluation info byte 4 (Slave →Master) |                       |           |
|--|-----------------------|-----------|
| Valid values:                          | Math_Evaluation_5_NOK | Bit 0 LSB |
|  | Math_Evaluation_6_NOK | Bit 1     |
|  | Rotary_Switch_1_NOK   | Bit 2     |
|  | Rotary_Switch_2_NOK   | Bit 3     |
|  | MeasChannel_Overload  | Bit 4     |
|  | Curve_Y1_NOK          | Bit 5     |
|  | Curve_Y2_NOK          | Bit 6     |
|  | Global_NOK            | Bit 7 MSB |

## 6.5 Byte reference list

### Data from Master to Slave

| Byte | Function          | Section | Comments |
|------|-------------------|---------|----------|
| 0    | PLC inputs Byte 1 | 5.2.1   |          |
| 1    | PLC inputs Byte 2 | 5.2.2   |          |
| 2    | PLC inputs Byte 3 | 5.2.3   |          |
| 3    | PLC inputs Byte 4 | 5.2.4   |          |

### Data from Slave to Master

| Byte | Function                            | Section   | Comments   |
|------|-------------------------------------|---|--|
| 0    | PLC outputs Byte 1                  | 5.3.1   |  |
| 1    | PLC outputs Byte 2                  | 5.3.2   |  |
| 2    | PLC outputs Byte 3                  | 5.3.3   |  |
| 3    | PLC outputs Byte 4                  | 5.3.4   |  |
| 4    | Evaluation info Byte 1              | 5.4.1   |  |
| 5    | Evaluation info Byte 2              | 5.4.2   |  |
| 6    | Evaluation info Byte 3              | 5.4.3   |  |
| 7    | Evaluation info Byte 4              | 5.4.4   |  |
| 8    | M5-1 value_1 (1 <sup>st</sup> Byte) | see DIGIFORCE® 9307 operation manual chapter 5.13 | User defined value in DIGIFORCE® 9307 List M5-1 (32-Bit float) |
| 9    | M5-1 value_1 (2 <sup>nd</sup> Byte) | see above   |  |
| 10   | M5-1 value_1 (3 <sup>rd</sup> Byte) | see above   |  |
| 11   | M5-1 value_1 (4 <sup>th</sup> Byte) | see above   |  |
| 12   | M5-1 value_2 (1 <sup>st</sup> Byte) | see above   | User defined value in DIGIFORCE® 9307 List M5-1 (32-Bit float) |
| 13   | M5-1 value_2 (2 <sup>nd</sup> Byte) | see above   |  |
| 14   | M5-1 value_2 (3 <sup>rd</sup> Byte) | see above   |  |
| 15   | M5-1 value_2 (4 <sup>th</sup> Byte) | see above   |  |
| 16   | M5-1 value_3 (1 <sup>st</sup> Byte) | see above   | User defined value in DIGIFORCE® 9307 List M5-1 (32-Bit float) |
| 17   | M5-1 value_3 (2 <sup>nd</sup> Byte) | see above   |  |
| 18   | M5-1 value_3 (3 <sup>rd</sup> Byte) | see above   |  |
| 19   | M5-1 value_3 (4 <sup>th</sup> Byte) | see above   |  |

| Byte | Function                             | Section   | Comments  |
|------|--------------------------------------|-----------|---|
| 20   | M5-1 value_4 (1 <sup>st</sup> Byte)  | see above |   |
| 21   | M5-1 value_4 (2 <sup>nd</sup> Byte)  | see above |   |
| 22   | M5-1 value_4 (3 <sup>rd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307<br>List M5-1 (32-Bit float) |
| 23   | M5-1 value_4 (4 <sup>th</sup> Byte)  | see above |   |
| 24   | M5-1 value_5 (1 <sup>st</sup> Byte)  | see above |   |
| 25   | M5-1 value_5 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307<br>List M5-1 (32-Bit float) |
| 26   | M5-1 value_5 (3 <sup>rd</sup> Byte)  | see above |   |
| 27   | M5-1 value_5 (4 <sup>th</sup> Byte)  | see above |   |
| 28   | M5-1 value_6 (1 <sup>st</sup> Byte)  | see above |   |
| 29   | M5-1 value_6 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307<br>List M5-1 (32-Bit float) |
| 30   | M5-1 value_6 (3 <sup>rd</sup> Byte)  | see above |   |
| 31   | M5-1 value_6 (4 <sup>th</sup> Byte)  | see above |   |
| 32   | M5-1 value_7 (1 <sup>st</sup> Byte)  | see above |   |
| 33   | M5-1 value_7 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307<br>List M5-1 (32-Bit float) |
| 34   | M5-1 value_7 (3 <sup>rd</sup> Byte)  | see above |   |
| 35   | M5-1 value_7 (4 <sup>th</sup> Byte)  | see above |   |
| 36   | M5-1 value_8 (1 <sup>st</sup> Byte)  | see above |   |
| 37   | M5-1 value_8 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307<br>List M5-1 (32-Bit float) |
| 38   | M5-1 value_8 (3 <sup>rd</sup> Byte)  | see above |   |
| 39   | M5-1 value_8 (4 <sup>th</sup> Byte)  | see above |   |
| 40   | M5-1 value_9 (1 <sup>st</sup> Byte)  | see above |   |
| 41   | M5-1 value_9 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307<br>List M5-1 (32-Bit float) |
| 42   | M5-1 value_9 (3 <sup>rd</sup> Byte)  | see above |   |
| 43   | M5-1 value_9 (4 <sup>th</sup> Byte)  | see above |   |
| 44   | M5-1 value_10 (1 <sup>st</sup> Byte) | see above |   |
| 45   | M5-1 value_10 (2 <sup>nd</sup> Byte) | see above | User defined value in DIGIFORCE® 9307<br>List M5-1 (32-Bit float) |
| 46   | M5-1 value_10 (3 <sup>rd</sup> Byte) | see above |   |
| 47   | M5-1 value_10 (4 <sup>th</sup> Byte) | see above |   |
| 48   | M5-1 value_11 (1 <sup>st</sup> Byte) | see above | User defined value in DIGIFORCE® 9307<br>List M5-1 (32-Bit float) |
| 49   | M5-1 value_11 (2 <sup>nd</sup> Byte) | see above |   |

| Byte | Function                             | Section   | Comments   |
|------|--------------------------------------|-----------|--|
| 50   | M5-1 value_11 (3 <sup>rd</sup> Byte) | see above |  |
| 51   | M5-1 value_11 (4 <sup>th</sup> Byte) | see above |  |
| 52   | M5-1 value_12 (1 <sup>st</sup> Byte) | see above |  |
| 53   | M5-1 value_12 (2 <sup>nd</sup> Byte) | see above | User defined value in DIGIFORCE® 9307 List M5-1 (32-Bit float) |
| 54   | M5-1 value_12 (3 <sup>rd</sup> Byte) | see above |  |
| 55   | M5-1 value_12 (4 <sup>th</sup> Byte) | see above |  |
| 56   | M5-2 value_1 (1 <sup>st</sup> Byte)  | see above |  |
| 57   | M5-2 value_1 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307 List M5-2 (32-Bit float) |
| 58   | M5-2 value_1 (3 <sup>rd</sup> Byte)  | see above |  |
| 59   | M5-2 value_1 (4 <sup>th</sup> Byte)  | see above |  |
| 60   | M5-2 value_2 (1 <sup>st</sup> Byte)  | see above |  |
| 61   | M5-2 value_2 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307 List M5-2 (32-Bit float) |
| 62   | M5-2 value_2 (3 <sup>rd</sup> Byte)  | see above |  |
| 63   | M5-2 value_2 (4 <sup>th</sup> Byte)  | see above |  |
| 64   | M5-2 value_3 (1 <sup>st</sup> Byte)  | see above |  |
| 65   | M5-2 value_3 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307 List M5-2 (32-Bit float) |
| 66   | M5-2 value_3 (3 <sup>rd</sup> Byte)  | see above |  |
| 67   | M5-2 value_3 (4 <sup>th</sup> Byte)  | see above |  |
| 68   | M5-2 value_4 (1 <sup>st</sup> Byte)  | see above |  |
| 69   | M5-2 value_4 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307 List M5-2 (32-Bit float) |
| 70   | M5-2 value_4 (3 <sup>rd</sup> Byte)  | see above |  |
| 71   | M5-2 value_4 (4 <sup>th</sup> Byte)  | see above |  |
| 72   | M5-2 value_5 (1 <sup>st</sup> Byte)  | see above |  |
| 73   | M5-2 value_5 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307 List M5-2 (32-Bit float) |
| 74   | M5-2 value_5 (3 <sup>rd</sup> Byte)  | see above |  |
| 75   | M5-2 value_5 (4 <sup>th</sup> Byte)  | see above |  |
| 76   | M5-2 value_6 (1 <sup>st</sup> Byte)  | see above |  |
| 77   | M5-2 value_6 (2 <sup>nd</sup> Byte)  | see above | User defined value in DIGIFORCE® 9307 List M5-2 (32-Bit float) |
| 78   | M5-2 value_6 (3 <sup>rd</sup> Byte)  | see above |  |
| 79   | M5-2 value_6 (4 <sup>th</sup> Byte)  | see above |  |

| Byte | Function                               | Section   | Comments  |
|------|--|-----------|---|
| 80   | M5-2 value_7 (1 <sup>st</sup> Byte)    | see above |   |
| 81   | M5-2 value_7 (2 <sup>nd</sup> Byte)    | see above |   |
| 82   | M5-2 value_7 (3 <sup>rd</sup> Byte)    | see above | User defined value in DIGIFORCE® 9307<br>List M5-2 (32-Bit float)         |
| 83   | M5-2 value_7 (4 <sup>th</sup> Byte)    | see above |   |
| 84   | M5-2 value_8 (1 <sup>st</sup> Byte)    | see above |   |
| 85   | M5-2 value_8 (2 <sup>nd</sup> Byte)    | see above | User defined value in DIGIFORCE® 9307<br>List M5-2 (32-Bit float)         |
| 86   | M5-2 value_8 (3 <sup>rd</sup> Byte)    | see above |   |
| 87   | M5-2 value_8 (4 <sup>th</sup> Byte)    | see above |   |
| 88   | M5-2 value_9 (1 <sup>st</sup> Byte)    | see above |   |
| 89   | M5-2 value_9 (2 <sup>nd</sup> Byte)    | see above | User defined value in DIGIFORCE® 9307<br>List M5-2 (32-Bit float)         |
| 90   | M5-2 value_9 (3 <sup>rd</sup> Byte)    | see above |   |
| 91   | M5-2 value_9 (4 <sup>th</sup> Byte)    | see above |   |
| 92   | M5-2 value_10 (1 <sup>st</sup> Byte)   | see above |   |
| 93   | M5-2 value_10 (2 <sup>nd</sup> Byte)   | see above | User defined value in DIGIFORCE® 9307<br>List M5-2 (32-Bit float)         |
| 94   | M5-2 value_10 (3 <sup>rd</sup> Byte)   | see above |   |
| 95   | M5-2 value_10 (4 <sup>th</sup> Byte)   | see above |   |
| 96   | M5-2 value_11 (1 <sup>st</sup> Byte)   | see above |   |
| 97   | M5-2 value_11 (2 <sup>nd</sup> Byte)   | see above | User defined value in DIGIFORCE® 9307<br>List M5-2 (32-Bit float)         |
| 98   | M5-2 value_11 (3 <sup>rd</sup> Byte)   | see above |   |
| 99   | M5-2 value_11 (4 <sup>th</sup> Byte)   | see above |   |
| 100  | M5-2 value_12 (1 <sup>st</sup> Byte)   | see above |   |
| 101  | M5-2 value_12 (2 <sup>nd</sup> Byte)   | see above | User defined value in DIGIFORCE® 9307<br>List M5-2 (32-Bit float)         |
| 102  | M5-2 value_12 (3 <sup>rd</sup> Byte)   | see above |   |
| 103  | M5-2 value_12 (4 <sup>th</sup> Byte)   | see above |   |
| 104  | M1_Curvevalue_1 (1 <sup>st</sup> Byte) | see above |   |
| 105  | M1_Curvevalue_1 (2 <sup>nd</sup> Byte) | see above | User defined value in DIGIFORCE® 9307<br>value in curve M1 (32-Bit float) |
| 106  | M1_Curvevalue_1 (3 <sup>rd</sup> Byte) | see above |   |
| 107  | M1_Curvevalue_1 (4 <sup>th</sup> Byte) | see above |   |
| 108  | M1_Curvevalue_2 (1 <sup>st</sup> Byte) | see above | User defined value in DIGIFORCE® 9307<br>value in curve M1                |
| 109  | M1_Curvevalue_2 (2 <sup>nd</sup> Byte) | see above |   |

| Byte | Function                                     | Section   | Comments   |
|------|--|-----------|--|
| 110  | M1_Curvevalue_2 (3 <sup>rd</sup> Byte)       | see above | (32-Bit float)   |
| 111  | M1_Curvevalue_2 (4 <sup>th</sup> Byte)       | see above |  |
| 112  | M1_Curvevalue_3 (1 <sup>st</sup> Byte)       | see above |  |
| 113  | M1_Curvevalue_3 (2 <sup>nd</sup> Byte)       | see above | User defined value in DIGIFORCE® 9307 value in curve M1 (32-Bit float) |
| 114  | M1_Curvevalue_3 (3 <sup>rd</sup> Byte)       | see above |  |
| 115  | M1_Curvevalue_3 (4 <sup>th</sup> Byte)       | see above |  |
| 116  | M1_Curvevalue_4 (1 <sup>st</sup> Byte)       | see above |  |
| 117  | M1_Curvevalue_4 (2 <sup>nd</sup> Byte)       | see above | User defined value in DIGIFORCE® 9307 value in curve M1 (32-Bit float) |
| 118  | M1_Curvevalue_4 (3 <sup>rd</sup> Byte)       | see above |  |
| 119  | M1_Curvevalue_4 (4 <sup>th</sup> Byte)       | see above |  |
| 120  | M1_Curvevalue_5 (1 <sup>st</sup> Byte)       | see above |  |
| 121  | M1_Curvevalue_5 (2 <sup>nd</sup> Byte)       | see above | User defined value in DIGIFORCE® 9307 value in curve M1 (32-Bit float) |
| 122  | M1_Curvevalue_5 (3 <sup>rd</sup> Byte)       | see above |  |
| 123  | M1_Curvevalue_5 (4 <sup>th</sup> Byte)       | see above |  |
| 124  | M1_Curvevalue_6 (1 <sup>st</sup> Byte)       | see above |  |
| 125  | M1_Curvevalue_6 (2 <sup>nd</sup> Byte)       | see above | User defined value in DIGIFORCE® 9307 value in curve M1 (32-Bit float) |
| 126  | M1_Curvevalue_6 (3 <sup>rd</sup> Byte)       | see above |  |
| 127  | M1_Curvevalue_6 (4 <sup>th</sup> Byte)       | see above |  |
| 128  | Live value Channel X (1 <sup>st</sup> Byte)  |           |  |
| 129  | Live value Channel X (2 <sup>nd</sup> Byte)  |           | (32-Bit float)<br>Channel X live value                                 |
| 130  | Live value Channel X (3 <sup>rd</sup> Byte)  |           | Updating rate of the live values 100/sec.                              |
| 131  | Live value Channel X (4 <sup>th</sup> Byte)  |           |  |
| 132  | Live value Channel Y1 (1 <sup>st</sup> Byte) |           |  |
| 133  | Live value Channel Y1 (2 <sup>nd</sup> Byte) |           | (32-Bit float)<br>Channel Y1 live value                                |
| 134  | Live value Channel Y1 (3 <sup>rd</sup> Byte) |           | Updating rate of the live values 100/sec.                              |
| 135  | Live value Channel Y1 (4 <sup>th</sup> Byte) |           |  |
| 136  | Live value Channel Y2 (1 <sup>st</sup> Byte) |           |  |
| 137  | Live value Channel Y2 (2 <sup>nd</sup> Byte) |           | (32-Bit float)<br>Channel Y2 live value                                |
| 138  | Live value Channel Y2 (3 <sup>rd</sup> Byte) |           | Updating rate of the live values 100/sec.                              |
| 139  | Live value Channel Y2 (4 <sup>th</sup> Byte) |           |  |

## 7 EtherCAT SDO – Service Data Objects

### EtherCAT-Firmware V201900 and above

**Note:** The current EtherCAT specification does not have any error codes in case the device cannot perform a command due to its current state, e.g. an optional analogue card is not build-in. If you write some data into the device, it is recommended to read the value back and compare it with the set value to be sure the device has accepted your parameter. Additionally, the device sends an emergency message if a parameter cannot be read or written. EtherCAT Master can read out these emergency messages. One message consists of 5 bytes: **CFGER** and means **Configuratiuon Error**. Please also use them with read commands, especially if the expected value is a 0 (zero). If the device fails to return data due to its current state, it sets all data bytes to zero and sends an emergency message.

The services are described from the point of view of the Master.

The SDO EtherCAT services allow access to following DIGIFORCE® 9307 functions:

- Complete device configuration
- Transfer of component/worker/job data for logging
- Retrieval of large amounts of process and curve data
- Abbreviations

|        |  |
|--------|--|
| WO     | Write Only   |
| RO     | Read Only  |
| RW     | Read and Write   |
| Event! | Writing an arbitrary byte initiates action                                   |
| BOOL   | Data type Boolean  |
| FLT    | Data type Float, floating point number according to IEEE754, Length = 4 Byte |
| STRn   | Data type String, String of n Bytes  |
| U8     | Data type Unsigned 8, Length = 1 Byte  |
| U16    | Data type Unsigned 16, Length = 2 Byte                                       |
| U32    | Data type Unsigned 32, Length = 4 Byte                                       |

### 7.1 Instrument configuration

#### 7.1.1 Index 0x2000: Master Outputs

| Index  | Sub-Index | Description | Value  | Meaning of value | Type | Len | R/W |
|--------|-----------|-------------|--------|------------------|------|-----|-----|
| 0x2000 | 1         | IN_PROG0    | 0<br>1 | Set<br>Not set   | BOOL |     | WO  |
| 0x2000 | 2         | IN_PROG1    | 0<br>1 | Set<br>Not set   | BOOL |     | WO  |
| 0x2000 | 3         | IN_PROG2    | 0<br>1 | Set<br>Not set   | BOOL |     | WO  |
| 0x2000 | 4         | IN_PROG3    | 0<br>1 | Set<br>Not set   | BOOL |     | WO  |
| 0x2000 | 5         | IN_PROG4    | 0<br>1 | Set<br>Not set   | BOOL |     | WO  |
| 0x2000 | 6         | IN_STROBE   | 0<br>1 | Set<br>Not set   | BOOL |     | WO  |
| 0x2000 | 7         | IN_ACK_OK   | 0<br>1 | Set<br>Not set   | BOOL |     | WO  |

|               |    |             |        |                |      |  |    |
|---------------|----|-------------|--------|----------------|------|--|----|
| <b>0x2000</b> | 8  | IN_ACK_NOK  | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 9  | IN_TEST_OP  | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 10 | IN_TEST_OPC | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 11 | IN_AUTO     | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 12 | IN_REF_MEAS | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 13 | IN_RESET    | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 14 | IN_PROG6*   | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 15 | IN_STEST    | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 16 | IN_PROG5*   | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 17 | IN_LTEST    | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 18 | IN_TAREX    | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 19 | IN_TAREY1   | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 20 | IN_TAREY2   | 0<br>1 | Set<br>Not set | BOOL |  | WO |
| <b>0x2000</b> | 21 | IN_START    | 0<br>1 | Set<br>Not set | BOOL |  | WO |

\*) IN\_PROG 6...5 in firmware with 128 Measurement programs

## 7.1.2 Index 0x2001: Master Inputs

| Index         | Sub-Index | Description    | Value  | Meaning of value | Type | Len | R/W |
|---------------|-----------|----------------|--------|------------------|------|-----|-----|
| <b>0x2001</b> | 1         | OUT_READY      | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |
| <b>0x2001</b> | 2         | OUT_ERROR      | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |
| <b>0x2001</b> | 3         | OUT_NOK_ONL1   | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |
| <b>0x2001</b> | 4         | OUT_NOK_ONL2   | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |
| <b>0x2001</b> | 5         | OUT_OK         | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |
| <b>0x2001</b> | 6         | OUT_NOK        | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |
| <b>0x2001</b> | 7         | OUT_S1         | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |
| <b>0x2001</b> | 8         | OUT_S2         | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |
| <b>0x2001</b> | 9         | OUT_USER_DEF_8 | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |
| <b>0x2001</b> | 10        | OUT_USER_DEF_7 | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |
| <b>0x2001</b> | 11        | OUT_USER_DEF_6 | 0<br>1 | Set<br>Not set   | BOOL |     | RO  |

|               |    |                 |        |                |      |  |    |
|---------------|----|-----------------|--------|----------------|------|--|----|
| <b>0x2001</b> | 12 | OUT_USER_DEF_5  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 13 | OUT_USER_DEF_4  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 14 | OUT_USER_DEF_3  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 15 | OUT_USER_DEF_2  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 16 | OUT_USER_DEF_1  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 17 | OUT_USER_DEF_9  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 18 | OUT_USER_DEF_10 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 19 | OUT_USER_DEF_11 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 20 | OUT_USER_DEF_12 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 21 | OUT_USER_DEF_13 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 22 | OUT_USER_DEF_14 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 23 | OUT_USER_DEF_15 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 24 | OUT_USER_DEF_16 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 25 | OUT_USER_DEF_23 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 26 | OUT_USER_DEF_22 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 27 | OUT_USER_DEF_21 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 28 | OUT_USER_DEF_20 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 29 | OUT_USER_DEF_19 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 30 | OUT_USER_DEF_18 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 31 | OUT_USER_DEF_17 | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 32 | Window 1 state  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 33 | Window 2 state  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 34 | Window 3 state  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 35 | Window 4 state  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 36 | Window 5 state  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 37 | Window 6 state  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 38 | Window 7 state  | 0<br>1 | Set<br>Not set | BOOL |  | RO |
| <b>0x2001</b> | 39 | Window 8 state  | 0<br>1 | Set<br>Not set | BOOL |  | RO |

|               |    |                               |        |                |      |   |    |
|---------------|----|-------------------------------|--------|----------------|------|---|----|
| <b>0x2001</b> | 40 | Window 9 state                | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 41 | Window 10 state               | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 42 | Trapezoid window X1 State     | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 43 | Trapezoid window X2 state     | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 44 | Trapezoid window Y1 state     | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 45 | Trapezoid window Y2 state     | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 46 | Threshold 1 state             | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 47 | Threshold 2 state             | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 48 | Threshold 3 state             | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 49 | Threshold 4 state             | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 50 | Envelope 1 state              | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 51 | Envelope 2 state              | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 52 | Mathematical function 1 state | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 53 | Mathematical function 2 state | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 54 | Mathematical function 3 state | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 55 | Mathematical function 4 state | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 56 | Mathematical function 5 state | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 57 | Mathematical function 6 state | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 58 | Rotary switch 1 state         | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 59 | Rotary switch 2 state         | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 60 | Channel overdriven            | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 61 | Channel Y1 is NOK             | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 62 | Channel Y2 is NOK             | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 63 | Overall result is NIO         | 0<br>1 | Set<br>Not set | BOOL |   | RO |
| <b>0x2001</b> | 64 | User-defined result 1         | 0<br>1 | Set<br>Not set | FLT  | 4 | RO |
| <b>0x2001</b> | 65 | User-defined result 2         | 0<br>1 | Set<br>Not set | FLT  | 4 | RO |
| <b>0x2001</b> | 66 | User-defined result 3         | 0<br>1 | Set<br>Not set | FLT  | 4 | RO |
| <b>0x2001</b> | 67 | User-defined result 4         | 0<br>1 | Set<br>Not set | FLT  | 4 | RO |

|               |    |                          |        |                |     |   |    |
|---------------|----|--------------------------|--------|----------------|-----|---|----|
| <b>0x2001</b> | 68 | User-defined result 5    | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 69 | User-defined result 6    | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 70 | User-defined result 7    | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 71 | User-defined result 8    | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 72 | User-defined result 9    | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 73 | User-defined result 10   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 74 | User-defined result 11   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 75 | User-defined result 12   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 76 | User-defined result 13   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 77 | User-defined result 14   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 78 | User-defined result 15   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 79 | User-defined result 16   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 80 | User-defined result 17   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 81 | User-defined result 18   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 82 | User-defined result 19   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 83 | User-defined result 20   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 84 | User-defined result 21   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 85 | User-defined result 22   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 86 | User-defined result 23   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 87 | User-defined result 24   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 88 | User-defined result 25   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 89 | User-defined result 26   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 90 | User-defined result 27   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 91 | User-defined result 28   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 92 | User-defined result 29   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 93 | User-defined result 30   | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 94 | Live value of channel X  | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
| <b>0x2001</b> | 95 | Live value of channel Y1 | 0<br>1 | Set<br>Not set | FLT | 4 | RO |

|               |    |                          |        |                |     |   |    |
|---------------|----|--------------------------|--------|----------------|-----|---|----|
| <b>0x2001</b> | 96 | Live value of channel Y2 | 0<br>1 | Set<br>Not set | FLT | 4 | RO |
|---------------|----|--------------------------|--------|----------------|-----|---|----|

### 7.1.3 General settings (Index 0x2030)

#### Index 0x2030, Subindex 1 to 20

| Index         | Sub-Index | Description                                      | Value                                | Meaning of value   | Type   | Len | R/W |
|---------------|-----------|--|--------------------------------------|--|--------|-----|-----|
| <b>0x2030</b> | 0         | Number of subindices                             | 115                                  |  | U8     | 1   | RO  |
| <b>0x2030</b> | 1...9     | Reserved   | -                                    | Not possible   |        |     | X   |
| <b>0x2030</b> | 10        | Device detection                                 | <i>DIGIFORCE model 9307</i>          |  | STR 18 | 18  | RO  |
| <b>0x2030</b> | 11        | Serial number                                    | 12345678                             |  | STR 11 | 11  | RO  |
| <b>0x2030</b> | 12        | Software version                                 | V201100                              |  | STR 25 | 25  | RO  |
| <b>0x2030</b> | 13        | Version boot loader software                     | V201100                              |  | STR 25 | 25  | RO  |
| <b>0x2030</b> | 14        | Software version Field bus interface             | EC-201400                            |  | STR 25 | 25  | RO  |
| <b>0x2030</b> | 15        | Optional analog interface enabled                | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7 | No option<br>Torque<br>Piezo<br>Torque+Piezo<br>Resistance<br>Torque+Resistance<br>Piezo+Resistance<br>Torque+Piezo+Resistance | U16    | 2   | RO  |
|               | 16        | Info: Calibration date analog interface          | 07.11.2012                           |  | STR 10 | 10  | RO  |
|               | 17        | Info: Calibration date optional analog interface | 07.11.2012                           |  | STR 10 | 10  | RO  |
|               | 18        | Reserved   | -                                    | Not possible   |        |     | XX  |
|               | 19        | Station name                                     | <i>Stat14 right</i>                  |  | STR 15 | 15  | RW  |
|               | 20        | Tool counter                                     | 0 ...<br>4294967296                  |  | U32    | 4   | RO  |

## Index 0x2030, Subindex 21 to 40

| Index  | Sub-Index | Description                                 | Value  | Meaning of value   | Type   | Len | R/W |
|--------|-----------|---|--|--|--------|-----|-----|
| 0x2030 | 21        | Standard value for tool counter             | 0 ... 4294967296   |  | U32    | 4   | RW  |
| 0x2030 | 22        | Reset tool counter                          | EVENT!   | Writing an arbitrary byte initiates action   | U8     | 1   | WO  |
| 0x2030 | 23        | Language                                    | 0<br>1<br>2<br>3<br>4  | german<br>english<br>french<br>spanish<br>italian  | U16    | 2   | RW  |
| 0x2030 | 24        | Date  | [dd.mm.yyyy]   | e.g.: 21.09.1963   | STR 10 | 10  | RW  |
| 0x2030 | 25        | Time  | [hh:mm:ss], 24h  | e.g.: 22:15:00   | STR 8  | 8   | RW  |
| 0x2030 | 26        | LCD brightness                              | 1 ... 10   | Integer value (10 max.)  | U16    | 2   | RW  |
| 0x2030 | 27        | Background graphical display bright/dark    | 0<br>1   | dark<br>bright   | U16    | 2   | RW  |
| 0x2030 | 28        | Measurement menu function key definition F1 | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9<br>10<br>11<br>12<br>13 | Off<br>Meas. menu page up<br>Meas. menu page down<br>Meas. program incremental<br>Meas. program decremental<br>Tare X<br>Tare Y<br>Tare Y2<br>Measurement Start/Stop<br>Acknowledge OK parts<br>Acknowledge NOK parts<br>Sensor test<br>Reference measurement<br>Edit mode | U16    | 2   | RW  |
| 0x2030 | 29        | Measurement menu function key definition F2 | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9<br>10<br>11<br>12<br>13 | Off<br>Meas. menu page up<br>Meas. menu page down<br>Meas. program incremental<br>Meas. program decremental<br>Tare X<br>Tare Y<br>Tare Y2<br>Measurement Start/Stop<br>Acknowledge OK parts<br>Acknowledge NOK parts<br>Sensor test<br>Reference measurement<br>Edit mode | U16    | 2   | RW  |
| 0x2030 | 30        | Measurement menu function key definition F3 | 0<br>1<br>2<br>3<br>4<br>5   | Off<br>Meas. menu page up<br>Meas. menu page down<br>Meas. program incremental<br>Meas. program decremental<br>Tare X  | U16    | 2   | RW  |

| Index  | Sub-Index | Description                                 | Value  | Meaning of value   | Type | Len | R/W |
|--------|-----------|---|--|--|------|-----|-----|
|        |           |   | 6<br>7<br>8<br>9<br>10<br>11<br>12<br>13                               | Tare Y<br>Tare Y2<br>Measurement Start/Stop<br>Acknowledge OK parts<br>Acknowledge NOK parts<br>Sensor test<br>Reference measurement<br>Edit mode  |      |     |     |
| 0x2030 | 31        | Measurement menu function key definition F4 | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9<br>10<br>11<br>12<br>13 | Off<br>Meas. menu page up<br>Meas. menu page down<br>Meas. program incremental<br>Meas. program decremental<br>Tare X<br>Tare Y<br>Tare Y2<br>Measurement Start/Stop<br>Acknowledge OK parts<br>Acknowledge NOK parts<br>Sensor test<br>Reference measurement<br>Edit mode | U16  | 2   | RW  |
|        |           |   | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9<br>10<br>11<br>12<br>13 | Off<br>Meas. menu page up<br>Meas. menu page down<br>Meas. program incremental<br>Meas. program decremental<br>Tare X<br>Tare Y<br>Tare Y2<br>Measurement Start/Stop<br>Acknowledge OK parts<br>Acknowledge NOK parts<br>Sensor test<br>Reference measurement<br>Edit mode |      |     |     |
|        |           |   | 0<br>1   | Meas. menu disabled<br>Meas. menu enabled  |      |     |     |
|        |           |   | 0<br>1   | Meas. menu disabled<br>Meas. menu enabled  |      |     |     |
|        |           |   | 0<br>1   | Meas. menu disabled<br>Meas. menu enabled  |      |     |     |
|        |           |   | 0<br>1   | Meas. menu disabled<br>Meas. menu enabled  |      |     |     |
|        |           |   | 0<br>1<br>2  | Off<br>Smiley<br>Text  |      |     |     |
|        |           |   | 0<br>1   | Meas. menu disabled<br>Meas. menu enabled  |      |     |     |
|        |           |   | 0<br>1   | Meas. menu disabled<br>Meas. menu enabled  |      |     |     |
|        |           |   | 0<br>1   | Meas. menu disabled<br>Meas. menu enabled  |      |     |     |
|        |           |   | 0<br>1   | Meas. menu disabled<br>Meas. menu enabled  |      |     |     |
|        |           |   | 0<br>1   | Meas. menu disabled<br>Meas. menu enabled  |      |     |     |
|        |           |   | 0<br>1   | Meas. menu disabled<br>Meas. menu enabled  |      |     |     |

| Index | Sub-Index | Description   | Value | Meaning of value | Type | Len | R/W |
|-------|-----------|---------------|-------|------------------|------|-----|-----|
|       |           | ROTARY SWITCH |       |                  |      |     |     |

**Index 0x2030, Subindex 41 to 58**

| Index  | Sub-Index | Description  | Value   | Meaning of value  | Type | Len | R/W |
|--------|-----------|--|---|---|------|-----|-----|
| 0x2030 | 41        | Display the measurement menu, read the currently displayed measurement menu<br><br><b>Note:</b> The menu is selected here, but not yet displayed. Display only occurs through access to index 30/15. | 101<br>102<br>103<br>104<br>105<br>106<br>107<br>108<br>109<br>110<br>111<br>112<br>113 | Y1 displaying meas. curves<br>Y2 displaying meas. curves<br>Y1 / Y2 displaying meas. curves<br>General curve data Y1<br>General curve data Y2<br>Smiley, Pass/Fail display.<br>Entry/Exit of window<br>Entry/Exit of evaluation elements (except for window)<br>User selected values 1 - 12<br>User selected values 13 - 24<br>Display statistics<br>Order sheet<br>Results of evaluation rotary switch | U16  | 2   | RW  |
| 0x2030 | 42        | Access authorisation Password protection on/off  | 0<br>1  | Password protection on<br>Password protection off   | U16  | 2   | RW  |
| 0x2030 | 43        | Access authorisation BASIC SETUP MENU  | 0<br>1  | Access level disabled<br>Access level enabled   | U16  | 2   | RW  |
| 0x2030 | 44        | Access authorisation MIN. SETUP MENU   | 0<br>1  | Access level disabled<br>Access level enabled   | U16  | 2   | RW  |
| 0x2030 | 45        | Access authorisation MAIN SETUP MENU   | 0<br>1  | Access level disabled<br>Access level enabled   | U16  | 2   | RW  |
| 0x2030 | 46        | Access authorisation CHANNEL SETUP MENU  | 0<br>1  | Access level disabled<br>Access level enabled   | U16  | 2   | RW  |
| 0x2030 | 47        | Access authorisation MEASUREMENT MODE  | 0<br>1  | Access level disabled<br>Access level enabled   | U16  | 2   | RW  |
| 0x2030 | 48        | Access authorisation EVALUATION  | 0<br>1  | Access level disabled<br>Access level enabled   | U16  | 2   | RW  |
| 0x2030 | 49        | Access authorisation SWITCHPOINTS  | 0<br>1  | Access level disabled<br>Access level enabled   | U16  | 2   | RW  |
| 0x2030 | 50        | Access authorisation TEST OPERATION SIMPLE   | 0<br>1  | Access level disabled<br>Access level enabled   | U16  | 2   | RW  |

| Index  | Sub-Index | Description                                 | Value            | Meaning of value                              | Type | Len | R/W |
|--------|-----------|---|------------------|---|------|-----|-----|
| 0x2030 | 51        | Access authorisation TEST OPERATION COMPLEX | 0<br>1           | Access level disabled<br>Access level enabled | U16  | 2   | RW  |
| 0x2030 | 52        | Access authorisation SENSOR TEST            | 0<br>1           | Access level disabled<br>Access level enabled | U16  | 2   | RW  |
| 0x2030 | 53        | Access authorisation USER DEFINED VALUES    | 0<br>1           | Access level disabled<br>Access level enabled | U16  | 2   | RW  |
| 0x2030 | 54        | Access authorisation COPY PROGRAMS          | 0<br>1           | Access level disabled<br>Access level enabled | U16  | 2   | RW  |
| 0x2030 | 55        | Reserved                                    | -                | -   | -    | -   | -   |
| 0x2030 | 56        | Controller password                         | 0000 ...<br>9999 |   | U16  | 2   | RW  |
| 0x2030 | 57        | Set Controller password to default          | EVENT!           | Writing an arbitrary byte initiates action    | U8   | 1   | WO  |
| 0x2030 | 58        | User password                               | 0000 ...<br>9999 |   | U16  | 2   | RW  |

### Index 0x2030, Subindex 59 (Assignment PLC outputs 1)

| Index  | Sub-Index | Description          | Value | Meaning of value        | Type | Len | R/W |
|--------|-----------|----------------------|-------|-------------------------|------|-----|-----|
| 0x2030 | 59        | PLC output 1 (Pin 2) | 0     | Switchpoint S3          | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 1     | Switchpoint S4          | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 2     | Strobe (switch program) | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 3     | A0 (switch program)     | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 4     | A1 (switch program)     | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 5     | A2 (switch program)     | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 6     | A3 (switch program)     | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 7     | A4 (switch program)     | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 8     | Tare warning            | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 9     | Warning tool counter    | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 10    | Warning Total           | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 11    | OK sensor test          | U16  | 2   | RW  |
| 0x2030 | 59        | PLC output 1 (Pin 2) | 12    | Test operation simple   | U16  | 2   | RW  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>   | <b>Value</b> | <b>Meaning of value</b>    | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|----------------------|--------------|----------------------------|-------------|------------|------------|
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 13           | Test operation complex     | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 14           | Measurement running        | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 15           | Configuration operation    | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 16           | Acknowledgement alarm      | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 17           | Acknowledgement lock       | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 18           | Acknowledgement OK (green) | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 19           | Acknowledgement NOK (red)  | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 20           | NOK window 1               | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 21           | NOK window 2               | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 22           | NOK window 3               | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 23           | NOK window 4               | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 24           | NOK window 5               | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 25           | NOK window 6               | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 26           | NOK window 7               | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 27           | NOK window 8               | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 28           | NOK window 9               | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 29           | NOK window 10              | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 30           | NOK trapezoid window X 1   | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 31           | NOK trapezoid window X 3   | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 32           | NOK trapezoid window Y 1   | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 33           | NOK trapezoid window X 2   | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 34           | NOK threshold 1            | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 35           | NOK threshold 2            | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 36           | NOK threshold 3            | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 37           | NOK threshold 4            | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 38           | NOK envelope 1             | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 39           | NOK envelope 2             | U16         | 2          | RW         |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>   | <b>Value</b> | <b>Meaning of value</b>               | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|----------------------|--------------|---------------------------------------|-------------|------------|------------|
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 40           | NOK result math 1                     | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 41           | NOK result math 2                     | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 42           | NOK result math 3                     | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 43           | NOK result math 4                     | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 44           | NOK result math 5                     | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 45           | NOK result math 6                     | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 46           | NOK channel Y1                        | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 47           | NOK channel Y2                        | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 48           | NOK rotary switch 1                   | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 49           | NOK rotary switch 2                   | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 50           | PC logging active (OUT_PC_LOGGING)    | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 51           | Reference measurement                 | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 52           | A5 (switch program.) (only if 128 MP) | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 53           | A6 (switch program) (only if 128 MP)  | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 54           | OK channel Y1                         | U16         | 2          | RW         |
| <b>0x2030</b> | 59               | PLC output 1 (Pin 2) | 55           | OK channel Y2                         | U16         | 2          | RW         |

## Index 0x2030, Subindexes 60 to 81 (Assignment PLC outputs 2 to 23)

| Index  | Sub-Index | Description            | Value                 | Meaning of value | Type | Len | R/W |
|--------|-----------|------------------------|-----------------------|------------------|------|-----|-----|
| 0x2030 | 60        | PLC output 2 (Pin 6)   | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 61        | PLC output 3 (Pin 8)   | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 62        | PLC output 4 (Pin 9)   | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 63        | PLC output 5 (Pin 10)  | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 64        | PLC output 6 (Pin 11)  | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 65        | PLC output 7 (Pin 12)  | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 66        | PLC output 8 (Pin 13)  | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 67        | PLC output 9 (Pin 16)  | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 68        | PLC output 10 (Pin 17) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 69        | PLC output 11 (Pin 21) | See<br>subindex<br>59 |                  | U16  | 2   | RW  |
| 0x2030 | 70        | PLC output 12 (Pin 22) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 71        | PLC output 13 (Pin 23) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 72        | PLC output 14 (Pin 24) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 73        | PLC output 15 (Pin 25) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 74        | PLC output 16 (Pin 26) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 75        | PLC output 17 (Pin 27) | seesub<br>index 59    |                  | U16  | 2   | RW  |
| 0x2030 | 76        | PLC output 18 (Pin 28) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 77        | PLC output 19 (Pin 29) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 78        | PLC output 20 (Pin 30) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 79        | PLC output 21 (Pin 31) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 80        | PLC output 22 (Pin 32) | see<br>subindex 59    |                  | U16  | 2   | RW  |
| 0x2030 | 81        | PLC output 23 (Pin 33) | see<br>subindex 59    |                  | U16  | 2   | RW  |

## Index 0x2030, Subindexes 82 to 115

| Index  | Sub-Index | Description  | Value                   | Meaning of value  | Type   | Len | R/W |
|--------|-----------|--|-------------------------|---|--------|-----|-----|
| 0x2030 | 82        | Order sheet: Operator  | Michael_Mueller         |   | STR 64 | 64  | RW  |
| 0x2030 | 83        | Order sheet: Order number  | AN_123456               |   | STR 64 | 64  | RW  |
| 0x2030 | 84        | Order sheet: Batch   | BATCH_257-3             |   | STR 64 | 64  | RW  |
| 0x2030 | 85        | Order sheet: Component   | Cylinder_right          |   | STR 64 | 64  | RW  |
| 0x2030 | 86        | Order sheet: Serial number 1   | SN_123456789            |   | STR 64 | 64  | RW  |
| 0x2030 | 87        | Order sheet: Serial number 2   | SN_987654321            |   | STR 64 | 64  | RW  |
| 0x2030 | 88        | Order sheet: Shift number  | 1 ... 6                 |   | U16    | 2   | RW  |
| 0x2030 | 89        | Order sheet: Shift name Current shift  | Shiftname_Current_Shift |   | STR 64 | 64  | RW  |
| 0x2030 | 90        | Order sheet: Shift name Shift 1  | Shiftname_Shift1        |   | STR 64 | 64  | RW  |
| 0x2030 | 91        | Order sheet: Shift name Shift 2  | Shiftname_Shift2        |   | STR 64 | 64  | RW  |
| 0x2030 | 92        | Order sheet: Shift name Shift 3  | Shiftname_Shift3        |   | STR 64 | 64  | RW  |
| 0x2030 | 93        | Order sheet: Shift name Shift 4  | Shiftname_Shift4        |   | STR 64 | 64  | RW  |
| 0x2030 | 94        | Order sheet: Shift name Shift 5  | Shiftname_Shift5        |   | STR 64 | 64  | RW  |
| 0x2030 | 95        | Order sheet: Shift name Shift 6  | Shiftname_Shift6        |   | STR 64 | 64  | RW  |
| 0x2030 | 96        | Order sheet: Reset shift counter<br>Shift selection through writing the shift number | Shift number            | EVENT!<br>Writing the shift number clears the shift counter concerned | U16    | 2   | WO  |
| 0x2030 | 97        | Order sheet: Shift counter read-out quantity of current shift                        | 0 ... 4294967296        |   | U32    | 4   | RO  |
| 0x2030 | 98        | Order sheet: Shift counter read-out quantity of shift 1                              | 0 ... 4294967296        |   | U32    | 4   | RO  |
| 0x2030 | 99        | Order sheet: Shift counter read-out quantity of shift 2                              | 0 ... 4294967296        |   | U32    | 4   | RO  |
| 0x2030 | 100       | Order sheet: Shift counter read-out quantity of shift 3                              | 0 ... 4294967296        |   | U32    | 4   | RO  |
| 0x2030 | 101       | Order sheet: Shift counter read-out quantity of shift 4                              | 0 ... 4294967296        |   | U32    | 4   | RO  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>   | <b>Value</b>     | <b>Meaning of value</b>  | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|--|------------------|--|-------------|------------|------------|
| <b>0x2030</b> | 102              | Order sheet: Shift counter read-out quantity of shift 5            | 0 ... 4294967296 |  | U32         | 4          | RO         |
| <b>0x2030</b> | 103              | Order sheet: Shift counter read-out quantity of shift 6            | 0 ... 4294967296 |  | U32         | 4          | RO         |
| <b>0x2030</b> | 104              | Order sheet: Shift counter read-out quantity of current NOK counts | 0 ... 4294967296 |  | U32         | 4          | RO         |
| <b>0x2030</b> | 105              | Order sheet: Shift counter read-out quantity of NOK counts shift 1 | 0 ... 4294967296 |  | U32         | 4          | RO         |
| <b>0x2030</b> | 106              | Order sheet: Shift counter read-out quantity of NOK counts shift 2 | 0 ... 4294967296 |  | U32         | 4          | RO         |
| <b>0x2030</b> | 107              | Order sheet: Shift counter read-out quantity of NOK counts shift 3 | 0 ... 4294967296 |  | U32         | 4          | RO         |
| <b>0x2030</b> | 108              | Order sheet: Shift counter read-out quantity of NOK counts shift 4 | 0 ... 4294967296 |  | U32         | 4          | RO         |
| <b>0x2030</b> | 109              | Order sheet: Shift counter read-out quantity of NOK counts shift 5 | 0 ... 4294967296 |  | U32         | 4          | RO         |
| <b>0x2030</b> | 110              | Order sheet: Shift counter read-out quantity of NOK counts shift 6 | 0 ... 4294967296 |  | U32         | 4          | RO         |
| <b>0x2030</b> | 111              | Acknowledgement function on/off                                    | 0<br>1           | Acknowledgement function off<br>Acknowledgement function on      | U16         | 2          | RW         |
| <b>0x2030</b> | 112              | Acknowledgement function:<br>Acknowledge OK parts on/off           | 0<br>1           | Not active<br>User has to confirm OK parts (F-Key or PLC input)  | U16         | 2          | RW         |
| <b>0x2030</b> | 113              | Acknowledgement function:<br>Acknowledge NOK parts on/off          | 0<br>1           | Not active<br>User has to confirm NOK parts (F-Key or PLC input) | U16         | 2          | RW         |
| <b>0x2030</b> | 114              | Acknowledgement function:<br>Buzzer volume                         | 0 ... 10         | 10: max. volume  | U16         | 2          |            |
| <b>0x2030</b> | 115              | Update display (refresh view)                                      | <i>Event!</i>    | Writing an arbitrary byte initiates action                       | U8          |            |            |

### 7.1.4 Communication: Change menu, display update, fault indication (Index 0x2032)

| Index         | Sub-Index | Description                                       | Value         | Meaning of value   | Type | Len | R/W |
|---------------|-----------|---|---------------|--|------|-----|-----|
| <b>0x2032</b> | 0         | Number of subindices                              | 12            |  | U8   | 1   | RO  |
| <b>0x2032</b> | 1 - 9     | Reserved  | -             | -  | X    | X   | X   |
| <b>0x2032</b> | 10        | Go to menu  | 0<br>1<br>2   | Meas. Menu<br>Graphical test menu<br>Complex test menu<br>EVENT! and entry | U16  | 2   | WO  |
| <b>0x2032</b> | 11        | Initiate update of the LCD display                | <i>EVENT!</i> | Writing an arbitrary byte initiates action                                 | U8   | 1   | WO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000001    | PREFIX addressing fault  | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000002    | Enquiry received in Device mode  | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000004    | Blockcheck error   | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000008    | Command fault  | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000010    | Parameter error  | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000020    | Timeout Receive Timer  | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000040    | Timeout Response Timer   | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000080    | Invalid ! or ?   | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000100    | Invalid configuration  | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000200    | Scaling fault  | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000400    | No valid measurements are available  | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00000800    | A/D converter overdriven   | U32  | 4   | RO  |
| <b>0x2032</b> | 12        | Fault status of the internal serial communication | 0x00001000    | Fault reading from EEPROM  | U32  | 4   | RO  |

| Index  | Sub-Index | Description                                       | Value      | Meaning of value  | Type | Len | R/W |
|--------|-----------|---|------------|---|------|-----|-----|
| 0x2032 | 12        | Fault status of the internal serial communication | 0x00002000 | Overdrive resulting from scaling  | U32  | 4   | RO  |
| 0x2032 | 12        | Fault status of the internal serial communication | 0x00004000 | Reading out the measurement curve was interrupted by the beginning of a new measurement | U32  | 4   | RO  |
| 0x2032 | 12        | Fault status of the internal serial communication | 0x00008000 | Invalid envelope limits   | U32  | 4   | RO  |
| 0x2032 | 12        | Fault status of the internal serial communication | 0x00010000 | The calibration has not worked  | U32  | 4   | RO  |

#### 7.1.5 Minimal setup menu (Index 0x2033)

| Index  | Sub-Index | Description                                  | Value               | Meaning of value   | Type   | Len | R/W |
|--------|-----------|--|---------------------|--|--------|-----|-----|
| 0x2033 | 0         | Number of subindices                         | 13                  |  | U8     | 1   | RO  |
| 0x2033 | 1 - 9     | Reserved slots                               | -                   | -  | X      | X   | X   |
| 0x2033 | 10        | Set program number                           | 0 ... 31<br>0...127 | In the standard device<br>In the corresponding device version  | U16    | 2   | RW  |
| 0x2033 | 11        | Program name                                 | Program name        |  | STR 20 | 20  | RW  |
| 0x2033 | 12        | Reset statistics of measurement program      | 0 ... 31<br>0...127 | In the standard device<br>In the corresponding device version<br>EVENT! Selection through writing the program number | U16    | 2   | WO  |
| 0x2033 | 13        | Reset statistics in all measurement programs | EVENT!              | Writing an arbitrary byte initiates action   | U8     | 1   | WO  |

#### 7.1.6 General channel settings (Index 0x2034)

| Index  | Sub-Index | Description   | Value  | Meaning of value   | Type | Len | R/W |
|--------|-----------|---|--|--|------|-----|-----|
| 0x2034 | 0         | Number of subindices  | 34   |  | U8   | 1   | RO  |
| 0x2034 | 1 - 9     | Reserved slots  | -  | -  |      |     | X   |
| 0x2034 | 10        | Channel settings channel X<br><br><b>Note:</b> First make the settings in indices 10, 11, 12, then initiate with subindex 13! | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9 | Terminals:<br>A, strain gauge<br>A, Potentiometer<br>A, standard signal<br>B, strain gauge<br>B, Potentiometer<br>B, standard signal<br>C, Incr. TTL<br>C, Incr. sinus 1Vpp<br>C, Incr. sinus 11 uApp<br>D, strain gauge | U16  | 2   | RW  |

| Index         | Sub-Index | Description  | Value  | Meaning of value   | Type | Len | R/W |
|---------------|-----------|--|--|--|------|-----|-----|
|               |           |  | 10<br>11<br>12<br>13<br>14<br>15<br>16<br>17<br>18   | D, Potentiometer<br>D, standard signal<br>D, Incr. TTL<br>E, resistance<br>F, Piezo<br>time<br>reserved<br>C, SSI<br>C, EnDat  |      |     |     |
| <b>0x2034</b> | 11        | Channel settings channel Y1<br><br><b>Note:</b> First make the settings in indices 10, 11, 12, then initiate with subindex 13! | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9<br>10<br>11<br>12<br>13<br>14<br>15<br>16<br>17<br>18 | Terminals:<br>A, strain gauge<br>A, Potentiometer<br>A, standard signal<br>B, strain gauge<br>B, Potentiometer<br>B, standard signal<br>C, Incr. TTL<br>C, Incr.sinus 1Vpp<br>C, Incr. sinus 11 uApp<br>D, strain gauge<br>D, Potentiometer<br>D, standard signal<br>D, Incr. TTL<br>E, resistance<br>F, Piezo<br>time<br>reserved<br>C, SSI<br>C, EnDat | U16  | 2   | RW  |
| <b>0x2034</b> | 12        | Channel settings channel Y2<br><br><b>Note:</b> First make the settings in indices 10, 11, 12, then initiate with subindex 13! | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9<br>10<br>11<br>12<br>13<br>14<br>15<br>16<br>17<br>18 | Terminals:<br>A, strain gauge<br>A, Potentiometer<br>A, standard signal<br>B, strain gauge<br>B, Potentiometer<br>B, standard signal<br>C, Incr. TTL<br>C, Incr. sinus 1Vpp<br>C, Incr. sinus 11 uApp<br>D, strain gauge<br>D, Potentiometer<br>D, standard signal<br>D, Incr. TTL<br>E, resistance<br>F, Piezo<br>Time<br>off<br>C, SSI<br>C, EnDat     | U16  | 2   | RW  |
| <b>0x2034</b> | 13        | Accept channel settings  | <i>Event!</i>  | The settings from indices 10, 11, 12 are being stored.<br>Writing an arbitrary byte initiates action.  | U8   | 1   | WO  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>  | <b>Value</b>                              | <b>Meaning of value</b>  | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---|---|--|-------------|------------|------------|
| <b>0x2034</b> | 14               | Filter channel X<br><br><b>Note:</b> Entry is not available for the channel settings "Time" and "Incremental".              | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8 | Off<br>5 Hz filter<br>10 Hz filter<br>25 Hz filter<br>50 Hz filter<br>100 Hz filter<br>200 Hz filter<br>400 Hz filter<br>800 Hz filter | U16         | 2          | RW         |
| <b>0x2034</b> | 15               | Filter channel Y1<br><br><b>Note:</b> Entry is not available for the channel settings "Time" and "Incremental".             | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8 | Off<br>5 Hz filter<br>10 Hz filter<br>25 Hz filter<br>50 Hz filter<br>100 Hz filter<br>200 Hz filter<br>400 Hz filter<br>800 Hz filter | U16         | 2          | RW         |
| <b>0x2034</b> | 16               | Filter channel Y2<br><br><b>Note:</b> Entry is not available for the channel settings "Time" and "Incremental"              | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8 | Off<br>5 Hz filter<br>10 Hz filter<br>25 Hz filter<br>50 Hz filter<br>100 Hz filter<br>200 Hz filter<br>400 Hz filter<br>800 Hz filter | U16         | 2          | RW         |
| <b>0x2034</b> | 17               | Transmitter supply channel X<br><br><b>Note:</b> Entry is not available for the channel settings "Piezo" and "Resistance".  | 0<br>1                                    | Transmitter supply off<br>Transmitter supply on  | U16         | 2          | RW         |
| <b>0x2034</b> | 18               | Transmitter supply channel Y1<br><br><b>Note:</b> Entry is not available for the channel settings "Piezo" and "Resistance". | 0<br>1                                    | Transmitter supply off<br>Transmitter supply on  | U16         | 2          | RW         |
| <b>0x2034</b> | 19               | Transmitter supply channel Y2<br><br><b>Note:</b> Entry is not available for the channel settings "Piezo" and "Resistance". | 0<br>1                                    | Transmitter supply off<br>Transmitter supply on  | U16         | 2          | RW         |
| <b>0x2034</b> | 20               | Set unit channel X<br><br><b>Note:</b> Entry is not available for the   | 0<br>1<br>2<br>3                          | User defined unit 1<br>User defined unit 2<br>User defined unit 3<br>mm  | U16         | 2          | RW         |

| Index         | Sub-Index | Description   | Value  | Meaning of value  | Type  | Len | R/W |
|---------------|-----------|---|--|---|-------|-----|-----|
|               |           | channel settings "Time" and "Resistance".   | 4<br>5<br>6<br>7<br>8<br>9<br>10<br>11<br>12                     | N<br>kN<br>Nm<br>Ncm<br>Grd<br>Bar<br>V<br>s<br>ms  |       |     |     |
| <b>0x2034</b> | 21        | Set unit channel Y1<br><br><b>Note:</b> Entry is not available for the channel settings "Time" and "Resistance".  | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9<br>10<br>11<br>12 | User defined unit 1<br>User defined unit 2<br>User defined unit 3<br>mm<br>N<br>kN<br>Nm<br>Ncm<br>Grd<br>Bar<br>V<br>s<br>ms | U16   | 2   | RW  |
| <b>0x2034</b> | 22        | Set unit channel Y2<br><br><b>Note:</b> Entry is not available for the channel settings "Off", "Time" and "Resistance".   | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9<br>10<br>11<br>12 | User defined unit 1<br>User defined unit 2<br>User defined unit 3<br>mm<br>N<br>kN<br>Nm<br>Ncm<br>Grd<br>Bar<br>V<br>s<br>ms | U16   | 2   | RW  |
| <b>0x2034</b> | 23        | Set user defined unit 1   | <i>abcd</i>  |   | STR 4 | 4   | RW  |
| <b>0x2034</b> | 24        | Set user defined unit 2   | <i>abcd</i>  |   | STR 4 | 4   | RW  |
| <b>0x2034</b> | 25        | Set user defined unit 3   | <i>ijkl</i>  |   | STR 4 | 4   | RW  |
| <b>0x2034</b> | 26        | Take the tare value for channel X and return the measured value<br><br><b>Note:</b> Entry is not available for the channel settings "Time", "Incremental" and "Resistance". | <i>EVENT!</i>  |   | FLT   | 4   | RO  |
| <b>0x2034</b> | 27        | Take the tare value for channel Y1 and  | <i>EVENT!</i>  |   | FLT   | 4   | RO  |

| Index         | Sub-Index | Description  | Value         | Meaning of value   | Type | Len | R/W |
|---------------|-----------|--|---------------|--|------|-----|-----|
|               |           | return the measured value<br><br><b>Note:</b> Entry is not available for the channel settings "Time", "Incremental" and "Resistance".  |               |  |      |     |     |
| <b>0x2034</b> | 28        | Take the tare value for channel Y2 and return the measured value<br><br><b>Note:</b> Entry is not available for the channel settings "Time", "Incremental" and "Resistance". | <i>EVENT!</i> |  | FLT  | 4   | RO  |
| <b>0x2034</b> | 29        | Channel to be scaled   | 0<br>1<br>2   | Channel X<br>Channel Y1<br>Channel Y2  | U 16 | 2   | WO  |
| <b>0x2034</b> | 30        | Lower scale value  |               | Concerns the channel selected under subindex 29  | FLT  | 4   | RW  |
| <b>0x2034</b> | 31        | Upper scale value  |               | Concerns the channel selected under subindex 29  | FLT  | 4   | RW  |
| <b>0x2034</b> | 32        | Lower calibration value  |               | Concerns the channel selected under subindex 29  | FLT  | 4   | RW  |
| <b>0x2034</b> | 33        | Upper calibration value  |               | Concerns the channel selected under subindex 29  | FLT  | 4   | RW  |
| <b>0x2034</b> | 34        | Perform scaling (as per subindex 29 ... 33)  | <i>EVENT</i>  | Entry is not available for the channel settings "Off", "Time", "Incremental" and "Resistance". | U8   | 1   | WO  |

### 7.1.7 Channel settings “Potentiometer” (Index 0x2035)

| Index         | Sub-Index | Description                         | Value  | Meaning of value                  | Type | Len | R/W |
|---------------|-----------|-------------------------------------|--------|-----------------------------------|------|-----|-----|
| <b>0x2035</b> | 0         | Number of subindices                | 12     |                                   | U8   | 1   | RO  |
| <b>0x2035</b> | 1 - 9     | Reserved                            | -      | -                                 |      |     | X   |
| <b>0x2035</b> | 10        | Potentiometer excitation channel X  | 0<br>1 | 5 V excitation<br>10 V excitation | U16  | 2   | RW  |
| <b>0x2035</b> | 11        | Potentiometer excitation channel Y1 | 0<br>1 | 5 V excitation<br>10 V excitation | U16  | 2   | RW  |

| Index  | Sub-Index | Description                         | Value  | Meaning of value                  | Type | Len | R/W |
|--------|-----------|-------------------------------------|--------|-----------------------------------|------|-----|-----|
| 0x2035 | 12        | Potentiometer excitation channel Y2 | 0<br>1 | 5 V excitation<br>10 V excitation | U16  | 2   | RW  |

## 7.1.8 Channel settings “Standard signal” (Index 0x2036)

| Index  | Sub-Index | Description                      | Value  | Meaning of value                    | Type | Len | R/W |
|--------|-----------|----------------------------------|--------|-------------------------------------|------|-----|-----|
| 0x2036 | 0         | Number of subindices             | 12     |                                     | U8   | 1   | RO  |
| 0x2036 | 1 - 9     | Reserved                         | -      | -                                   |      |     | X   |
| 0x2036 | 10        | Standard signal input channel X  | 0<br>1 | 5 V input range<br>10 V input range | U16  | 2   | RW  |
| 0x2036 | 11        | Standard signal input channel Y1 | 0<br>1 | 5 V input range<br>10 V input range | U16  | 2   | RW  |
| 0x2036 | 12        | Standard signal input channel Y2 | 0<br>1 | 5 V input range<br>10 V input range | U16  | 2   | RW  |

## 7.1.9 Channel settings “Strain gauge” (Index 0x2037)

| Index  | Sub-Index | Description                         | Value                      | Meaning of value   | Type | Len | R/W |
|--------|-----------|-------------------------------------|----------------------------|--|------|-----|-----|
| 0x2037 | 0         | Number of subindices                | 24                         |  | U8   | 1   | RO  |
| 0x2037 | 1 - 9     | Reserved                            | -                          | -  |      |     | X   |
| 0x2037 | 10        | Strain gauge excitation channel X   | 0<br>1<br>2                | 2.5 V excitation<br>5 V excitation<br>10 V excitation  | U16  | 2   | RW  |
| 0x2037 | 11        | Strain gauge excitation channel Y1  | 0<br>1<br>2                | 2.5 V excitation<br>5 V excitation<br>10 V excitation  | U16  | 2   | RW  |
| 0x2037 | 12        | Strain gauge excitation channel Y2  | 0<br>1<br>2                | 2.5 V excitation<br>5 V excitation<br>10 V excitation  | U16  | 2   | RW  |
| 0x2037 | 13        | Strain gauge input range channel X  | 0<br>1<br>2<br>3<br>4<br>5 | 1 mV/V input range<br>2 mV/V input range<br>4 mV/V input range<br>10 mV/V input range<br>20 mV/V input range<br>40 mV/V input range (40 mV/V are not allowed at 10 V excitation) | U16  | 2   | RW  |
| 0x2037 | 14        | Strain gauge input range channel Y1 | 0<br>1<br>2<br>3<br>4<br>5 | 1 mV/V input range<br>2 mV/V input range<br>4 mV/V input range<br>10 mV/V input range<br>20 mV/V input range<br>40 mV/V input range (40 mV/V are not allowed at 10 V excitation) | U16  | 2   | RW  |
| 0x2037 | 15        | Strain gauge input range channel Y2 | 0<br>1<br>2                | 1 mV/V input range<br>2 mV/V input range<br>4 mV/V input range   | U16  | 2   | RW  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                    | <b>Value</b>               | <b>Meaning of value</b>  | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---------------------------------------|----------------------------|--|-------------|------------|------------|
|               |                  |                                       | 3<br>4<br>5                | 10 mV/V input range<br>20 mV/V input range<br>40 mV/V input range (40 mV/V are not allowed at 10 V excitation) |             |            |            |
| <b>0x2037</b> | 16               | Strain gauge sensitivity channel X    | 0.01 ... 100.0             | IEEE754 Float  | FLT         | 4          | RW         |
| <b>0x2037</b> | 17               | Strain gauge sensitivity channel Y1   | 0.01 ... 100.0             | IEEE754 Float  | FLT         | 4          | RW         |
| <b>0x2037</b> | 18               | Strain gauge sensitivity channel Y2   | 0.01 ... 100.0             | IEEE754 Float  | FLT         | 4          | RW         |
| <b>0x2037</b> | 19               | Request strain gauge level channel X  | 0.01 ... 100.0             | IEEE754 Float  | FLT         | 4          | RO         |
| <b>0x2037</b> | 20               | Request strain gauge level channel Y1 | 0.01 ... 100.0             | IEEE754 Float  | FLT         | 4          | RO         |
| <b>0x2037</b> | 21               | Request strain gauge level channel Y2 | 0.01 ... 100.0             | IEEE754 Float  | FLT         | 4          | RO         |
| <b>0x2037</b> | 22               | Strain gauge shunt channel X          | 0<br>1<br>2<br>3<br>4<br>5 | OFF<br>10 kOhm<br>59 kOHM<br>80 kOHM<br>100 kOHM<br>300 kOHM   | U16         | 2          | RW         |
| <b>0x2037</b> | 23               | Strain gauge shunt channel Y1         | 0<br>1<br>2<br>3<br>4<br>5 | OFF<br>10 kOhm<br>59 kOHM<br>80 kOHM<br>100 kOHM<br>300 kOHM   | U16         | 2          | RW         |
| <b>0x2037</b> | 24               | Strain gauge shunt channel Y2         | 0<br>1<br>2<br>3<br>4<br>5 | OFF<br>10 kOhm<br>59 kOHM<br>80 kOHM<br>100 kOHM<br>300 kOHM   | U16         | 2          | RW         |

### 7.1.10 Channel settings “Resistance” (Index 0x2038)

| Index         | Sub-Index | Description                       | Value       | Meaning of value                                 | Type | Len | R/W |
|---------------|-----------|-----------------------------------|-------------|--|------|-----|-----|
| <b>0x2038</b> | 0         | Number of subindices              | 12          |  | U8   | 1   | RO  |
| <b>0x2038</b> | 1 - 9     | Reserved                          | -           | -  |      |     | X   |
| <b>0x2038</b> | 10        | Resistance input range channel X  | 0<br>1<br>2 | 200 mOhm range<br>2 kOhm range<br>100 kOhm range | U16  | 2   | RW  |
| <b>0x2038</b> | 11        | Resistance input range channel Y1 | 0<br>1<br>2 | 200 mOhm range<br>2 kOhm range<br>100 kOhm range | U16  | 2   | RW  |
| <b>0x2038</b> | 12        | Resistance input range channel Y2 | 0<br>1<br>2 | 200 mOhm range<br>2 kOhm range<br>100 kOhm range | U16  | 2   | RW  |

### 7.1.11 Channel settings “Piezo” (Index 0x2039)

| Index         | Sub-Index | Description                  | Value  | Meaning of value   | Type | Len | R/W |
|---------------|-----------|------------------------------|--|--|------|-----|-----|
| <b>0x2039</b> | 0         | Number of subindices         | 15   |  | U8   | 1   | RO  |
| <b>0x2039</b> | 1 - 9     | Reserved                     | -  | -  |      |     | X   |
| <b>0x2039</b> | 10        | Piezo input range channel X  | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9 | 1nC range<br>2nC range<br>5nC range<br>10nC range<br>20nC range<br>40nC range<br>80nC range<br>200nC range<br>400nC range<br>1uC range | U16  | 2   | RW  |
| <b>0x2039</b> | 11        | Piezo input range channel Y1 | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9 | 1nC range<br>2nC range<br>5nC range<br>10nC range<br>20nC range<br>40nC range<br>80nC range<br>200nC range<br>400nC range<br>1uC range | U16  | 2   | RW  |
| <b>0x2039</b> | 12        | Piezo input range channel Y2 | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9 | 1nC range<br>2nC range<br>5nC range<br>10nC range<br>20nC range<br>40nC range<br>80nC range<br>200nC range<br>400nC range<br>1uC range | U16  | 2   | RW  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                   | <b>Value</b> | <b>Meaning of value</b>                                       | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|--------------------------------------|--------------|---|-------------|------------|------------|
| <b>0x2039</b> | 13               | Piezo short-circuit on/to channel X  | 0<br>1       | Do not short-circuit piezo input<br>Short-circuit piezo input | U16         | 2          | WO         |
| <b>0x2039</b> | 14               | Piezo short-circuit on/to channel Y1 | 0<br>1       | Do not short-circuit piezo input<br>Short-circuit piezo input | U16         | 2          | WO         |
| <b>0x2039</b> | 15               | Piezo short-circuit on/to channel Y2 | 0<br>1       | Do not short-circuit piezo input<br>Short-circuit piezo input | U16         | 2          | WO         |

### 7.1.12 Channel settings “Incremental” (Index 0x2040)

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                                  | <b>Value</b>                             | <b>Meaning of value</b>  | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---|--|--|-------------|------------|------------|
| <b>0x2040</b> | 0                | Number of subindices                                | 39                                       |  | U8          | 1          | RO         |
| <b>0x2040</b> | 1 - 9            | Reserved  | -  | -  |             |            | X          |
| <b>0x2040</b> | 10               | Incremental reference mark channel X                | 0<br>1<br>2                              | reference mark off<br>reference mark on<br>reference mark distance coded | U16         | 2          | RW         |
| <b>0x2040</b> | 11               | Incremental reference mark channel Y1               | 0<br>1<br>2                              | reference mark off<br>reference mark on<br>reference mark distance coded | U16         | 2          | RW         |
| <b>0x2040</b> | 12               | Incremental reference mark channel Y2               | 0<br>1<br>2                              | reference mark off<br>reference mark on<br>reference mark distance coded | U16         | 2          | RW         |
| <b>0x2040</b> | 13               | Incremental set value at reference mark channel X   | <i>between - 9999999.0 and 9999999.0</i> | Float value,<br>Float according to IEEE754                               | FLT         | 4          | RW         |
| <b>0x2040</b> | 14               | Incremental set value at reference mark channel Y1  | <i>between - 9999999.0 and 9999999.0</i> | Float value,<br>Float according to IEEE754                               | FLT         | 4          | RW         |
| <b>0x2040</b> | 15               | Incremental set value at reference mark channel Y2  | <i>between - 9999999.0 and 9999999.0</i> | Float value,<br>Float according to IEEE754                               | FLT         | 4          | RW         |
| <b>0x2040</b> | 16               | Incremental reference measurement on/off channel X  | 0<br>1                                   | off<br>on  | U16         | 2          | RW         |
| <b>0x2040</b> | 17               | Incremental reference measurement on/off channel Y1 | 0<br>1                                   | off<br>on  | U16         | 2          | RW         |
| <b>0x2040</b> | 18               | Incremental reference measurement on/off channel Y2 | 0<br>1                                   | off<br>on  | U16         | 2          | RW         |

| Index         | Sub-Index | Description  | Value   | Meaning of value                           | Type | Len | R/W |
|---------------|-----------|--|---|--|------|-----|-----|
| <b>0x2040</b> | 19        | Incremental<br>Set to value at start<br>off/on<br>channel X  | 0<br>1  | on<br>off                                  | U16  | 2   | RW  |
| <b>0x2040</b> | 20        | Incremental<br>Set to value at start<br>off/on<br>channel Y1 | 0<br>1  | on<br>off                                  | U16  | 2   | RW  |
| <b>0x2040</b> | 21        | Incremental<br>Set to value at start<br>off/on<br>channel Y2 | 0<br>1  | on<br>off                                  | U16  | 2   | RW  |
| <b>0x2040</b> | 22        | Incremental<br>set value at start<br>channel X               | <i>between</i><br>- 9999999.0<br>and<br>9999999.0 | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2040</b> | 23        | Incremental<br>set value at start<br>channel Y1              | <i>between</i><br>- 9999999.0<br>and<br>9999999.0 | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2040</b> | 24        | Incremental<br>set value at start<br>channel Y2              | <i>between</i><br>- 9999999.0<br>and<br>9999999.0 | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2040</b> | 25        | Incremental<br>nominal increment<br>channel X                | <i>between</i><br>- 9999999.0<br>and<br>9999999.0 | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2040</b> | 26        | Incremental<br>nominal increment<br>channel Y1               | <i>between</i><br>- 9999999.0<br>and<br>9999999.0 | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2040</b> | 27        | Incremental<br>nominal increment<br>channel Y2               | <i>between</i><br>- 9999999.0<br>and<br>9999999.0 | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2040</b> | 28        | Incremental grating<br>period channel X                      | <i>between</i><br>- 9999999.0<br>and<br>9999999.0 | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2040</b> | 29        | Incremental grating<br>period channel Y1                     | <i>between</i><br>- 9999999.0<br>and<br>9999999.0 | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2040</b> | 30        | Incremental grating<br>period channel Y2                     | <i>between</i><br>- 9999999.0<br>and<br>9999999.0 | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2040</b> | 31        | Incremental<br>interpolation<br>channel X                    | <i>between</i><br>-1 and<br>65000                 | Integer value                              | U16  | 2   | RW  |
| <b>0x2040</b> | 32        | Incremental<br>interpolation<br>channel Y1                   | <i>between</i><br>-1 and<br>65000                 | Integer value                              | U16  | 2   | RW  |

| Index         | Sub-Index | Description  | Value                       | Meaning of value     | Type | Len | R/W |
|---------------|-----------|--|-----------------------------|----------------------|------|-----|-----|
| <b>0x2040</b> | 33        | Incremental interpolation channel Y2               | <i>between -1 and 65000</i> | Integer value        | U16  | 2   | RW  |
| <b>0x2040</b> | 34        | Incremental termination resistor off/on channel X  | 0<br>1                      | off<br>on            | U16  | 2   | RW  |
| <b>0x2040</b> | 35        | Incremental termination resistor off/on channel Y1 | 0<br>1                      | off<br>on            | U16  | 2   | RW  |
| <b>0x2040</b> | 36        | Incremental termination resistor off/on channel Y2 | 0<br>1                      | off<br>on            | U16  | 2   | RW  |
| <b>0x2040</b> | 37        | Direction of counting positive/negative channel X  | 0<br>1                      | positive<br>negative | U16  | 2   | RW  |
| <b>0x2040</b> | 38        | Direction of counting positive/negative channel X1 | 0<br>1                      | positive<br>negative | U16  | 2   | RW  |
| <b>0x2040</b> | 39        | Direction of counting positive/negative channel Y2 | 0<br>1                      | positive<br>negative | U16  | 2   | RW  |

### 7.1.13 Channel settings “SSI” (Index 0x2041)

| Index         | Sub-Index | Description   | Value       | Meaning of value   | Type | Len | R/W |
|---------------|-----------|---|-------------|--|------|-----|-----|
| <b>0x2041</b> | 0         | Number of subindices  | 39          |  | U8   | 1   | RO  |
| <b>0x2041</b> | 1 .. 9    | Reserved  | -           | -  |      |     | X   |
| <b>0x2041</b> | 10        | SSI sensor type channel X<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.  | 0<br>1<br>2 | Displacement sensor<br>Singleturn encoder<br>Multiturn encoder | U16  | 2   | RW  |
| <b>0x2041</b> | 11        | SSI sensor type channel Y1<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39. | 0<br>1<br>2 | Displacement sensor<br>Singleturn encoder<br>Multiturn encoder | U16  | 2   | RW  |
| <b>0x2041</b> | 12        | SSI sensor type channel Y2<br><br><b>Note:</b> At the end, settings must be initiated through a                                   | 0<br>1<br>2 | Displacement sensor<br>Singleturn encoder<br>Multiturn encoder | U16  | 2   | RW  |

| Index         | Sub-Index | Description  | Value  | Meaning of value    | Type | Len | R/W |
|---------------|-----------|--|--------|---------------------|------|-----|-----|
|               |           | write access to indices 37/38/39.  |        |                     |      |     |     |
| <b>0x2041</b> | 13        | SSI code channel X<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.  | 0<br>1 | Binary<br>Gray code | U16  | 2   | RW  |
| <b>0x2041</b> | 14        | SSI code channel Y1<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.   | 0<br>1 | Binary<br>Gray code | U16  | 2   | RW  |
| <b>0x2041</b> | 15        | SSI code channel Y2<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.   | 0<br>1 | Binary<br>Gray code | U16  | 2   | RW  |
| <b>0x2041</b> | 16        | SSI format channel X<br><br><b>Note:</b> Only permitted for multturn angle sensor! At the end, settings must be initiated through a write access to indices 37/38/39.  | 0<br>1 | Right aligned Tree  | U16  | 2   | RW  |
| <b>0x2041</b> | 17        | SSI format channel Y1<br><br><b>Note:</b> Only permitted for multturn angle sensor! At the end, settings must be initiated through a write access to indices 37/38/39. | 0<br>1 | Right aligned Tree  | U16  | 2   | RW  |
| <b>0x2041</b> | 18        | SSI format channel Y2<br><br><b>Note:</b> Only permitted for multturn angle sensor! At the end, settings must be   | 0<br>1 | Right aligned Tree  | U16  | 2   | RW  |

| Index         | Sub-Index | Description   | Value                                    | Meaning of value                           | Type | Len | R/W |
|---------------|-----------|---|--|--|------|-----|-----|
|               |           | initiated through a write access to indices 37/38/39.   |  |  |      |     |     |
| <b>0x2041</b> | 19        | SSI parity channel X<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.           | 0<br>1                                   | off<br>even                                | U16  | 2   | RW  |
| <b>0x2041</b> | 20        | SSI parity channel Y1<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.          | 0<br>1                                   | off<br>even                                | U16  | 2   | RW  |
| <b>0x2041</b> | 21        | SSI parity channel Y2<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.          | 0<br>1                                   | off<br>even                                | U16  | 2   | RW  |
| <b>0x2041</b> | 22        | SSI clock frequency channel X<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.  | 0<br>1<br>2                              | 100 kHz<br>200 kHz<br>1 MHz                | U16  | 2   | RW  |
| <b>0x2041</b> | 23        | SSI clock frequency channel Y1<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39. | 0<br>1<br>2                              | 100 kHz<br>200 kHz<br>1 MHz                | U16  | 2   | RW  |
| <b>0x2041</b> | 24        | SSI clock frequency channel Y2<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39. | 0<br>1<br>2                              | 100 kHz<br>200 kHz<br>1 MHz                | U16  | 2   | RW  |
| <b>0x2041</b> | 25        | SSI resolution channel X  | <i>between - 9999999.0 and 9999999.0</i> | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |

| Index         | Sub-Index | Description   | Value                                    | Meaning of value                           | Type | Len | R/W |
|---------------|-----------|---|--|--|------|-----|-----|
|               |           | <b>Note:</b> Only permitted for displacement sensors! At the end, settings must be initiated through a write access to indices 37/38/39.                                  |  |  |      |     |     |
| <b>0x2041</b> | 26        | SSI resolution channel Y1<br><br><b>Note:</b> Only permitted for displacement sensors! At the end, settings must be initiated through a write access to indices 37/38/39. | <i>between - 9999999.0 and 9999999.0</i> | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2041</b> | 27        | SSI resolution channel Y2<br><br><b>Note:</b> Only permitted for displacement sensors! At the end, settings must be initiated through a write access to indices 37/38/39. | <i>between - 9999999.0 and 9999999.0</i> | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2041</b> | 28        | SSI total number of bits channel X<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.                                 | 0 ... 48                                 | Integer value                              | U16  | 2   | RW  |
| <b>0x2041</b> | 29        | SSI total number of bits channel Y1<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.                                | 0 ... 48                                 | Integer value                              | U16  | 2   | RW  |
| <b>0x2041</b> | 30        | SSI total number of bits channel Y2<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.                                | 0 ... 48                                 | Integer value                              | U16  | 2   | RW  |

| Index         | Sub-Index | Description   | Value    | Meaning of value | Type | Len | R/W |
|---------------|-----------|---|----------|------------------|------|-----|-----|
| <b>0x2041</b> | 31        | SSI bit number angle singleturn or displacement channel X<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.  | 0 ... 32 | Integer value    | U16  | 2   | RW  |
| <b>0x2041</b> | 32        | SSI bit number angle singleturn or displacement channel Y1<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39. | 0 ... 32 | Integer value    | U16  | 2   | RW  |
| <b>0x2041</b> | 33        | SSI bit number angle singleturn or displacement channel Y2<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39. | 0 ... 32 | Integer value    | U16  | 2   | RW  |
| <b>0x2041</b> | 34        | SSI bit number rotations for multiturn angle channel X<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.     | 0 ... 32 | Integer value    | U16  | 2   | RW  |
| <b>0x2041</b> | 35        | SSI bit number rotations for multiturn angle channel Y1<br><br><b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39.    | 0 ... 32 | Integer value    | U16  | 2   | RW  |
| <b>0x2041</b> | 36        | SSI bit number rotations for multiturn angle channel Y2   | 0 ... 32 | Integer value    | U16  | 2   | RW  |

| Index         | Sub-Index | Description   | Value         | Meaning of value                           | Type | Len | R/W |
|---------------|-----------|---|---------------|--|------|-----|-----|
|               |           | <b>Note:</b> At the end, settings must be initiated through a write access to indices 37/38/39. |               |  |      |     |     |
| <b>0x2041</b> | 37        | Check & initiate SSI settings channel X   | <i>EVENT!</i> | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| <b>0x2041</b> | 38        | Check & initiate SSI settings channel Y1  | <i>EVENT!</i> | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| <b>0x2041</b> | 39        | Check & initiate SSI settings channel Y2  | <i>EVENT!</i> | Writing an arbitrary byte initiates action | U8   | 1   | WO  |

### 7.1.14 Channel settings “EnDat” (Index 0x2042)

| Index  | Sub-Index | Description   | Value            | Meaning of value                           | Type | Len | R/W |
|--------|-----------|---|------------------|--|------|-----|-----|
| 0x2042 | 0         | Number of subindices  | 57               |  | U8   | 1   | RO  |
| 0x2042 | 1 .. 9    | Reserved  | -                | -  |      |     | X   |
| 0x2042 | 10        | Read-out EnDat sensor data channel X<br><br><b>Note:</b> At the end, settings must be initiated through a write access to subindex 16.  | EVENT!           | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2042 | 11        | Read-out EnDat sensor data channel Y1<br><br><b>Note:</b> At the end, settings must be initiated through a write access to subindex 17. | EVENT!           | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2042 | 12        | Read-out EnDat sensor data channel Y2<br><br><b>Note:</b> At the end, settings must be initiated through a write access to subindex 18. | EVENT!           | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2042 | 13        | EnDat clock frequency channel X<br><br><b>Note:</b> At the end, settings must be initiated through a write access to subindex 16.       | 0<br>1<br>2<br>3 | 100k Hz<br>200 kHz<br>1 MHz<br>2 MHz       | U16  | 2   | RW  |
| 0x2042 | 14        | EnDat clock frequency channel Y1<br><br><b>Note:</b> At the end, settings must be initiated through a write access to subindex 17.      | 0<br>1<br>2<br>3 | 100k Hz<br>200 kHz<br>1 MHz<br>2 MHz       | U16  | 2   | RW  |
| 0x2042 | 15        | EnDat clock frequency channel Y2  | 0<br>1<br>2<br>3 | 100k Hz<br>200 kHz<br>1 MHz<br>2 MHz       | U16  | 2   | RW  |

| Index  | Sub-Index | Description  | Value  | Meaning of value                           | Type | Len | R/W |
|--------|-----------|--|--------|--|------|-----|-----|
|        |           | <b>Note:</b> At the end, settings must be initiated through a write access to subindex 18.                                       |        |  |      |     |     |
| 0x2042 | 16        | Copy EnDat sensor setup channel X<br><br><b>Note:</b> Sensor data must be read beforehand, and the clock frequency must be set.  | EVENT! | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2042 | 17        | Copy EnDat sensor setup channel Y1<br><br><b>Note:</b> Sensor data must be read beforehand, and the clock frequency must be set. | EVENT! | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2042 | 18        | Copy EnDat sensor setup channel Y2<br><br><b>Note:</b> Sensor data must be read beforehand, and the clock frequency must be set. | EVENT! | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2042 | 19        | EnDat status channel X<br><br><b>Note:</b> See comment at the end of the index.  | 0<br>1 | Ready<br>Error                             | U16  | 2   | RW  |
| 0x2042 | 20        | EnDat status channel Y1<br><br><b>Note:</b> See comment at the end of the index.   | 0<br>1 | Ready<br>Error                             | U16  | 2   | RW  |
| 0x2042 | 21        | EnDat status channel Y2<br><br><b>Note:</b> See comment at the end of the index.   | 0<br>1 | Ready<br>Error                             | U16  | 2   | RW  |
| 0x2042 | 22        | EnDat standard channel X<br><br><b>Note:</b> See comment at the end of the index.  | 0<br>1 | EnDat 2.1<br>EnDat 2.2                     | U16  | 2   | RW  |
| 0x2042 | 23        | EnDat standard channel Y1  | 0<br>1 | EnDat 2.1<br>EnDat 2.2                     | U16  | 2   | RW  |

| Index         | Sub-Index | Description   | Value            | Meaning of value       | Type   | Len | R/W |
|---------------|-----------|---|------------------|------------------------|--------|-----|-----|
|               |           | <b>Note:</b> See comment at the end of the index.   |                  |                        |        |     |     |
| <b>0x2042</b> | 24        | EnDat standard channel Y2<br><br><b>Note:</b> See comment at the end of the index.                                      | 0<br>1           | EnDat 2.1<br>EnDat 2.2 | U16    | 2   | RW  |
| <b>0x2042</b> | 25        | EnDat name of sensor channel X<br><br><b>Note:</b> Only available with EnDat 2.2! See comment at the end of the index.  | "angle z-axis"   |                        | STR 20 | 20  | RW  |
| <b>0x2042</b> | 26        | EnDat name of sensor channel Y1<br><br><b>Note:</b> Only available with EnDat 2.2! See comment at the end of the index. | "angle z-axis"   |                        | STR 20 | 20  | RW  |
| <b>0x2042</b> | 27        | EnDat name of sensor channel Y2<br><br><b>Note:</b> Only available with EnDat 2.2! See comment at the end of the index. | "angle z-axis"   |                        | STR 20 | 20  | RW  |
| <b>0x2042</b> | 28        | EnDat sensor serial number channel X<br><br><b>Note:</b> See comment at the end of the index.                           | SN12345678<br>90 |                        | STR 20 | 20  | RW  |
| <b>0x2042</b> | 29        | EnDat sensor serial number channel Y1<br><br><b>Note:</b> See comment at the end of the index.                          | SN12345678<br>90 |                        | STR 20 | 20  | RW  |
| <b>0x2042</b> | 30        | EnDat sensor serial number channel Y2<br><br><b>Note:</b> See comment at the end of the index.                          | SN12345678<br>90 |                        | STR 20 | 20  | RW  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>   | <b>Value</b> | <b>Meaning of value</b>                                 | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|--|--------------|---|-------------|------------|------------|
| <b>0x2042</b> | 31               | EnDat sensor type channel X<br><br><b>Note:</b> See comment at the end of the index.                                   | 0<br>1<br>2  | Displacement<br>Singelturn encoder<br>Multiturn encoder | U16         | 2          | RW         |
| <b>0x2042</b> | 32               | EnDat sensor type channel Y1<br><br><b>Note:</b> See comment at the end of the index.                                  | 0<br>1<br>2  | Displacement<br>Singelturn encoder<br>Multiturn encoder | U16         | 2          | RW         |
| <b>0x2042</b> | 33               | EnDat sensor type channel Y2<br><br><b>Note:</b> See comment at the end of the index.                                  | 0<br>1<br>2  | Displacement<br>Singelturn encoder<br>Multiturn encoder | U16         | 2          | RW         |
| <b>0x2042</b> | 34               | EnDat total number of bits channel X<br><br><b>Note:</b> See comment at the end of the index.                          | 0 ... 48     | Integer value   | U16         | 2          | RW         |
| <b>0x2042</b> | 35               | EnDat total number of bits channel Y1<br><br><b>Note:</b> See comment at the end of the index.                         | 0 ... 48     | Integer value   | U16         | 2          | RW         |
| <b>0x2042</b> | 36               | EnDat total number of bits channel Y2<br><br><b>Note:</b> See comment at the end of the index.                         | 0 ... 48     | Integer value   | U16         | 2          | RW         |
| <b>0x2042</b> | 37               | EnDat bit number displacement or angle singletturn channel X<br><br><b>Note:</b> See comment at the end of the index.  | 0 ... 32     | Integer value   | U16         | 2          | RW         |
| <b>0x2042</b> | 38               | EnDat bit number displacement or angle singletturn channel Y1<br><br><b>Note:</b> See comment at the end of the index. | 0 ... 32     | Integer value   | U16         | 2          | RW         |
| <b>0x2042</b> | 39               | EnDat bit number displacement or   | 0 ... 32     | Integer value   | U16         | 2          | RW         |

| Index         | Sub-Index | Description   | Value                                   | Meaning of value | Type | Len | R/W |
|---------------|-----------|---|---|------------------|------|-----|-----|
|               |           | angle singleturn channel Y2<br><br><b>Note:</b> See comment at the end of the index.                              |   |                  |      |     |     |
| <b>0x2042</b> | 40        | EnDat bit number angle multiturn channel X<br><br><b>Note:</b> See comment at the end of the index.               | 0 ... 32                                | Integer value    | U16  | 2   | RW  |
| <b>0x2042</b> | 41        | EnDat bit number angle multiturn channel Y1<br><br><b>Note:</b> See comment at the end of the index.              | 0 ... 32                                | Integer value    | U16  | 2   | RW  |
| <b>0x2042</b> | 42        | EnDat bit number angle multiturn channel Y2<br><br><b>Note:</b> See comment at the end of the index.              | 0 ... 32                                | Integer value    | U16  | 2   | RW  |
| <b>0x2042</b> | 43        | EnDat resolution channel X<br><br><b>Note:</b> See comment at the end of the index.                               | <i>between -9999999.0 and 9999999.0</i> | Float value      | FLT  | 4   | RW  |
| <b>0x2042</b> | 44        | EnDat resolution channel Y1<br><br><b>Note:</b> See comment at the end of the index.                              | <i>between -9999999.0 and 9999999.0</i> | Float value      | FLT  | 4   | RW  |
| <b>0x2042</b> | 45        | EnDat resolution channel Y2<br><br><b>Note:</b> See comment at the end of the index.                              | <i>between -9999999.0 and 9999999.0</i> | Float value      | FLT  | 4   | RW  |
| <b>0x2042</b> | 46        | EnDat measuring length for displacement sensor channel X<br><br><b>Note:</b> See comment at the end of the index. | <i>16-Bit-Integer value</i>             |                  | U16  | 2   | RW  |
| <b>0x2042</b> | 47        | EnDat measuring length for  | <i>16-Bit-Integer value</i>             |                  | U16  | 2   | RW  |

| Index  | Sub-Index | Description   | Value                | Meaning of value   | Type | Len | R/W |
|--------|-----------|---|----------------------|--|------|-----|-----|
|        |           | displacement sensor channel Y1<br><br><b>Note:</b> See comment at the end of the index.                                       |                      |  |      |     |     |
| 0x2042 | 48        | EnDat measuring length for displacement sensor channel Y2<br><br><b>Note:</b> See comment at the end of the index.            | 16-Bit-Integer value |  | U16  | 2   | RW  |
| 0x2042 | 49        | EnDat unit of measuring length channel X<br><br><b>Note:</b> See comment at the end of the index.                             | 0<br>1<br>2<br>3     | GP (grating period)<br>µm (Micrometer)<br>mm (Millimeter)<br>m (Meter) | U16  | 2   | RW  |
| 0x2042 | 50        | EnDat unit of measuring length channel Y1<br><br><b>Note:</b> See comment at the end of the index.                            | 0<br>1<br>2<br>3     | GP (grating period)<br>µm (Micrometer)<br>mm (Millimeter)<br>m (Meter) | U16  | 2   | RW  |
| 0x2042 | 51        | EnDat unit of measuring length channel Y2<br><br><b>Note:</b> See comment at the end of the index.                            | 0<br>1<br>2<br>3     | GP (grating period)<br>µm (Micrometer)<br>mm (Millimeter)<br>m (Meter) | U16  | 2   | RW  |
| 0x2042 | 52        | EnDat max. clock frequency channel X<br><br><b>Note:</b> Only available with EnDat 2.2! See comment at the end of the index.  | 16-Bit-Integer value |  | U16  | 2   | RW  |
| 0x2042 | 53        | EnDat max. clock frequency channel Y1<br><br><b>Note:</b> Only available with EnDat 2.2! See comment at the end of the index. | 16-Bit-Integer value |  | U16  | 2   | RW  |

| Index  | Sub-Index | Description  | Value                | Meaning of value                           | Type | Len | R/W |
|--------|-----------|--|----------------------|--|------|-----|-----|
| 0x2042 | 54        | EnDat max. clock frequency channel Y2<br><br><b>Note:</b> Only available with EnDat 2.2! See comment at the end of the index.  | 16-Bit-Integer value |  | U16  | 2   | RW  |
| 0x2042 | 55        | Transmit EnDat manual sensor setup channel X<br><br><b>Note:</b> Sensor data must be entered beforehand into the indices 19 ... 54!  | EVENT!               | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2042 | 56        | Transmit EnDat manual sensor setup channel Y1<br><br><b>Note:</b> Sensor data must be entered beforehand into the indices 19 ... 54!   | EVENT!               | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2042 | 57        | Transmit EnDat manual sensor setup channel Y2<br><br><b>Note:</b> Sensor data must be entered beforehand into the indices 19 ... 54!   | EVENT!               | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2042 | 19 ... 54 | Comment on slots 19 ... 54:<br>Reading these entries only makes sense if the data has been read from the sensor beforehand (indices 10, 11, 12)<br>It is also possible to write sensor data here.<br>A certain risk is hidden here: If data that is not appropriate for the sensor has been written, the results of the sensor measurements can no longer be read correctly! |                      |  |      |     |     |

| Index | Sub-Index | Description  | Value | Meaning of value | Type | Len | R/W |
|-------|-----------|--|-------|------------------|------|-----|-----|
|       |           | In cases of doubt, the data should not be written here manually, but should instead be read out of the sensor through indices 10/11/12. After all the sensor data for the channel concerned has been written, they still have to be transferred into the device through a write access to indices 55/56/57, and then adopted by the device's internal FPGA through write access to indices 16/17/18. |       |                  |      |     |     |

### 7.1.15 Tare (Index 0x2043)

| Index  | Sub-Index | Description                        | Value                                   | Meaning of value                           | Type | Len | R/W |
|--------|-----------|------------------------------------|---|--|------|-----|-----|
| 0x2043 | 0         | Number of subindices               | 27                                      |  | U8   | 1   | RO  |
| 0x2043 | 1 .. 9    | Reserved                           | -                                       | -  |      |     | X   |
| 0x2043 | 10        | Tare at meas. start channel X      | 0<br>1                                  | off<br>on                                  | U16  | 2   | RW  |
| 0x2043 | 11        | Tare at meas. start channel Y1     | 0<br>1                                  | off<br>on                                  | U16  | 2   | RW  |
| 0x2043 | 12        | Tare at meas. start channel Y2     | 0<br>1                                  | off<br>on                                  | U16  | 2   | RW  |
| 0x2043 | 13        | Standard value for tare channel X  | <i>between -9999999.0 and 9999999.0</i> | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2043 | 14        | Standard value for tare channel Y1 | <i>between -9999999.0 and 9999999.0</i> | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2043 | 15        | Standard value for tare channel Y2 | <i>between -9999999.0 and 9999999.0</i> | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2043 | 16        | Tare warning on/off channel X      | 0<br>1                                  | off<br>on                                  | U16  | 2   | RW  |
| 0x2043 | 17        | Tare warning on/off channel Y1     | 0<br>1                                  | off<br>on                                  | U16  | 2   | RW  |
| 0x2043 | 18        | Tare warning on/off channel Y2     | 0<br>1                                  | off<br>on                                  | U16  | 2   | RW  |
| 0x2043 | 19        | Set tare warning limit channel X   | <i>between 1.0 and 20.0</i>             | Float value,<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2043 | 20        | Set tare warning limit channel Y1  | <i>between 1.0 and 20.0</i>             | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2043 | 21        | Set tare warning limit channel Y2  | <i>between 1.0 and 20.0</i>             | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2043 | 22        | Tare channel X                     | EVENT!                                  | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2043 | 23        | Delete tare channel X              | EVENT!                                  | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2043 | 24        | Tare channel Y1                    | EVENT!                                  | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2043 | 25        | Delete tare channel Y1             | EVENT!                                  | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2043 | 26        | Tare channel Y2                    | EVENT!                                  | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2043 | 27        | Delete tare channel Y2             | EVENT!                                  | Writing an arbitrary byte initiates action | U8   | 1   | WO  |

### 7.1.16 Measurement mode (Index 0x2044)

| Index         | Sub-Index | Description   | Value  | Meaning of value   | Type | Len | R/W |
|---------------|-----------|---|--|--|------|-----|-----|
| <b>0x2044</b> | 0         | Number of subindices  | 36   |  | U8   | 1   | RO  |
| <b>0x2044</b> | 1 .. 9    | Reserved  | -  | -  |      |     | X   |
| <b>0x2044</b> | 10        | X sampling off/on   | 0<br>1   | off<br>on  | U16  | 2   | RW  |
| <b>0x2044</b> | 11        | X sample rate   | <i>between 0.0 and 9999999.0</i>               | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2044</b> | 12        | Y1 sampling off/on  | 0<br>1   | off<br>on  | U16  | 2   | RW  |
| <b>0x2044</b> | 13        | Y1 sample rate  | <i>between 0.0 and 9999999.0</i>               | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2044</b> | 14        | Y2 sampling off/on  | 0<br>1   | off<br>on  | U16  | 2   | RW  |
| <b>0x2044</b> | 15        | Y2 sample rate  | <i>between 0.0 and 9999999.0</i>               | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2044</b> | 16        | Time sampling off/on  | 0<br>1   | off<br>on  | U16  | 2   | RW  |
| <b>0x2044</b> | 17        | Time sample rate  | <i>between 0.0 and 9999999.0</i>               | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2044</b> | 18        | Set reference of curve<br><br><b>Note:</b> "Underrun" is not permitted if the channel concerned is set to time. | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8<br>9 | Absolute<br>Final force<br>Y1 reference line overrun<br>Y1 reference line underrun<br>Y1 trigger overrun<br>Y1 trigger underrun<br>Y2 reference line overrun<br>(not allowed when channel Y2 is off)<br>Y2 reference line underrun (not allowed when channel Y2 is off)<br>Y2 trigger overrun (not allowed when channel Y2 is off)<br>Y2 trigger underrun (not allowed when channel Y2 is off) | U16  | 2   | RW  |
| <b>0x2044</b> | 19        | Set reference line Y1   | <i>between -9999999.0 and 9999999.0</i>        | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2044</b> | 20        | Set reference line Y2   | <i>between -9999999.0 and 9999999.0</i>        | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2044</b> | 21        | Set trigger line Y1   | <i>between -9999999.0 and 9999999.0</i>        | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |

| Index         | Sub-Index | Description                           | Value                                     | Meaning of value  | Type | Len | R/W |
|---------------|-----------|---------------------------------------|---|---|------|-----|-----|
| <b>0x2044</b> | 22        | Set trigger line Y2                   | <i>between -9999999.0 and 9999999.0</i>   | Float value<br>Float according to IEEE754   | FLT  | 4   | RW  |
| <b>0x2044</b> | 23        | Pretrigger display on/off             | 0<br>1                                    | off<br>on   | U16  | 2   | RW  |
| <b>0x2044</b> | 24        | Set return point                      | 0<br>1<br>2<br>3                          | XMIN<br>XMAX<br>YMIN<br>YMAX  | U16  | 2   | RW  |
| <b>0x2044</b> | 25        | Set "Record curve to"                 | 0<br>1                                    | Entire curve<br>Up to return point  | U16  | 2   | RW  |
| <b>0x2044</b> | 26        | Set start mode                        | 0<br>1<br>2<br>3<br>4<br>5<br>6           | External<br>X internal overrun<br>X internal underrun<br>Y1 internal overrun<br>Y1 internal underrun<br>Y2 internal overrun (not possible if Y2 is switched off)<br>Y2 internal underrun (not possible if Y2 is switched off)   | U16  | 2   | RW  |
| <b>0x2044</b> | 27        | Set stop mode                         | 0<br>1<br>2<br>3<br>4<br>5<br>6<br>7<br>8 | External<br>X internal overrun<br>X internal underrun<br>Y1 internal overrun<br>Y1 internal underrun<br>Timeout<br>Defined number of measured values<br>Y2 internal overrun (not possible if Y2 is switched off)<br>Y2 internal underrun (not possible if Y2 is switched off) | U16  | 2   | RW  |
| <b>0x2044</b> | 28        | Set X start value for internal start  | <i>between -9999999.0 and 9999999.0</i>   | Float value<br>Float according to IEEE754   | FLT  | 4   | RW  |
| <b>0x2044</b> | 29        | Set Y1 start value for internal start | <i>between -9999999.0 and 9999999.0</i>   | Float value<br>Float according to IEEE754   | FLT  | 4   | RW  |
| <b>0x2044</b> | 30        | Set Y2 start value for internal start | <i>between -9999999.0 and 9999999.0</i>   | Float value<br>Float according to IEEE754   | FLT  | 4   | RW  |
| <b>0x2044</b> | 31        | Set X stop value for internal start   | <i>between -9999999.0 and 9999999.0</i>   | Float value<br>Float according to IEEE754   | FLT  | 4   | RW  |
| <b>0x2044</b> | 32        | Set Y1 stop value for internal stop   | <i>between</i>                            | Float value   | FLT  | 4   | RW  |

| Index         | Sub-Index | Description                              | Value  | Meaning of value                          | Type | Len | R/W |
|---------------|-----------|--|--|---|------|-----|-----|
|               |           |  | -9999999.0<br>and<br>9999999.0                   | Float according to IEEE754                |      |     |     |
| <b>0x2044</b> | 33        | Set Y2 stop value for internal stop      | <i>between</i><br>-9999999.0<br>and<br>9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2044</b> | 34        | Set the "stop" timeout value             | <i>between</i><br>-9999999.0<br>and<br>9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2044</b> | 35        | Set the "stop" number of measured values | <i>0 bis 5000</i>                                | Integer value                             | U16  | 2   | RW  |
| <b>0x2044</b> | 36        | Set bend-up factor                       | <i>between</i><br>-9999999.0<br>and<br>9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |

## 7.1.17 Evaluation window 1 (Index 0x2045)

| Index         | Sub-Index | Description  | Value  | Meaning of value                          | Type | Len | R/W |
|---------------|-----------|--|--|---|------|-----|-----|
| <b>0x2045</b> | 0         | Number of subindices   | 43   |   | U8   | 1   | RO  |
| <b>0x2045</b> | 1 .. 9    | Reserved   | -  | -   |      |     | X   |
| <b>0x2045</b> | 10        | Window 1 off/on  | 0<br>1   | off<br>on                                 | U16  | 2   | RW  |
| <b>0x2045</b> | 11        | Window 1 limit Xmin<br><br><b>Note:</b> At the end, entry must be adopted through subindex 15. | <i>between</i><br>-9999999.0<br>and<br>9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2045</b> | 12        | Window 1 limit Xmax<br><br><b>Note:</b> At the end, entry must be adopted through subindex 15. | <i>between</i><br>-9999999.0<br>and<br>9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2045</b> | 13        | Window 1 limit Ymin<br><br><b>Note:</b> At the end, entry must be adopted through subindex 15. | <i>between</i><br>-9999999.0<br>and<br>9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2045</b> | 14        | Window 1 limit Ymax<br><br><b>Note:</b> At the end, entry must be                              | <i>between</i><br>-9999999.0<br>and<br>9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |

| Index         | Sub-Index | Description  | Value         | Meaning of value                           | Type | Len | R/W |
|---------------|-----------|--|---------------|--|------|-----|-----|
|               |           | adopted through subindex 15.   |               |  |      |     |     |
| <b>0x2045</b> | 15        | Window 1 copy limit<br><br><b>Note:</b> Values entered into indices 11, 12, 13, 14 are adopted   | <i>EVENT!</i> | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| <b>0x2045</b> | 16        | Window 1 entry left<br><br><b>Note:</b> At the end, entry must be adopted through subindex 24.   | 0<br>1        | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2045</b> | 17        | Window 1 entry right<br><br><b>Note:</b> At the end, entry must be adopted through subindex 24.  | 0<br>1        | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2045</b> | 18        | Window 1 entry bottom<br><br><b>Note:</b> At the end, entry must be adopted through subindex 24. | 0<br>1        | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2045</b> | 19        | Window 1 entry top<br><br><b>Note:</b> At the end, entry must be adopted through subindex 24.    | 0<br>1        | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2045</b> | 20        | Window 1 exit left<br><br><b>Note:</b> At the end, entry must be adopted through subindex 24.    | 0<br>1        | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2045</b> | 21        | Window 1 exit right<br><br><b>Note:</b> At the end, entry must be adopted through subindex 24.   | 0<br>1        | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2045</b> | 22        | Window 1 exit bottom<br><br><b>Note:</b> At the end, entry must be adopted through subindex 24.  | 0<br>1        | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2045</b> | 23        | Window 1 exit top  | 0<br>1        | no<br>yes                                  | U16  | 2   | RW  |

| Index         | Sub-Index | Description   | Value                            | Meaning of value  | Type | Len | R/W |
|---------------|-----------|---|----------------------------------|---|------|-----|-----|
|               |           | <b>Note:</b> At the end, entry must be adopted through subindex 24. |                                  |   |      |     |     |
| <b>0x2045</b> | 24        | Copy window entry/exit  | <i>EVENT!</i>                    | no<br>yes   | U8   | 1   | WO  |
|               |           | <b>Note:</b> Values entered into indices 16 - 23 are adopted        |                                  |   |      |     |     |
| <b>0x2045</b> | 25        | Window 1 evaluation   | 0<br>1                           | off<br>on   | U16  | 2   | RW  |
| <b>0x2045</b> | 26        | Window 1 curve segment for evaluation                               | 0<br>1<br>2                      | Forward<br>Return<br>Complete curve   | U16  | 2   | RW  |
| <b>0x2045</b> | 27        | Window 1 online evaluation  | 0<br>1<br>2<br>3<br>4            | Off<br>left - right<br>right - left<br>bottom - top<br>top - bottom         | U16  | 2   | RW  |
| <b>0x2045</b> | 28        | Window 1 online signal number                                       | 1 or 2                           |   | U16  | 2   | RW  |
| <b>0x2045</b> | 29        | Window 1 Online signal level  | 0<br>1                           | Low active<br>High active   | U16  | 2   | RW  |
| <b>0x2045</b> | 30        | Window 1 "Evaluate only first passage"                              | 0<br>1                           | Evaluate all passages (like 9310)<br>Evaluate only fist passage (like 9306) | U16  | 2   | RW  |
| <b>0x2045</b> | 31        | Window 1 channel Y1/Y2  | 1<br>2                           | Channel Y1<br>Channel Y2  | U16  | 2   | RW  |
| <b>0x2045</b> | 32        | Window 1 calculate bend in window                                   | 0<br>1                           | no<br>yes   | U16  | 2   | RW  |
| <b>0x2045</b> | 33        | Window 1 delta gradient for bend                                    | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754                                   | FLT  | 4   | RW  |
| <b>0x2045</b> | 34        | Window 1 delta-Y for bend   | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754                                   | FLT  | 4   | RW  |
| <b>0x2045</b> | 35        | Window 1 calculate absolute maximum                                 | 0<br>1                           | no<br>yes   | U16  | 2   | RW  |
| <b>0x2045</b> | 36        | Window 1 calculate absolute minimum                                 | 0<br>1                           | no<br>yes   | U16  | 2   | RW  |
| <b>0x2045</b> | 37        | Window 1 calculate local maximum                                    | 0<br>1                           | no<br>yes   | U16  | 2   | RW  |
| <b>0x2045</b> | 38        | Window 1 set delta-Y for local maximum                              | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754                                   | FLT  | 4   | RW  |
| <b>0x2045</b> | 39        | Window 1 set local minimum  | 0<br>1                           | no<br>yes   | U16  | 2   | RW  |
| <b>0x2045</b> | 40        | Window 1 set delta-Y for local minimum                              | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754                                   | FLT  | 4   | RW  |

| Index         | Sub-Index | Description                         | Value  | Meaning of value | Type | Len | R/W |
|---------------|-----------|-------------------------------------|--------|------------------|------|-----|-----|
| <b>0x2045</b> | 41        | Window 1 calculate mean value       | 0<br>1 | no<br>yes        | U16  | 2   | RW  |
| <b>0x2045</b> | 42        | Window 1 calculate gradient         | 0<br>1 | no<br>yes        | U16  | 2   | RW  |
| <b>0x2045</b> | 43        | Window 1 calculate area under curve | 0<br>1 | no<br>yes        | U16  | 2   | RW  |

### 7.1.18 Evaluation window 2 (Index 0x2046)

| Index         | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|---------------|-----------|----------------------|-------|------------------|------|-----|-----|
| <b>0x2046</b> | 0         | Number of subindices | 43    |                  | U8   | 1   | RO  |
| <b>0x2046</b> | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| <b>0x2046</b> | 10 ...    | See index 0x2045     |       |                  |      |     |     |

### 7.1.19 Evaluation window 3 (Index 0x2047)

| Index         | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|---------------|-----------|----------------------|-------|------------------|------|-----|-----|
| <b>0x2047</b> | 0         | Number of subindices | 43    |                  | U8   | 1   | RO  |
| <b>0x2047</b> | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| <b>0x2047</b> | 10 ...    | See index 0x2045     |       |                  |      |     |     |

### 7.1.20 Evaluation window 4 (Index 0x2048)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2048 | 0         | Number of subindices | 43    |                  | U8   | 1   | RO  |
| 0x2048 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2048 | 10 ...    | See index 0x2045     |       |                  |      |     |     |

### 7.1.21 Evaluation window 5 (Index 0x2049)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2049 | 0         | Number of subindices | 43    |                  | U8   | 1   | RO  |
| 0x2049 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2049 | 10 ...    | See index 0x2045     |       |                  |      |     |     |

### 7.1.22 Evaluation window 6 (Index 0x2050)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2050 | 0         | Number of subindices | 43    |                  | U8   | 1   | RO  |
| 0x2050 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2050 | 10 ...    | See index 0x2045     |       |                  |      |     |     |

### 7.1.23 Evaluation window 7 (Index 0x2051)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2051 | 0         | Number of subindices | 43    |                  | U8   | 1   | RO  |
| 0x2051 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2051 | 10 ...    | See index 0x2045     |       |                  |      |     |     |

### 7.1.24 Evaluation window 8 (Index 0x2052)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2052 | 0         | Number of subindices | 43    |                  | U8   | 1   | RO  |
| 0x2052 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2052 | 10 ...    | See index 0x2045     |       |                  |      |     |     |

### 7.1.25 Evaluation window 9 (Index 0x2053)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2053 | 0         | Number of subindices | 43    |                  | U8   | 1   | RO  |
| 0x2053 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2053 | 10 ...    | See index 0x2045     |       |                  |      |     |     |

### 7.1.26 Evaluation window 10 (Index 0x2054)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2054 | 0         | Number of subindices | 43    |                  | U8   | 1   | RO  |
| 0x2054 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2054 | 10 ...    | See index 0x2045     |       |                  |      |     |     |

### 7.1.27 Evaluation trapezoid window X1 (Index 0x2055)

| Index  | Sub-Index | Description  | Value                            | Meaning of value                          | Type | Len | R/W |
|--------|-----------|--|----------------------------------|---|------|-----|-----|
| 0x2055 | 0         | Number of subindices   | 26                               |   | U8   | 1   | RO  |
| 0x2055 | 1 .. 9    | Reserved   | -                                | -   |      |     | X   |
| 0x2055 | 10 ...    | Trapezoid X1 off/on  | 0<br>1                           | off<br>on                                 | U16  | 2   | RW  |
| 0x2055 | 11        | Trapezoid X1 limit Xmin  | between -9999999.0 and 9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2055 | 12        | Trapezoid X1 limit Xmax<br><br><b>Note:</b> At the end, entry must be adopted through subindex 17.         | between -9999999.0 and 9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2055 | 13        | Trapezoid X1 Y limit max. left<br><br><b>Note:</b> At the end, entry must be adopted through subindex 17.  | between -9999999.0 and 9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2055 | 14        | Trapezoid X1 Y limit max. right<br><br><b>Note:</b> At the end, entry must be adopted through subindex 17. | between -9999999.0 and 9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |

| Index  | Sub-Index | Description  | Value                                   | Meaning of value                           | Type | Len | R/W |
|--------|-----------|--|---|--|------|-----|-----|
| 0x2055 | 15        | Trapezoid X1 Y limit min. left<br><br><b>Note:</b> At the end, entry must be adopted through subindex 17.  | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2055 | 16        | Trapezoid X1 Y limit min. right<br><br><b>Note:</b> At the end, entry must be adopted through subindex 17. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2055 | 17        | Trapezoid X1 copy the limits<br><br><b>Note:</b> Values entered into indices 11 - 16 are adopted           | EVENT                                   | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2055 | 18        | Trapezoid X1 entry left<br><br><b>Note:</b> At the end, entry must be adopted through subindex 22.         | 0<br>1                                  | no<br>yes                                  | U16  | 2   | RW  |
| 0x2055 | 19        | Trapezoid X1 entry right<br><br><b>Note:</b> At the end, entry must be adopted through subindex 22.        | 0<br>1                                  | no<br>yes                                  | U16  | 2   | RW  |
| 0x2055 | 20        | Trapezoid X1 exit left<br><br><b>Note:</b> At the end, entry must be adopted through subindex 22.          | 0<br>1                                  | no<br>yes                                  | U16  | 2   | RW  |
| 0x2055 | 21        | Trapezoid X1 exit right<br><br>Note: At the end, entry must be adopted through subindex 22.                | 0<br>1                                  | no<br>yes                                  | U16  | 2   | RW  |
| 0x2055 | 22        | Trapezoid X1 copy entry/exit<br><br><b>Note:</b> Values entered into indices 16 - 21 are adopted.          | EVENT                                   | Writing an arbitrary byte initiates action | U8   | 1   | WO  |

| Index         | Sub-Index | Description                                | Value       | Meaning of value   | Type | Len | R/W |
|---------------|-----------|--|-------------|--|------|-----|-----|
| <b>0x2055</b> | 23        | Trapezoid X1 evaluation                    | 0<br>1      | off<br>on  | U16  | 2   | RW  |
| <b>0x2055</b> | 24        | Trapezoid X1 curve segment for evaluation  | 0<br>1<br>2 | Forward<br>Return<br>Complete curve  | U16  | 2   | RW  |
| <b>0x2055</b> | 25        | Trapezoid X1 "Evaluate only first passage" | 0<br>1      | Evaluate all passages (like 9310)<br>Evaluate only first passage (like 9306) | U16  | 2   | RW  |
| <b>0x2055</b> | 26        | Trapezoid X1 channel Y1/Y2                 | 1<br>2      | Channel Y1<br>Channel Y2   | U16  | 2   | RW  |

### 7.1.28 Evaluation trapezoid window X2 (Index 0x2056)

| Index         | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|---------------|-----------|----------------------|-------|------------------|------|-----|-----|
| <b>0x2056</b> | 0         | Number of subindices | 26    |                  | U8   | 1   | RO  |
| <b>0x2056</b> | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| <b>0x2056</b> | 10 ...    | See index 0x2055     |       |                  |      |     |     |

### 7.1.29 Evaluation trapezoid window Y1 (Index 0x2057)

| Index         | Sub-Index | Description   | Value                                   | Meaning of value                          | Type | Len | R/W |
|---------------|-----------|---|---|---|------|-----|-----|
| <b>0x2057</b> | 0         | Number of subindices  | 26                                      |   | U8   | 1   | RO  |
| <b>0x2057</b> | 1 .. 9    | Reserved  | -                                       | -   |      |     | X   |
| <b>0x2057</b> | 10        | Trapezoid Y1 off/on   | 0<br>1                                  | off<br>on                                 | U16  | 2   | RW  |
| <b>0x2057</b> | 11        | Trapezoid Y1 limit Ymin   | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2057</b> | 12        | Trapezoid Y1 limit Ymax<br><br><b>Note:</b> At the end, entry must be adopted through subindex 17.      | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2057</b> | 13        | Trapezoid Y1 X limit min top<br><br><b>Note:</b> At the end, entry must be adopted through subindex 17. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2057</b> | 14        | Trapezoid Y1 X limit max top  | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |

| Index         | Sub-Index | Description  | Value                                   | Meaning of value                           | Type | Len | R/W |
|---------------|-----------|--|---|--|------|-----|-----|
|               |           | <b>Note:</b> At the end, entry must be adopted through subindex 17.  |   |  |      |     |     |
| <b>0x2057</b> | 15        | Trapezoid Y1 X limit min bottom<br><br><b>Note:</b> At the end, entry must be adopted through subindex 17. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2057</b> | 16        | Trapezoid Y1 X limit max bottom<br><br><b>Note:</b> At the end, entry must be adopted through subindex 17. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2057</b> | 17        | Trapezoid Y1 copy limits<br><br><b>Note:</b> Values entered into indices 11 - 16 are adopted               | EVENT                                   | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| <b>0x2057</b> | 18        | Trapezoid Y1 entry bottom<br><br><b>Note:</b> At the end, entry must be adopted through subindex 22.       | 0<br>1                                  | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2057</b> | 19        | Trapezoid Y1 entry top<br><br><b>Note:</b> At the end, entry must be adopted through subindex 22.          | 0<br>1                                  | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2057</b> | 20        | Trapezoid Y1 exit bottom<br><br><b>Note:</b> At the end, entry must be adopted through subindex 22.        | 0<br>1                                  | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2057</b> | 21        | Trapezoid Y1 exit top<br><br><b>Note:</b> At the end, entry must be adopted through subindex 22.           | 0<br>1                                  | no<br>yes                                  | U16  | 2   | RW  |
| <b>0x2057</b> | 22        | Trapezoid Y1 copy entry/exit   | EVENT                                   | Writing an arbitrary byte initiates action | U8   | 1   | WO  |

| Index         | Sub-Index | Description  | Value       | Meaning of value  | Type | Len | R/W |
|---------------|-----------|--|-------------|---|------|-----|-----|
|               |           | <b>Note:</b> Values entered into indices 16 - 21 are adopted |             |   |      |     |     |
| <b>0x2057</b> | 23        | Trapezoid Y1 evaluation                                      | 0<br>1      | off<br>on   | U16  | 2   | RW  |
| <b>0x2057</b> | 24        | Trapezoid Y1 Curve segment for evaluation                    | 0<br>1<br>2 | Forward<br>Return<br>Complete curve   | U16  | 2   | RW  |
| <b>0x2057</b> | 25        | Trapezoid Y1 "Evaluate only first passage"                   | 0<br>1      | Evaluate all passages (like 9310)<br>Evaluate only first passages (like 9306) | U16  | 2   | RW  |
| <b>0x2057</b> | 26        | Trapezoid Y1 channel Y1/Y2                                   | 1<br>2      | Channel Y1<br>Channel Y2  | U16  | 2   | RW  |

### 7.1.30 Evaluation trapezoid window Y2 (Index 0x2058)

| Index         | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|---------------|-----------|----------------------|-------|------------------|------|-----|-----|
| <b>0x2058</b> | 0         | Number of subindices | 26    |                  | U8   | 1   | RO  |
| <b>0x2058</b> | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| <b>0x2058</b> | 10 ...    | See index 0x2057     |       |                  |      |     |     |

### 7.1.31 Evaluation threshold 1 (Index 0x2059)

| Index         | Sub-Index | Description  | Value                                     | Meaning of value                          | Type | Len | R/W |
|---------------|-----------|--|---|---|------|-----|-----|
| <b>0x2059</b> | 0         | Number of subindices   | 34  |   | U8   | 1   | RO  |
| <b>0x2059</b> | 1 .. 9    | Reserved   | -   | -   |      |     | X   |
| <b>0x2059</b> | 10        | Threshold 1 off/on   | 0<br>1                                    | off<br>on                                 | U16  | 2   | RW  |
| <b>0x2059</b> | 11        | Threshold 1 type of threshold  | 0<br>1                                    | Type X (vertical)<br>Type Y (horizontal)  | U16  | 2   | RW  |
| <b>0x2059</b> | 12        | Threshold 1 position Type X: X value<br>Type Y: Y value<br><br><b>Note:</b> At the end, entry must be adopted through subindex 15.   | between<br>-9999999.0<br>and<br>9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2059</b> | 13        | Threshold 1 limit<br>For type X: Ymin<br>For type Y: Xmin<br><br><b>Note:</b> At the end, entry must be adopted through subindex 15. | between<br>-9999999.0<br>and<br>9999999.0 | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |

| Index  | Sub-Index | Description  | Value                            | Meaning of value   | Type | Len | R/W |
|--------|-----------|--|----------------------------------|--|------|-----|-----|
| 0x2059 | 14        | Threshold 1 limit<br>For type X: Ymax<br>For type Y: Xmax<br><br><b>Note:</b> At the end, entry must be adopted through subindex 15.     | between -9999999.0 and 9999999.0 | Float value<br>Float according to IEEE754                                    | FLT  | 4   | RW  |
| 0x2059 | 15        | Threshold 1 copy position and limits<br><br><b>Note:</b> Values entered into indices 11 - 14 are adopted                                 | EVENT                            | Writing an arbitrary byte initiates action                                   | U8   | 1   | WO  |
| 0x2059 | 16        | Threshold 1 passage Type X: left > right Type Y: bottom > top<br><br><b>Note:</b> At the end, entry must be adopted through subindex 18. | 0<br>1                           | no<br>yes  | U16  | 2   | RW  |
| 0x2059 | 17        | Threshold 1 passage Type X: right > left Type Y: top > bottom<br><br><b>Note:</b> At the end, entry must be adopted through subindex 18. | 0<br>1                           | no<br>yes  | U16  | 2   | RW  |
| 0x2059 | 18        | Threshold 1 Copy passage<br><br><b>Note:</b> Values entered into indices 16 - 17 are adopted   | EVENT                            | Writing an arbitrary byte initiates action                                   | U8   | 1   | WO  |
| 0x2059 | 19        | Threshold 1 evaluation   | 0<br>1                           | off<br>on  | U16  | 2   | RW  |
| 0x2059 | 20        | Threshold 1 Curve segment for evaluation   | 0<br>1<br>2                      | Forward<br>Return<br>Complete curve  | U16  | 2   | RW  |
| 0x2059 | 21        | Threshold 1 "Evaluate only first passage"  | 0<br>1                           | Evaluate all passages (like 9310)<br>Evaluate only first passage (like 9306) | U16  | 2   | RW  |
| 0x2059 | 22        | Threshold 1 Channel Y1/Y2  | 1<br>2                           | Channel Y1<br>Channel Y2   | U16  | 2   | RW  |

| Index         | Sub-Index | Description   | Value                            | Meaning of value                          | Type | Len | R/W |
|---------------|-----------|---|----------------------------------|---|------|-----|-----|
| <b>0x2059</b> | 23        | Threshold 1<br>Calculate bend<br><br><b>Note:</b> Only for type Y             | 0<br>1                           | no<br>yes                                 | U16  | 2   | RW  |
| <b>0x2059</b> | 24        | Threshold 1<br>Delta gradient for bend  | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2059</b> | 25        | Threshold 1<br>Delta Y bend   | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2059</b> | 26        | Threshold 1<br>Calculate absolute maximum<br><br><b>Note:</b> Only for type Y | 0<br>1                           | no<br>yes                                 | U16  | 2   | RW  |
| <b>0x2059</b> | 27        | Threshold 1<br>Calculate absolute minimum<br><br><b>Note:</b> Only for type Y | 0<br>1                           | no<br>yes                                 | U16  | 2   | RW  |
| <b>0x2059</b> | 28        | Threshold 1<br>Calculate local maximum<br><br><b>Note:</b> Only for type Y    | 0<br>1                           | no<br>yes                                 | U16  | 2   | RW  |
| <b>0x2059</b> | 29        | Threshold 1<br>Delta Y local maximum  | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2059</b> | 30        | Threshold 1<br>Calculate local minimum<br><br><b>Note:</b> Only for type Y    | 0<br>1                           | no<br>yes                                 | U16  | 2   | RW  |
| <b>0x2059</b> | 31        | Threshold 1<br>Delta Y local minimum  | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2059</b> | 32        | Threshold 1<br>Calculate mean value<br><br><b>Note:</b> Only for type Y       | 0<br>1                           | no<br>yes                                 | U16  | 2   | RW  |
| <b>0x2059</b> | 33        | Threshold 1<br>Calculate gradient<br><br><b>Note:</b> Only for type Y         | 0<br>1                           | no<br>yes                                 | U16  | 2   | RW  |
| <b>0x2059</b> | 34        | Threshold 1<br>Calculate area   | 0<br>1                           | no<br>yes                                 | U16  | 2   | RW  |

| <b>Index</b> | <b>Sub-Index</b> | <b>Description</b>           | <b>Value</b> | <b>Meaning of value</b> | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|--------------|------------------|------------------------------|--------------|-------------------------|-------------|------------|------------|
|              |                  | <b>Note:</b> Only for type Y |              |                         |             |            |            |

### 7.1.32 Evaluation threshold 2 (Index 0x2060)

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>   | <b>Value</b> | <b>Meaning of value</b> | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|----------------------|--------------|-------------------------|-------------|------------|------------|
| <b>0x2060</b> | 0                | Number of subindices | 34           |                         | U8          | 1          | RO         |
| <b>0x2060</b> | 1 .. 9           | Reserved             | -            | -                       |             |            | X          |
| <b>0x2060</b> | 10 ...           | See index 0x2059     |              |                         |             |            |            |

### 7.1.33 Evaluation threshold 3 (Index 0x2061)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2061 | 0         | Number of subindices | 34    |                  | U8   | 1   | RO  |
| 0x2061 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2061 | 10 ...    | See index 0x2059     |       |                  |      |     |     |

### 7.1.34 Evaluation threshold 4 (Index 0x2062)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2062 | 0         | Number of subindices | 34    |                  | U8   | 1   | RO  |
| 0x2062 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2062 | 10 ...    | See index 0x2059     |       |                  |      |     |     |

### 7.1.35 Evaluation envelope 1 (Index 0x2063 to 0x2067)

Index/subindex data on request

### 7.1.36 Evaluation envelope 2 (Index 0x2068 to 0x2069 and 0x2070 to 0x2072)

Index /subindex data on request

### 7.1.37 Evaluation rotary switch 1 (Index 0x2073)

Index /subindex data on request

### 7.1.38 Evaluation rotary switch 2 (Index 0x2074)

Index /subindex data on request

## 7.1.39 Evaluation mathematical functions (Index 0x2075)

| Index  | Sub-Index | Description   | Value                                   | Meaning of value                          | Type | Len | R/W |
|--------|-----------|---|---|---|------|-----|-----|
| 0x2075 | 0         | Number of subindices  | 83                                      |   | U8   | 1   | RO  |
| 0x2075 | 1 .. 9    | Reserved  | -                                       | -   |      |     | X   |
| 0x2075 | 10        | Math. function Constant 1   | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2075 | 11        | Math. function Constant 2   | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2075 | 12        | Math. function Constant 3   | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2075 | 13        | Math. function Constant 4   | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2075 | 14        | Math. function Constant 5   | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2075 | 15        | Math. function Constant 6   | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2075 | 16        | Math. function Constant 7   | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2075 | 17        | Math. function Constant 8   | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2075 | 18        | Math. function Constant 9   | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2075 | 19        | Math. function Constant 10  | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| 0x2075 | 20        | Math. function formula row 1 operand A<br><br><b>Note:</b> At the end, entry must be adopted through subindex 23. | <i>Integer value</i>                    | See operand table in appendix             | U16  | 2   | RW  |

| Index  | Sub-Index | Description   | Value                | Meaning of value                           | Type | Len | R/W |
|--------|-----------|---|----------------------|--|------|-----|-----|
| 0x2075 | 21        | Math. function formula row 1 operator<br><br><b>Note:</b> At the end, entry must be adopted through subindex 23.  | 0<br>1<br>2<br>3     | Sum up<br>Subtract<br>Multiply<br>Divide   | U16  | 2   | RW  |
| 0x2075 | 22        | Math. function formula row 1 operand B<br><br><b>Note:</b> At the end, entry must be adopted through subindex 23. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 23        | Math. function Copy formula 1<br><br><b>Note:</b> Values entered into indices 20 - 22 are adopted                 | <i>EVENT</i>         | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 24        | Math. function formula row 2 operand A<br><br><b>Note:</b> At the end, entry must be adopted through subindex 27. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 25        | Math. function formula row 2 Operator<br><br><b>Note:</b> At the end, entry must be adopted through subindex 27.  | 0<br>1<br>2<br>3     | Sum up<br>Subtract<br>Multiply<br>Divide   | U16  | 2   | RW  |
| 0x2075 | 26        | Math. function formula row 2 operand B<br><br><b>Note:</b> At the end, entry must be adopted through subindex 27. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 27        | Math. function Copy formula 2<br><br><b>Note:</b> Values entered into indices 24 - 26 are adopted                 | <i>EVENT</i>         | Writing an arbitrary byte initiates action | U8   | 1   | WO  |

| Index  | Sub-Index | Description   | Value                | Meaning of value                           | Type | Len | R/W |
|--------|-----------|---|----------------------|--|------|-----|-----|
| 0x2075 | 28        | Math. function formula row 3 operand A<br><br><b>Note:</b> At the end, entry must be adopted through subindex 31. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 29        | Math. function formula row 3 operator<br><br><b>Note:</b> At the end, entry must be adopted through subindex 31.  | 0<br>1<br>2<br>3     | Sum up<br>Subtract<br>Multiply<br>Divide   | U16  | 2   | RW  |
| 0x2075 | 30        | Math. function formula row 3 operand B<br><br><b>Note:</b> At the end, entry must be adopted through subindex 31. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 31        | Math. function Copy formula 3<br><br><b>Note:</b> Values entered into indices 28 - 30 are adopted.                | EVENT                | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 32        | Math. function formula row 4 operand A<br><br><b>Note:</b> At the end, entry must be adopted through subindex 35. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 33        | Math. function formula row 4 operator<br><br><b>Note:</b> At the end, entry must be adopted through subindex 35.  | 0<br>1<br>2<br>3     | Sum up<br>Subtract<br>Multiply<br>Divide   | U16  | 2   | RW  |
| 0x2075 | 34        | Math. function formula row 4 operand B  | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |

| Index  | Sub-Index | Description   | Value                | Meaning of value                           | Type | Len | R/W |
|--------|-----------|---|----------------------|--|------|-----|-----|
|        |           | <b>Note:</b> At the end, entry must be adopted through subindex 35.   |                      |  |      |     |     |
| 0x2075 | 35        | Math. function Copy formula 4<br><br><b>Note:</b> Values entered into indices 32 - 34 are adopted.                | EVENT                | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 36        | Math. function formula row 5 operand A<br><br><b>Note:</b> At the end, entry must be adopted through subindex 39. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 37        | Math. function formula row 5 operator<br><br><b>Note:</b> At the end, entry must be adopted through subindex 39.  | 0<br>1<br>2<br>3     | Sum up<br>Subtract<br>Multiply<br>Divide   | U16  | 2   | RW  |
| 0x2075 | 38        | Math. function formula row 5 operand B<br><br><b>Note:</b> At the end, entry must be adopted through subindex 39. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 39        | Math. function Copy formula 5<br><br><b>Note:</b> Values entered into indices 36 - 38 are adopted.                | EVENT                | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 40        | Math. function formula row 6 operand A<br><br><b>Note:</b> At the end, entry must be adopted through subindex 43. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |

| Index  | Sub-Index | Description   | Value                | Meaning of value                           | Type | Len | R/W |
|--------|-----------|---|----------------------|--|------|-----|-----|
| 0x2075 | 41        | Math. function formula row 6 operator<br><br><b>Note:</b> At the end, entry must be adopted through subindex 43.  | 0<br>1<br>2<br>3     | Sum up<br>Subtract<br>Multiply<br>Divide   | U16  | 2   | RW  |
| 0x2075 | 42        | Math. function formula row 6 operand B<br><br><b>Note:</b> At the end, entry must be adopted through subindex 43. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 43        | Math. function Copy formula 6<br><br><b>Note:</b> Values entered into indices 40 - 42 are adopted.                | <i>EVENT</i>         | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 44        | Math. function formula row 7 operand A<br><br><b>Note:</b> At the end, entry must be adopted through subindex 47. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 45        | Math. function formula row 7 operator<br><br><b>Note:</b> At the end, entry must be adopted through subindex 47.  | 0<br>1<br>2<br>3     | Sum up<br>Subtract<br>Multiply<br>Divide   | U16  | 2   | RW  |
| 0x2075 | 46        | Math. function formula row 7 operand B<br><br><b>Note:</b> At the end, entry must be adopted through subindex 47. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 47        | Math. function Copy formula 7   | <i>EVENT</i>         | Writing an arbitrary byte initiates action | U8   | 1   | WO  |

| Index  | Sub-Index | Description   | Value                | Meaning of value                           | Type | Len | R/W |
|--------|-----------|---|----------------------|--|------|-----|-----|
|        |           | <b>Note:</b> Values entered into indices 44 - 46 are adopted.   |                      |  |      |     |     |
| 0x2075 | 48        | Math. function formula row 8 operand A<br><br><b>Note:</b> At the end, entry must be adopted through subindex 51. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 49        | Math. function formula row 8 operator<br><br><b>Note:</b> At the end, entry must be adopted through subindex 51.  | 0<br>1<br>2<br>3     | Sum up<br>Subtract<br>Multiply<br>Divide   | U16  | 2   | RW  |
| 0x2075 | 50        | Math. function formula row 8 operand B<br><br><b>Note:</b> At the end, entry must be adopted through subindex 51. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 51        | Math. function Copy formula 8<br><br><b>Note:</b> Values entered into indices 48 - 50 are adopted.                | EVENT                | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 52        | Math. function formula row 9 operand A<br><br><b>Note:</b> At the end, entry must be adopted through subindex 55. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 53        | Math. function formula row 9 operator<br><br><b>Note:</b> At the end, entry must be adopted through subindex 55.  | 0<br>1<br>2<br>3     | Sum up<br>Subtract<br>Multiply<br>Divide   | U16  | 2   | RW  |

| Index  | Sub-Index | Description  | Value                | Meaning of value                           | Type | Len | R/W |
|--------|-----------|--|----------------------|--|------|-----|-----|
| 0x2075 | 54        | Math. function formula row 9 operand B<br><br><b>Note:</b> At the end, entry must be adopted through subindex 55.  | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 55        | Math. function Copy formula 9<br><br><b>Note:</b> Values entered into indices 52 - 54 are adopted.                 | EVENT                | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 56        | Math. function formula row 10 operand A<br><br><b>Note:</b> At the end, entry must be adopted through subindex 59. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 57        | Math. function formula row 10 operator<br><br><b>Note:</b> At the end, entry must be adopted through subindex 59.  | 0<br>1<br>2<br>3     | Sum up<br>Subtract<br>Multiply<br>Divide   | U16  | 2   | RW  |
| 0x2075 | 58        | Math. function formula row 10 operand B<br><br><b>Note:</b> At the end, entry must be adopted through subindex 59. | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 59        | Math. function Copy formula 10<br><br><b>Note:</b> Values entered into indices 56 - 58 are adopted.                | EVENT                | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 60        | Math. function Evaluation operand 1  | <i>Integer value</i> | See operand table in appendix              | U16  | 2   | RW  |

| Index         | Sub-Index | Description   | Value                                   | Meaning of value                           | Type | Len | R/W |
|---------------|-----------|---|---|--|------|-----|-----|
|               |           | <b>Note:</b> At the end, entry must be adopted through subindex 63.   |   |  |      |     |     |
| <b>0x2075</b> | 61        | Math. function Evaluation operand 1 Min. tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 63. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2075</b> | 62        | Math. function Evaluation operand 1 Max. tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 63. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2075</b> | 63        | Math. function Copy evaluation1<br><br><b>Note:</b> Values entered into indices 60 - 62 are adopted.                                | <i>EVENT</i>                            | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| <b>0x2075</b> | 64        | Math. function Evaluation operand 2<br><br><b>Note:</b> At the end, entry must be adopted through subindex 67.                      | <i>Integer value</i>                    | See operand table in appendix              | U16  | 2   | RW  |
| <b>0x2075</b> | 65        | Math. function Evaluation operand 2 Min. tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 67. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2075</b> | 66        | Math. function Evaluation operand 2 Max. tolerance limit  | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |

| Index  | Sub-Index | Description   | Value                                   | Meaning of value                           | Type | Len | R/W |
|--------|-----------|---|---|--|------|-----|-----|
|        |           | <b>Note:</b> At the end, entry must be adopted through subindex 67.   |   |  |      |     |     |
| 0x2075 | 67        | Math. function Copy evaluation 2<br><br><b>Note:</b> Values entered into indices 64 - 66 are adopted.                               | EVENT                                   | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 68        | Math. function Evaluation operand 3<br><br><b>Note:</b> At the end, entry must be adopted through subindex 71.                      | <i>Integer value</i>                    | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 69        | Math. function Evaluation operand 3 Min. tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 71. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2075 | 70        | Math. function Evaluation operand 3 Max. tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 71. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2075 | 71        | Math. function Copy evaluation 3<br><br><b>Note:</b> Values entered into indices 68 - 70 are adopted.                               | EVENT                                   | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 72        | Math. function Evaluation operand 4   | <i>Integer value</i>                    | See operand table in appendix              | U16  | 2   | RW  |

| Index         | Sub-Index | Description   | Value                                   | Meaning of value                           | Type | Len | R/W |
|---------------|-----------|---|---|--|------|-----|-----|
|               |           | <b>Note:</b> At the end, entry must be adopted through subindex 75.   |   |  |      |     |     |
| <b>0x2075</b> | 73        | Math. function Evaluation operand 4 Min. tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 75. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2075</b> | 74        | Math. function Evaluation operand 4 Max-tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 75.  | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2075</b> | 75        | Math. function Copy evaluation 4<br><br><b>Note:</b> Values entered into indices 72 - 74 are adopted.                               | <i>EVENT</i>                            | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| <b>0x2075</b> | 76        | Math. function Evaluation operand 5<br><br><b>Note:</b> At the end, entry must be adopted through subindex 79.                      | <i>Integer value</i>                    | See operand table in appendix              | U16  | 2   | RW  |
| <b>0x2075</b> | 77        | Math. function Evaluation operand 5 Min. tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 79. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| <b>0x2075</b> | 78        | Math. function Evaluation operand   | <i>between -9999999.0 and</i>           | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |

| Index  | Sub-Index | Description   | Value                                   | Meaning of value                           | Type | Len | R/W |
|--------|-----------|---|---|--|------|-----|-----|
|        |           | 5 Max. tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 79.                                   | 9999999.0                               |  |      |     |     |
| 0x2075 | 79        | Math. function Copy evaluation 5<br><br><b>Note:</b> Values entered into indices 76 - 78 are adopted.                               | EVENT                                   | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2075 | 80        | Math. function Evaluation operand 6<br><br><b>Note:</b> At the end, entry must be adopted through subindex 83.                      | <i>Integer value</i>                    | See operand table in appendix              | U16  | 2   | RW  |
| 0x2075 | 81        | Math. function Evaluation operand 6 Min. tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 83. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2075 | 82        | Math. function Evaluation operand 6 Max. tolerance limit<br><br><b>Note:</b> At the end, entry must be adopted through subindex 83. | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2075 | 83        | Math. function Copy evaluation 6<br><br><b>Note:</b> Values entered into indices 80 - 82 are adopted.                               | EVENT                                   | Writing an arbitrary byte initiates action | U8   | 1   | WO  |

#### 7.1.40 Tolerance band for evaluation elements (Index 0x2076)

| Index  | Sub-Index | Description  | Value                            | Meaning of value                           | Type | Len | R/W |
|--------|-----------|--|----------------------------------|--|------|-----|-----|
| 0x2076 | 0         | Number of subindices   | 13                               |  | U8   | 1   | RO  |
| 0x2076 | 1 .. 9    | Reserved   | -                                | -  |      |     | X   |
| 0x2076 | 10        | Tolerance band X<br><br><b>Note:</b> At the end, entry must be adopted through subindex 13.  | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2076 | 11        | Tolerance band Y1<br><br><b>Note:</b> At the end, entry must be adopted through subindex 13. | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2076 | 12        | Tolerance band Y2<br><br><b>Note:</b> At the end, entry must be adopted through subindex 13. | <i>between 0.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2076 | 13        | Copy tolerance bands<br><br><b>Note:</b> Values entered into indices 10 - 12 are adopted.    | EVENT                            | Writing an arbitrary byte initiates action | U8   | 1   | WO  |

## 7.1.41 Realtime switchpoints S1 (Index 0x2077)

| Index  | Sub-Index | Description  | Value                                   | Meaning of value                           | Type | Len | R/W |
|--------|-----------|--|---|--|------|-----|-----|
| 0x2077 | 0         | Number of subindices   | 14                                      |  | U8   | 1   | RO  |
| 0x2077 | 1 .. 9    | Reserved   | -                                       | -  |      |     | X   |
| 0x2077 | 10        | Switchpoint S1 value<br><br><b>Note:</b> At the end, entry must be adopted through subindex 14.    | <i>between -9999999.0 and 9999999.0</i> | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2077 | 11        | Switchpoint S1 channel<br><br><b>Note:</b> At the end, entry must be adopted through subindex 14.  | 0<br>1<br>2                             | Channel X<br>Channel Y1<br>Channel Y2      | U16  | 2   | RW  |
| 0x2077 | 12        | Switchpoint S1 level<br><br><b>Note:</b> At the end, entry must be adopted through subindex 14.    | 0<br>1                                  | Low active<br>High active                  | U16  | 2   | RW  |
| 0x2077 | 13        | Switchpoint 1 reference<br><br><b>Note:</b> At the end, entry must be adopted through subindex 14. | 0<br>1                                  | Absolute reference<br>Trigger reference    | U16  | 2   | RW  |
| 0x2077 | 14        | Switchpoint 1 Copy settings<br><br><b>Note:</b> Values entered into indices 10 - 13 are adopted.   | EVENT                                   | Writing an arbitrary byte initiates action | U8   | 1   | WO  |

## 7.1.42 Realtime switchpoints S2 (Index 0x2078)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2078 | 0         | Number of subindices | 14    |                  | U8   | 1   | RO  |
| 0x2078 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2078 | 10..      | See index 0x2077     |       |                  |      |     |     |

## 7.1.43 Realtime switchpoints S3 (Index 0x2079)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2079 | 0         | Number of subindices | 14    |                  | U8   | 1   | RO  |
| 0x2079 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2079 | 10..      | See index 0x2077     |       |                  |      |     |     |

#### 7.1.44 Realtime switchpoints S4 (Index 0x2080)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2080 | 0         | Number of subindices | 14    |                  | U8   | 1   | RO  |
| 0x2080 | 1 .. 9    | Reserved             | -     | -                |      |     | X   |
| 0x2080 | 10..      | See index 0x2077     |       |                  |      |     |     |

#### 7.1.45 Sensortest (Index 0x2081)

| Index  | Sub-Index | Description                                    | Value                            | Meaning of value                           | Type | Len | R/W |
|--------|-----------|--|----------------------------------|--|------|-----|-----|
| 0x2081 | 0         | Number of subindices                           | 22                               |  | U8   | 1   | RO  |
| 0x2081 | 1 .. 9    | Reserved                                       | -                                | -  |      |     | X   |
| 0x2081 | 10        | Sensor test Channel X on/off                   | 0<br>1                           | off<br>on                                  | U16  | 2   | RW  |
| 0x2081 | 11        | Sensor test Channel Y1 on/off                  | 0<br>1                           | off<br>on                                  | U16  | 2   | RW  |
| 0x2081 | 12        | Sensor test Channel Y2 on/off                  | 0<br>1                           | off<br>on                                  | U16  | 2   | RW  |
| 0x2081 | 13        | Sensor test Channel X measure reference value  | EVENT                            | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2081 | 14        | Sensor test Channel Y1 measure reference value | EVENT                            | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2081 | 15        | Sensor test Channel Y2 measure reference value | EVENT                            | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2081 | 16        | Sensor test Channel X reference value          | between -9999999.0 and 9999999.0 | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2081 | 17        | Sensor test Channel Y1 reference value         | between -9999999.0 and 9999999.0 | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |
| 0x2081 | 18        | Sensor test Channel Y2 reference value         | between -9999999.0 and 9999999.0 | Float value<br>Float according to IEEE754  | FLT  | 4   | RW  |

| Index         | Sub-Index | Description   | Value                                    | Meaning of value                          | Type | Len | R/W |
|---------------|-----------|---|--|---|------|-----|-----|
| <b>0x2081</b> | 19        | Sensor test<br>Channel X allowed deviation  | <i>between<br/>0.0 and<br/>9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2081</b> | 20        | Sensor test<br>Channel Y1 allowed deviation   | <i>between<br/>0.0 and<br/>9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2081</b> | 21        | Sensor test<br>Channel Y2 allowed deviation   | <i>between<br/>0.0 and<br/>9999999.0</i> | Float value<br>Float according to IEEE754 | FLT  | 4   | RW  |
| <b>0x2081</b> | 22        | Initiate sensor test<br><br><b>Note:</b> Read access initiates the sensor test and delivers the result. | 0<br>1                                   | NOK<br>OK                                 | U16  | 2   | RO  |

## 7.1.46 Setup user-defined values (Index 0x2082)

| Index         | Sub-Index | Description                  | Value                | Meaning of value              | Type | Len | R/W |
|---------------|-----------|------------------------------|----------------------|-------------------------------|------|-----|-----|
| <b>0x2082</b> | 0         | Number of subindices         | 39                   |                               | U8   | 1   | RO  |
| <b>0x2082</b> | 1 .. 9    | Reserved                     | -                    | -                             |      |     | X   |
| <b>0x2082</b> | 10        | User-defined values value 1  | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 11        | User-defined values value 2  | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 12        | User-defined values value 3  | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 13        | User-defined values value 4  | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 14        | User-defined values value 5  | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 15        | User-defined values value 6  | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 16        | User-defined values value 7  | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 17        | User-defined values value 8  | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 18        | User-defined values value 9  | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 19        | User-defined values value 10 | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 20        | User-defined values value 11 | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 21        | User-defined values value 12 | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 22        | User-defined values value 13 | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 23        | User-defined values value 14 | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 24        | User-defined values value 15 | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |

| Index         | Sub-Index | Description  | Value                | Meaning of value              | Type | Len | R/W |
|---------------|-----------|--|----------------------|-------------------------------|------|-----|-----|
| <b>0x2082</b> | 25        | User-defined values value 16   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 26        | User-defined values value 17   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 27        | User-defined values value 18   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 28        | User-defined values value 19   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 29        | User-defined values value 20   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 30        | User-defined values value 21   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 31        | User-defined values value 22   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 32        | User-defined values value 23   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 33        | User-defined values value 24   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 34        | User-defined values value 25<br><br><b>Note:</b> Values 25 ... 30 will also be displayed as results in process window M1 (curve) | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 35        | User-defined values value 26   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 36        | User-defined values value 27   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 37        | User-defined values value 28   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 38        | User-defined values value 29   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |
| <b>0x2082</b> | 39        | User-defined values value 30   | <i>Integer value</i> | See operand table in appendix | U16  | 2   | RW  |

#### 7.1.47 Copy/initialize measurement programs (Index 0x2083)

| Index         | Sub-Index | Description   | Value               | Meaning of value  | Type | Len | R/W |
|---------------|-----------|---|---------------------|---|------|-----|-----|
| <b>0x2083</b> | 0         | Number of subindices  | 16                  |   | U8   | 1   | RO  |
| <b>0x2083</b> | 1 .. 9    | Reserved  | -                   | -   |      | X   | X   |
| <b>0x2083</b> | 10        | Meas. program number source<br><br><b>Note:</b> The settings from indices 10 - 12 are being adopted through indices 13, 14 or 15. | 0 ... 31<br>0...127 | In the standard device<br>In the corresponding device version | U16  | 2   | WO  |

| Index  | Sub-Index | Description   | Value               | Meaning of value  | Type | Len | R/W |
|--------|-----------|---|---------------------|---|------|-----|-----|
| 0x2083 | 11        | Meas. program number Target start<br><br><b>Note:</b> The settings from indices 10 - 12 are being adopted through indices 13, 14 or 15. | 0 ... 31<br>0...127 | In the standard device<br>In the corresponding device version | U16  | 2   | WO  |
| 0x2083 | 12        | Meas. program number Target end<br><br><b>Note:</b> The settings from indices 10 - 12 are being adopted through indices 13, 14 or 15.   | 0 ... 31<br>0...127 | In the standard device<br>In the corresponding device version | U16  | 2   | WO  |
| 0x2083 | 13        | Copy whole program setup<br><br><b>Note:</b> Copy according to entries in indices 10 - 12.  | EVENT               | Writing an arbitrary byte initiates action                    | U8   | 1   | WO  |
| 0x2083 | 14        | Copy sensor setup<br><br><b>Note:</b> Copy according to entries in indices 10 - 12.   | EVENT               | Writing an arbitrary byte initiates action                    | U8   | 1   | WO  |
| 0x2083 | 15        | Initialize selected programs<br><br><b>Note:</b> Initializing according to indices 11 - 12.   | EVENT               | Writing an arbitrary byte initiates action                    | U8   | 1   | WO  |
| 0x2083 | 16        | Initialize all measurement programs   | EVENT               | Writing an arbitrary byte initiates action                    | U8   | 1   | WO  |

## 7.1.48 Reference curve Y1, Y2 (Index 0x2084 to 0x2088)

Index/subindex data on request

### 7.1.49 Test operation (Index 0x2089)

| Index  | Sub-Index | Description                          | Value              | Meaning of value           | Type | Len | R/W |
|--------|-----------|--------------------------------------|--------------------|----------------------------|------|-----|-----|
| 0x2089 | 0         | Number of subindices                 | 12                 |                            | U8   | 1   | RO  |
| 0x2089 | 1...9     | Reserved                             |                    |                            |      |     |     |
| 0x2089 | 10        | Current measurement value channel X  | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2089 | 11        | Current measurement value channel Y1 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2089 | 12        | Current measurement value channel Y2 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |

### 7.1.50 Zoom and autoscale (Index 0x2090)

| Index  | Sub-Index | Description  | Value              | Meaning of value              | Type | Len | R/W |
|--------|-----------|--|--------------------|-------------------------------|------|-----|-----|
| 0x2090 | 0         | Number of subindices   | 20                 |                               | U8   | 1   | RO  |
| 0x2090 | 1...9     | Reserved   | -                  | -                             | X    | X   | X   |
| 0x2090 | 10        | Switching autoscale/fix scale  | 0<br>1             | Autoscale off<br>Autoscale on | U16  | 2   | RW  |
| 0x2090 | 11        | Fix scale Xmin channel Y1<br><br><b>Note:</b> At the end, entry must be adopted through subindex 15. | <i>Float value</i> | Float according to IEEE754    | FLT  | 4   | RW  |
| 0x2090 | 12        | Fix scale Xmax channel Y1<br><br><b>Note:</b> At the end, entry must be adopted through subindex 15. | <i>Float value</i> | Float according to IEEE754    | FLT  | 4   | RW  |
| 0x2090 | 13        | Fix scale Ymin channel Y1<br><br><b>Note:</b> At the end, entry must be adopted through subindex 15. | <i>Float value</i> | Float according to IEEE754    | FLT  | 4   | RW  |
| 0x2090 | 14        | Fix scale Ymax channel Y1<br><br><b>Note:</b> At the end, entry must be adopted through subindex 15. | <i>Float value</i> | Float according to IEEE754    | FLT  | 4   | RW  |

| Index  | Sub-Index | Description  | Value       | Meaning of value                           | Type | Len | R/W |
|--------|-----------|--|-------------|--|------|-----|-----|
| 0x2090 | 15        | Copy fix scale channel Y1<br><br><b>Note:</b> Values entered into indices 11 - 14 are adopted.       | EVENT!      | Writing an arbitrary byte initiates action | U8   | 1   | WO  |
| 0x2090 | 16        | Fix scale Xmin channel Y2<br><br><b>Note:</b> At the end, entry must be adopted through subindex 20. | Float value | Float according to IEEE754                 | FLT  | 4   | RW  |
| 0x2090 | 17        | Fix scale Xmax channel Y2<br><br><b>Note:</b> At the end, entry must be adopted through subindex 20. | Float value | Float according to IEEE754                 | FLT  | 4   | RW  |
| 0x2090 | 18        | Fix scale Ymin channel Y2<br><br><b>Note:</b> At the end, entry must be adopted through subindex 20. | Float value | Float according to IEEE754                 | FLT  | 4   | RW  |
| 0x2090 | 19        | Fix scale Ymax channel Y2<br><br><b>Note:</b> At the end, entry must be adopted through subindex 20. | Float value | Float according to IEEE754                 | FLT  | 4   | RW  |
| 0x2090 | 20        | Copy fix scale channel Y2<br><br><b>Note:</b> Values entered into indices 16 - 19 are adopted.       | EVENT!      | Writing an arbitrary byte initiates action | U8   | 1   | WO  |

## 7.2 Measurement results

### 7.2.1 Status of measurement (index 0x2100)

| Index  | Sub-Index | Description   | Value                | Meaning of value  | Type | Len | R/W |
|--------|-----------|---|----------------------|---|------|-----|-----|
| 0x2100 | 0         | Number of subindices  | 12                   |   | U8   | 1   | RO  |
| 0x2100 | 1...9     | Reserved  |                      |   |      | X   | X   |
| 0x2100 | 10        | Index of the last measured value of the current curve<br><br><b>Caution:</b> The number of the pair of values is shown on the display. The subindex begins at 0, the number at 1! | 16 Bit Integer value | 0 means that there is no measurement curve                                  | U16  | 2   | RO  |
| 0x2100 | 11        | Running measurement curve counter   | 32 Bit Integer value | This counter is incremented by 1 when a measurement curve is newly acquired | U32  | 4   | RO  |
| 0x2100 | 12        | Amount of curves in current array of curves   | 0...10               | Integer value between 0 and 10  | U16  | 2   | RO  |

### 7.2.2 Further information for current measurement curve (index 0x2101)

| Index  | Sub-Index | Description   | Value                | Meaning of value | Type | Len | R/W |
|--------|-----------|---|----------------------|------------------|------|-----|-----|
| 0x2101 | 0         | Number of subindices  | 22                   |                  | U8   | 1   | RO  |
| 0x2101 | 1...9     | Reserved  | -                    | -                |      | X   | X   |
| 0x2101 | 10        | Toolcounter   | 32 Bit Integer value |                  | U32  | 4   | RO  |
| 0x2101 | 11        | NOK counter (sum)   | 32 Bit Integer value |                  | U32  | 4   | RO  |
| 0x2101 | 12        | Total evaluation  | 0<br>1               | NOK<br>OK        | U16  | 2   | RO  |
| 0x2101 | 13        | Evaluation channel Y1   | 0<br>1               | NOK<br>OK        | U16  | 2   | RO  |
| 0x2101 | 14        | Evaluation channel Y2   | 0<br>1               | NOK<br>OK        | U16  | 2   | RO  |
| 0x2101 | 15        | Index of the curve's return point<br><br><b>Caution:</b> The number of the pair of values is shown on the display. The subindex begins at 0, the number at 1! | 16 Bit Integer value |                  | U16  | 2   | RO  |

| Index  | Sub-Index | Description   | Value   | Meaning of value          | Type  | Len | R/W |
|--------|-----------|---|---|---------------------------|-------|-----|-----|
| 0x2101 | 16        | Index of the last measured value of the curve<br><br><b>Caution:</b> The number of the pair of values is shown on the display. The subindex begins at 0, the number at 1! | 16 Bit Integer value                              |                           | U16   | 2   | RO  |
| 0x2101 | 17        | Status overdrive of the A/D converter   | 0<br>1  | No overdrive<br>Overdrive | U16   | 2   | RO  |
| 0x2101 | 18        | Date of recording   | String in format dd.mm.yyyy                       |                           | STR10 | 10  | RO  |
| 0x2101 | 19        | Time of recording hh:mm:ss  | String in format hh:mm:ss                         |                           | STR8  | 8   | RO  |
| 0x2101 | 20        | Unit channel X  | String with max. 4 characters, e.g. "N" or "inch" |                           | STR4  | 4   | RO  |
| 0x2101 | 21        | Unit channel Y1   | String with max. 4 characters, e.g. "N" or "inch" |                           | STR4  | 4   | RO  |
| 0x2101 | 22        | Unit channel Y2   | String with max. 4 characters, e.g. "N" or "inch" |                           | STR4  | 4   | RO  |

### 7.2.3 Further information for current pretrigger curve (index 0x2102)

| Index  | Sub-Index | Description                                | Value                | Meaning of value              | Type | Len | R/W |
|--------|-----------|--|----------------------|-------------------------------|------|-----|-----|
| 0x2102 | 0         | Number of subindices                       | 13                   |                               | U8   | 1   | RO  |
| 0x2102 | 1...9     | Reserved                                   | -                    | -                             | X    | X   |     |
| 0x2102 | 10        | Pretrigger recording on/off                | 0<br>1               | off<br>on                     | U16  | 2   | RO  |
| 0x2102 | 11        | Whole amount of pretrigger values          | 32 Bit Integer value |                               | U32  | 4   | RO  |
| 0x2102 | 12        | Index of first pretrigger value (0...255)  | 0...255              | Integer value between 0...255 | U16  | 2   | RO  |
| 0x2102 | 13        | Index of X-last pretrigger value (0...255) | 0...255              | Integer value between 0...255 | U16  | 2   | RO  |

### 7.2.4 General curve data channel Y1 (index 0x2103)

| Index  | Sub-Index | Description                | Value              | Meaning of value           | Type | Len | R/W |
|--------|-----------|----------------------------|--------------------|----------------------------|------|-----|-----|
| 0x2103 | 0         | Number of subindices       | 23                 |                            | U8   | 1   | RO  |
| 0x2103 | 1...9     | Reserved                   | -                  | -                          |      | X   | X   |
| 0x2103 | 10        | X-minimum, X-coordinate    | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 11        | X-minimum, Y1-coordinate   | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 12        | X-maximum, X-coordinate    | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 13        | X-maximum, Y1-coordinate   | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 14        | Y1-minimum, X-coordinate   | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 15        | Y1-minimum, Y1-coordinate  | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 16        | Y1-maximum, X-coordinate   | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 17        | Y1-maximum, Y1-coordinate  | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 18        | First value X-coordinate   | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 19        | First value Y1-coordinate  | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 20        | Last value X-coordinate    | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 21        | Last value Y1-coordinate   | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 22        | Return point X-coordinate  | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2103 | 23        | Return point Y1-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |

### 7.2.5 General curve data channel Y2 (index 0x21014)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2104 | 0         | Number of subindices | 23    |                  | U8   | 1   | RO  |
| 0x2104 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2104 | 10        | See index 0x2103     |       |                  |      |     |     |

### 7.2.6 Request measurement results of user-defined values (index 0x2105)

| Index  | Sub-Index | Description               | Value                  | Meaning of value  | Type   | Len | R/W |
|--------|-----------|---------------------------|------------------------|---|--------|-----|-----|
| 0x2105 | 0         | Number of subindices      | 99                     |   | U8     | 1   | RO  |
| 0x2105 | 1...9     | Reserved                  | -                      | -   |        | X   | X   |
| 0x2105 | 10        | User-defined value 1 name | <i>String with the</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16  | RO  |

| Index         | Sub-Index | Description                               | Value  | Meaning of value  | Type   | Len | R/W |
|---------------|-----------|---|--|---|--------|-----|-----|
|               |           |   | <i>designator of the value</i>                           |   |        |     |     |
| <b>0x2105</b> | 11        | User-defined value<br>1 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT    | 4   | RO  |
| <b>0x2105</b> | 12        | User-defined value<br>1 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4  | 4   | RO  |
| <b>0x2105</b> | 13        | User-defined value<br>2 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16 | 16  | RO  |
| <b>0x2105</b> | 14        | User-defined value<br>2 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT    | 4   | RO  |
| <b>0x2105</b> | 15        | User-defined value<br>2 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4  | 4   | RO  |
| <b>0x2105</b> | 16        | User-defined value<br>3 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16 | 16  | RO  |
| <b>0x2105</b> | 17        | User-defined value<br>3 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT    | 4   | RO  |
| <b>0x2105</b> | 18        | User-defined value<br>3 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4  | 4   | RO  |
| <b>0x2105</b> | 19        | User-defined value<br>4 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16 | 16  | RO  |
| <b>0x2105</b> | 20        | User-defined value<br>4 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT    | 4   | RO  |
| <b>0x2105</b> | 21        | User-defined value<br>4 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4  | 4   | RO  |
| <b>0x2105</b> | 22        | User-defined value<br>5 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16 | 16  | RO  |
| <b>0x2105</b> | 23        | User-defined value<br>5 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT    | 4   | RO  |

| Index         | Sub-Index | Description                                  | Value  | Meaning of value  | Type      | Len | R/W |
|---------------|-----------|--|--|---|-----------|-----|-----|
| <b>0x2105</b> | 24        | User-defined value<br>5 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4  | 4   | RO  |
| <b>0x2105</b> | 25        | User-defined value<br>6 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16 | 16  | RO  |
| <b>0x2105</b> | 26        | User-defined value<br>6 measurement<br>value | <i>Float value</i>   | Float according to<br>IEEE754   | FLT       | 4   | RO  |
| <b>0x2105</b> | 27        | User-defined value<br>6 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4  | 4   | RO  |
| <b>0x2105</b> | 28        | User-defined value<br>7 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16 | 16  | RO  |
| <b>0x2105</b> | 29        | User-defined value<br>7 measurement<br>value | <i>Float value</i>   | Float according to<br>IEEE754   | FLT       | 4   | RO  |
| <b>0x2105</b> | 30        | User-defined value<br>7 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4  | 4   | RO  |
| <b>0x2105</b> | 31        | User-defined value<br>8 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16 | 16  | RO  |
| <b>0x2105</b> | 32        | User-defined value<br>8 measurement<br>value | <i>Float value</i>   | Float according to<br>IEEE754   | FLT       | 4   | RO  |
| <b>0x2105</b> | 33        | User-defined value<br>8 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4  | 4   | RO  |
| <b>0x2105</b> | 34        | User-defined value<br>9 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16 | 16  | RO  |
| <b>0x2105</b> | 35        | User-defined value<br>9 measurement<br>value | <i>Float value</i>   | Float according to<br>IEEE754   | FLT       | 4   | RO  |
| <b>0x2105</b> | 36        | User-defined value<br>9 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4  | 4   | RO  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                      | <b>Value</b>   | <b>Meaning of value</b>   | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---|--|---|-------------|------------|------------|
| <b>0x2105</b> | 37               | User-defined value 10 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16      | 16         | RO         |
| <b>0x2105</b> | 38               | User-defined value 10 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT         | 4          | RO         |
| <b>0x2105</b> | 39               | User-defined value 10 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4       | 4          | RO         |
| <b>0x2105</b> | 40               | User-defined value 11 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16      | 16         | RO         |
| <b>0x2105</b> | 41               | User-defined value 11 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT         | 4          | RO         |
| <b>0x2105</b> | 42               | User-defined value 11 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4       | 4          | RO         |
| <b>0x2105</b> | 43               | User-defined value 12 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16      | 16         | RO         |
| <b>0x2105</b> | 44               | User-defined value 12 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT         | 4          | RO         |
| <b>0x2105</b> | 45               | User-defined value 12 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4       | 4          | RO         |
| <b>0x2105</b> | 46               | User-defined value 13 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16      | 16         | RO         |
| <b>0x2105</b> | 47               | User-defined value 13 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT         | 4          | RO         |
| <b>0x2105</b> | 48               | User-defined value 13 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4       | 4          | RO         |
| <b>0x2105</b> | 49               | User-defined value 14 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16      | 16         | RO         |
| <b>0x2105</b> | 50               | User-defined value 14 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT         | 4          | RO         |

| Index         | Sub-Index | Description                                   | Value  | Meaning of value  | Type      | Len | R/W |
|---------------|-----------|---|--|---|-----------|-----|-----|
| <b>0x2105</b> | 51        | User-defined value<br>14 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4  | 4   | RO  |
| <b>0x2105</b> | 52        | User-defined value<br>15 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16 | 16  | RO  |
| <b>0x2105</b> | 53        | User-defined value<br>15 measurement<br>value | Float value  | Float according to<br>IEEE754   | FLT       | 4   | RO  |
| <b>0x2105</b> | 54        | User-defined value<br>15 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4  | 4   | RO  |
| <b>0x2105</b> | 55        | User-defined value<br>16 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16 | 16  | RO  |
| <b>0x2105</b> | 56        | User-defined value<br>16 measurement<br>value | Float value  | Float according to<br>IEEE754   | FLT       | 4   | RO  |
| <b>0x2105</b> | 57        | User-defined value<br>16 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4  | 4   | RO  |
| <b>0x2105</b> | 58        | User-defined value<br>17 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16 | 16  | RO  |
| <b>0x2105</b> | 59        | User-defined value<br>17 measurement<br>value | Float value  | Float according to<br>IEEE754   | FLT       | 4   | RO  |
| <b>0x2105</b> | 60        | User-defined value<br>17 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4  | 4   | RO  |
| <b>0x2105</b> | 61        | User-defined value<br>18 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16 | 16  | RO  |
| <b>0x2105</b> | 62        | User-defined value<br>18 measurement<br>value | Float value  | Float according to<br>IEEE754   | FLT       | 4   | RO  |
| <b>0x2105</b> | 63        | User-defined value<br>18 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4  | 4   | RO  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                            | <b>Value</b>   | <b>Meaning of value</b>   | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---|--|---|-------------|------------|------------|
| <b>0x2105</b> | 64               | User-defined value<br>19 name                 | String with<br>the<br>designator of<br>the value                         | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16   | 16         | RO         |
| <b>0x2105</b> | 65               | User-defined value<br>19 measurement<br>value | Float value  | Float according to<br>IEEE754   | FLT         | 4          | RO         |
| <b>0x2105</b> | 66               | User-defined value<br>19 unit                 | String with<br>max. 4<br>characters,<br>e.g. "N" or<br>"inch"            | See operand table in<br>appendix  | STR<br>4    | 4          | RO         |
| <b>0x2105</b> | 67               | User-defined value<br>20 name                 | String with<br>the<br>designator of<br>the value                         | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16   | 16         | RO         |
| <b>0x2105</b> | 68               | User-defined value<br>20 measurement<br>value | Float value  | Float according to<br>IEEE754   | FLT         | 4          | RO         |
| <b>0x2105</b> | 69               | User-defined value<br>20 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4    | 4          | RO         |
| <b>0x2105</b> | 70               | User-defined value<br>21 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16   | 16         | RO         |
| <b>0x2105</b> | 71               | User-defined value<br>21 measurement<br>value | <i>Float value</i>   | Float according to<br>IEEE754   | FLT         | 4          | RO         |
| <b>0x2105</b> | 72               | User-defined value<br>21 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4    | 4          | RO         |
| <b>0x2105</b> | 73               | User-defined value<br>22 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16   | 16         | RO         |
| <b>0x2105</b> | 74               | User-defined value<br>22 measurement<br>value | <i>Float value</i>   | Float according to<br>IEEE754   | FLT         | 4          | RO         |
| <b>0x2105</b> | 75               | User-defined value<br>22 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4    | 4          | RO         |
| <b>0x2105</b> | 76               | User-defined value<br>23 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16   | 16         | RO         |
| <b>0x2105</b> | 77               | User-defined value<br>23 measurement<br>value | <i>Float value</i>   | Float according to<br>IEEE754   | FLT         | 4          | RO         |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                      | <b>Value</b>   | <b>Meaning of value</b>   | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---|--|---|-------------|------------|------------|
| <b>0x2105</b> | 78               | User-defined value 23 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4       | 4          | RO         |
| <b>0x2105</b> | 79               | User-defined value 24 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16      | 16         | RO         |
| <b>0x2105</b> | 80               | User-defined value 24 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT         | 4          | RO         |
| <b>0x2105</b> | 81               | User-defined value 24 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4       | 4          | RO         |
| <b>0x2105</b> | 82               | User-defined value 25 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16      | 16         | RO         |
| <b>0x2105</b> | 83               | User-defined value 25 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT         | 4          | RO         |
| <b>0x2105</b> | 84               | User-defined value 25 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4       | 4          | RO         |
| <b>0x2105</b> | 85               | User-defined value 26 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16      | 16         | RO         |
| <b>0x2105</b> | 86               | User-defined value 26 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT         | 4          | RO         |
| <b>0x2105</b> | 87               | User-defined value 26 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4       | 4          | RO         |
| <b>0x2105</b> | 88               | User-defined value 27 name              | <i>String with the designator of the value</i>           | Designator = "0" means that no value is defined for this value number | STR 16      | 16         | RO         |
| <b>0x2105</b> | 89               | User-defined value 27 measurement value | <i>Float value</i>                                       | Float according to IEEE754  | FLT         | 4          | RO         |
| <b>0x2105</b> | 90               | User-defined value 27 unit              | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix   | STR 4       | 4          | RO         |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                            | <b>Value</b>   | <b>Meaning of value</b>   | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---|--|---|-------------|------------|------------|
| <b>0x2105</b> | 91               | User-defined value<br>28 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16   | 16         | RO         |
| <b>0x2105</b> | 92               | User-defined value<br>28 measurement<br>value | <i>Float value</i>   | Float according to<br>IEEE754   | FLT         | 4          | RO         |
| <b>0x2105</b> | 93               | User-defined value<br>28 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4    | 4          | RO         |
| <b>0x2105</b> | 94               | User-defined value<br>29 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16   | 16         | RO         |
| <b>0x2105</b> | 95               | User-defined value<br>29 measurement<br>value | <i>Float value</i>   | Float according to<br>IEEE754   | FLT         | 4          | RO         |
| <b>0x2105</b> | 96               | User-defined value<br>29 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4    | 4          | RO         |
| <b>0x2105</b> | 97               | User-defined value<br>30 name                 | <i>String with<br/>the<br/>designator of<br/>the value</i>               | Designator = "0" means<br>that no value is defined for<br>this value number | STR<br>16   | 16         | RO         |
| <b>0x2105</b> | 98               | User-defined value<br>30 measurement<br>value | <i>Float value</i>   | Float according to<br>IEEE754   | FLT         | 4          | RO         |
| <b>0x2105</b> | 99               | User-defined value<br>30 unit                 | <i>String with<br/>max. 4<br/>characters,<br/>e.g. "N" or<br/>"inch"</i> | See operand table in<br>appendix  | STR<br>4    | 4          | RO         |

**7.2.7 Statistic measurement result evaluation element window 1 (EvElem 1)**

Index/subindex data on request

**7.2.8 Statistic measurement result evaluation element window 2 (EvElem 2)**

Index/subindex data on request

**7.2.9 Statistic measurement result evaluation element window 3 (EvElem 3)**

Index/subindex data on request

**7.2.10 Statistic measurement result evaluation element window 4 (EvElem 4)**

Index/subindex data on request

**7.2.11 Statistic measurement result evaluation element window 5 (EvElem 5)**

Index/subindex data on request

**7.2.12 Statistic measurement result evaluation element window 6 (EvElem 6)**

Index/subindex data on request

**7.2.13 Statistic measurement result evaluation element window 7 (EvElem 7)**

Index/subindex data on request

**7.2.14 Statistic measurement result evaluation element window 8 (EvElem 8)**

Index/subindex data on request

**7.2.15 Statistic measurement result evaluation element window 9 (EvElem 9)**

Index/subindex data on request

**7.2.16 Statistic measurement result evaluation element window 10 (EvElem 10)**

Index/subindex data on request

**7.2.17 Statistic measurement result evaluation element threshold 1 (EvElem 11)**

Index/subindex data on request

**7.2.18 Statistic measurement result evaluation element threshold 2 (EvElem 12)**

Index/subindex data on request

**7.2.19 Statistic measurement result evaluation element threshold 3 (EvElem 13)**

Index/subindex data on request

**7.2.20 Statistic measurement result evaluation element threshold 4 (EvElem 14)**

Index/subindex data on request

**7.2.21 Statistic measurement result evaluation element trapezoid window X1  
(EvElem 15)**

Inde /subindex data on request

**7.2.22 Statistic measurement result evaluation element trapezoid window X2  
(EvElem 16)**

Index/subindex data on request

**7.2.23 Statistic measurement result evaluation element trapezoid window Y1  
(EvElem 17)**

Index/subindex data on request

**7.2.24 Statistic measurement result evaluation element trapezoid window Y2  
(EvElem 18)**

Index/subindex data on request

**7.2.25 Statistic measurement result evaluation element envelope 1 (EvElem 19)**

Index/subindex data on request

**7.2.26 Statistic measurement result evaluation element envelope 2 (EvElem 20)**

Index/subindex data on request

**7.2.27 Statistic measurement result evaluation element mathematical calculation  
1 (EvElem 21)**

Index/subindex data on request

**7.2.28 Statistic measurement result evaluation element mathematical calculation  
2 (EvElem 22)**

Index/subindex data on request

**7.2.29 Statistic measurement result evaluation element mathematical calculation  
3 (EvElem 23)**

Index/subindex data on request

**7.2.30 Statistic measurement result evaluation element mathematical calculation  
4 (EvElem 24)**

Index/subindex data on request

### 7.2.31 Statistic measurement result evaluation element mathematical calculation

#### 5 (EvElem 25)

Index/subindex data on request

### 7.2.32 Statistic measurement result evaluation element mathematical calculation

#### 6 (EvElem 26)

Index/subindex data on request

### 7.2.33 Read-out X-coordinates of current measurement curve (index 0x2132)

| Index  | Sub-Index | Description   | Value                         | Meaning of value | Type | Len | R/W |
|--------|-----------|---|-------------------------------|------------------|------|-----|-----|
| 0x2132 | 0         | Number of subindices  | 11                            |                  | U8   | 1   | RO  |
| 0x2132 | 1...9     | Reserved  | -                             | -                |      | X   | X   |
| 0x2132 | 10        | Index of the last coordinate; if 0, there is no curve   | <i>Integer value 0...4999</i> |                  | U32  | 4   | RO  |
| 0x2132 | 11        | Read curve values<br><br>The values are read as a binary array. The floating point numbers are encoded accordinaly to IEEE754 und being transferred without any separators.<br>The last curve index shoud be read at index 10.<br><br>Number of curve values = last index + 1 | -                             | -                |      |     | RO  |

### 7.2.34 Read-out Y1-coordinates of current measurement curve (index 0x2133)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2133 | 0         | Number of subindices | 11    |                  | U8   | 1   | RO  |
| 0x2133 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2133 | 10...11   | See index 0x2132     |       |                  |      | X   | X   |

### 7.2.35 Read-out Y2-coordinates of current measurement curve (index 0x2134)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2134 | 0         | Number of subindices | 11    |                  | U8   | 1   | RO  |
| 0x2134 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2134 | 10..11    | See index 0x2132     |       |                  |      | X   | X   |

### 7.2.36 Read-out X-coordinates of current pretrigger curve (index 0x2135)

| Index  | Sub-Index | Description   | Value                        | Meaning of value | Type | Len | R/W |
|--------|-----------|---|------------------------------|------------------|------|-----|-----|
| 0x2135 | 0         | Number of subindices  | 11                           |                  | U8   | 1   | RO  |
| 0x2135 | 1...9     | Reserved  | -                            | -                |      | X   | X   |
| 0x2135 | 10        | Index of the last coordinate; if 0, there is no curve   | <i>Integer value 0...255</i> |                  | U32  | 4   | RO  |
| 0x2135 | 11        | Read pretrigger curve values<br><br>The values are read as a binary array. The floating point numbers are encoded accordinaly to IEEE754 und being transferred without any separators. The last curve index shoud be read at index 10.<br><br>Number of curve values = last index + 1 | -                            | -                |      |     | RO  |

### 7.2.37 Read-out Y1-coordinates of current pretrigger curve (index 0x2136)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2136 | 0         | Number of subindices | 11    |                  | U8   | 1   | RO  |
| 0x2136 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2136 | 10..11    | See index 0x2135     |       |                  |      | X   | X   |

### 7.2.38 Read-out Y2-coordinates of current pretrigger curve (index 0x2137)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2137 | 0         | Number of subindices | 11    |                  | U8   | 1   | RO  |
| 0x2137 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2137 | 10..11    | See index 0x2135     |       |                  |      | X   | X   |

### 7.2.39 Evaluation results window 1 (index 0x2138)

| Index  | Sub-Index | Description   | Value                              | Meaning of value           | Type | Len | R/W |
|--------|-----------|---|------------------------------------|----------------------------|------|-----|-----|
| 0x2138 | 0         | Number of subindices                                | 28                                 |                            | U8   | 1   | RO  |
| 0x2138 | 1...9     | Reserved  | -                                  | -                          |      | X   | X   |
| 0x2138 | 10        | Window 1 evaluation results OK/NOK                  | 0<br>1                             | NOK<br>OK                  | U16  | 2   | RO  |
| 0x2138 | 11        | Window 1 NOK counter                                | <i>32bit-Integer value &gt;= 0</i> |                            | U32  | 4   | RO  |
| 0x2138 | 12        | Window 1 entry of curve X-coordinate                | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2138 | 13        | Window 1 entry of curve Y-coordinate                | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2138 | 14        | Window 1 exit of curve X-coordinate                 | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2138 | 15        | Window 1 exit of curve Y-coordinate                 | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2138 | 16        | Window 1 absolute Y- maximum in window X-coordinate | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2138 | 17        | Window 1 absolute Y-maximum in window Y-coordinate  | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2138 | 18        | Window 1 absolute Y-minimum in window X-coordinate  | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2138 | 19        | Window 1 absolute Y-minimum in window Y-coordinate  | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2138 | 20        | Window 1 local Y-maximum in window X-coordinate     | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2138 | 21        | Window 1 local Y-maximum in window Y-coordinate     | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                              | <b>Value</b>       | <b>Meaning of value</b>    | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---|--------------------|----------------------------|-------------|------------|------------|
| <b>0x2138</b> | 22               | Window 1 local Y-minimum in window X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2138</b> | 23               | Window 1 local Y-minimum in window Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2138</b> | 24               | Window 1 bend X-coordinate                      | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2138</b> | 25               | Window 1 bend Y-coordinate                      | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2138</b> | 26               | Window 1 gradient value                         | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2138</b> | 27               | Window 1 Y-mean value                           | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2138</b> | 28               | Window 1 area below curve                       | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |

#### 7.2.40 Evaluation results window 2 (index 0x2139)

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>   | <b>Value</b> | <b>Meaning of value</b> | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|----------------------|--------------|-------------------------|-------------|------------|------------|
| <b>0x2139</b> | 0                | Number of subindices | 28           |                         | U8          | 1          | RO         |
| <b>0x2139</b> | 1...9            | Reserved             | -            | -                       |             | X          | X          |
| <b>0x2139</b> | 10...            | See index 0x2138     |              |                         |             | X          | X          |

#### 7.2.41 Evaluation results window 3 (index 0x2140)

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>   | <b>Value</b> | <b>Meaning of value</b> | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|----------------------|--------------|-------------------------|-------------|------------|------------|
| <b>0x2140</b> | 0                | Number of subindices | 28           |                         | U8          | 1          | RO         |
| <b>0x2140</b> | 1...9            | Reserved             | -            | -                       |             | X          | X          |
| <b>0x2140</b> | 10...            | See index 0x2138     |              |                         |             | X          | X          |

#### 7.2.42 Evaluation results window 4 (index 0x2141)

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>   | <b>Value</b> | <b>Meaning of value</b> | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|----------------------|--------------|-------------------------|-------------|------------|------------|
| <b>0x2141</b> | 0                | Number of subindices | 28           |                         | U8          | 1          | RO         |
| <b>0x2141</b> | 1...9            | Reserved             | -            | -                       |             | X          | X          |
| <b>0x2141</b> | 10...            | See index 0x2138     |              |                         |             | X          | X          |

### 7.2.43 Evaluation results window 5 (index 0x2142)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2142 | 0         | Number of subindices | 28    |                  | U8   | 1   | RO  |
| 0x2142 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2142 | 10...     | See index 0x2138     |       |                  |      | X   | X   |

### 7.2.44 Evaluation results window 6 (index 0x2143)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2143 | 0         | Number of subindices | 28    |                  | U8   | 1   | RO  |
| 0x2143 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2143 | 10...     | See index 0x2138     |       |                  |      | X   | X   |

### 7.2.45 Evaluation results window 7 (index 0x2144)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2144 | 0         | Number of subindices | 28    |                  | U8   | 1   | RO  |
| 0x2144 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2144 | 10...     | See index 0x2138     |       |                  |      | X   | X   |

### 7.2.46 Evaluation results window 8 (index 0x2145)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2145 | 0         | Number of subindices | 28    |                  | U8   | 1   | RO  |
| 0x2145 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2145 | 10...     | See index 0x2138     |       |                  |      | X   | X   |

### 7.2.47 Evaluation results window 9 (index 0x2146)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2146 | 0         | Number of subindices | 28    |                  | U8   | 1   | RO  |
| 0x2146 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2146 | 10...     | See index 0x2138     |       |                  |      | X   | X   |

### 7.2.48 Evaluation results window 10 (index 0x2147)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2147 | 0         | Number of subindices | 28    |                  | U8   | 1   | RO  |
| 0x2147 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2147 | 10...     | See index 0x2138     |       |                  |      | X   | X   |

### 7.2.49 Evaluation results threshold 1 (index 0x2148)

| Index  | Sub-Index | Description  | Value                              | Meaning of value           | Type | Len | R/W |
|--------|-----------|--|------------------------------------|----------------------------|------|-----|-----|
| 0x2148 | 0         | Number of subindices                                     | 26                                 |                            | U8   | 1   | RO  |
| 0x2148 | 1...9     | Reserved   | -                                  | -                          |      | X   | X   |
| 0x2148 | 10        | Threshold 1 evaluation result OK/NOK                     | 0<br>1                             | NOK<br>OK                  | U16  | 2   | RO  |
| 0x2148 | 11        | Threshold 1 NOK counter                                  | <i>32bit-Integer value &gt;= 0</i> |                            | U32  | 4   | RO  |
| 0x2148 | 12        | Threshold intersection point 1 X-coordinate              | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2148 | 13        | Threshold intersection point 1 Y-coordinate              | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2148 | 14        | Threshold 1 absolute Y-maximum in threshold X-coordinate | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2148 | 15        | Threshold 1 absolute Y-maximum in threshold Y-coordinate | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2148 | 16        | Threshold 1 absolute Y-minimum in threshold X-coordinate | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2148 | 17        | Threshold 1 absolute Y-minimum in threshold Y-coordinate | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2148 | 18        | Threshold 1 local Y-maximum in threshold X-coordinate    | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2148 | 19        | Threshold 1 local Y-maximum in threshold                 | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |

| Index         | Sub-Index | Description   | Value              | Meaning of value           | Type | Len | R/W |
|---------------|-----------|---|--------------------|----------------------------|------|-----|-----|
|               |           | Y-coordinate  |                    |                            |      |     |     |
| <b>0x2148</b> | 20        | Threshold 1 local Y-minimum in threshold X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2148</b> | 21        | Threshold 1 local Y-minimum in threshold Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2148</b> | 22        | Threshold 1 bend X-coordinate                         | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2148</b> | 23        | Threshold 1 bend Y-coordinate                         | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2148</b> | 24        | Threshold 1 gradient value                            | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2148</b> | 25        | Threshold 1 Y-mean value                              | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2148</b> | 26        | Threshold 1 area below curve                          | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |

#### 7.2.50 Evaluation results threshold 2 (index 0x2149)

| Index         | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|---------------|-----------|----------------------|-------|------------------|------|-----|-----|
| <b>0x2149</b> | 0         | Number of subindices | 26    |                  | U8   | 1   | RO  |
| <b>0x2149</b> | 1...9     | Reserved             | -     | -                |      | X   | X   |
| <b>0x2149</b> | 10...     | See index 0x2148     |       |                  |      | X   | X   |

#### 7.2.51 Evaluation results threshold 3 (index 0x2150)

| Index         | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|---------------|-----------|----------------------|-------|------------------|------|-----|-----|
| <b>0x2150</b> | 0         | Number of subindices | 26    |                  | U8   | 1   | RO  |
| <b>0x2150</b> | 1...9     | Reserved             | -     | -                |      | X   | X   |
| <b>0x2150</b> | 10...     | See index 0x2148     |       |                  |      | X   | X   |

#### 7.2.52 Evaluation results threshold 4 (index 0x2151)

| Index         | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|---------------|-----------|----------------------|-------|------------------|------|-----|-----|
| <b>0x2151</b> | 0         | Number of subindices | 26    |                  | U8   | 1   | RO  |
| <b>0x2151</b> | 1...9     | Reserved             | -     | -                |      | X   | X   |
| <b>0x2151</b> | 10...     | See index 0x2148     |       |                  |      | X   | X   |

### 7.2.53 Evaluation results trapezoid window X1 (index 0x2152)

| Index  | Sub-Index | Description                                 | Value                              | Meaning of value           | Type | Len | R/W |
|--------|-----------|---|------------------------------------|----------------------------|------|-----|-----|
| 0x2152 | 0         | Number of subindices                        | 15                                 |                            | U8   | 1   | RO  |
| 0x2152 | 1...9     | Reserved                                    | -                                  | -                          |      | X   | X   |
| 0x2152 | 10        | Trapezoid X 1 evaluation result OK/NOK      | 0<br>1                             | NOK<br>OK                  | U16  | 2   | RO  |
| 0x2152 | 11        | Trapezoid X 1 NOK counter                   | <i>32bit-Integer value &gt;= 0</i> |                            | U32  | 4   | RO  |
| 0x2152 | 12        | Trapezoid X 1 entry coordinate X-coordinate | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2152 | 13        | Trapezoid X 1 entry coordinate Y-coordinate | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2152 | 14        | Trapezoid X 1 exit coordinate X-coordinate  | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2152 | 15        | Trapezoid X 1 exit coordinate Y-coordinate  | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |

### 7.2.54 Evaluation results trapezoid window X2 (index 0x2153)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2153 | 0         | Number of subindices | 15    |                  | U8   | 1   | RO  |
| 0x2153 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2153 | 10...     | See index 0x2152     |       |                  |      | X   | X   |

### 7.2.55 Evaluation results trapezoid window Y1 (index 0x2154)

| Index  | Sub-Index | Description                                | Value                              | Meaning of value           | Type | Len | R/W |
|--------|-----------|--|------------------------------------|----------------------------|------|-----|-----|
| 0x2154 | 0         | Number of subindices                       | 15                                 |                            | U8   | 1   | RO  |
| 0x2154 | 1...9     | Reserved                                   | -                                  | -                          |      | X   | X   |
| 0x2154 | 10        | Trapezoid Y1 evaluation results OK/NOK     | 0<br>1                             | NOK<br>OK                  | U16  | 2   | RO  |
| 0x2154 | 11        | Trapezoid Y1 NOK counter                   | <i>32bit-Integer value &gt;= 0</i> |                            | U32  | 4   | RO  |
| 0x2154 | 12        | Trapezoid Y1 entry coordinate X-coordinate | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2154 | 13        | Trapezoid Y1 entry coordinate Y-coordinate | <i>Float value</i>                 | Float according to IEEE754 | FLT  | 4   | RO  |

| Index  | Sub-Index | Description                               | Value       | Meaning of value           | Type | Len | R/W |
|--------|-----------|---|-------------|----------------------------|------|-----|-----|
| 0x2154 | 14        | Trapezoid Y1 exit coordinate X-coordinate | Float value | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2154 | 15        | Trapezoid Y1 exit coordinate Y-coordinate | Float value | Float according to IEEE754 | FLT  | 4   | RO  |

#### 7.2.56 Evaluation results trapezoid window Y2 (index 0x2155)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2155 | 0         | Number of subindices | 15    |                  | U8   | 1   | RO  |
| 0x2155 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2155 | 10...     | See index 0x2154     |       |                  |      | X   | X   |

#### 7.2.57 Evaluation results envelope 1 (index 0x2156)

| Index  | Sub-Index | Description                              | Value                    | Meaning of value           | Type | Len | R/W |
|--------|-----------|--|--------------------------|----------------------------|------|-----|-----|
| 0x2156 | 0         | Number of subindices                     | 15                       |                            | U8   | 1   | RO  |
| 0x2156 | 1...9     | Reserved                                 | -                        | -                          |      | X   | X   |
| 0x2156 | 10        | Envelope 1 evaluation result OK/NOK      | 0<br>1                   | NOK<br>OK                  | U16  | 2   | RO  |
| 0x2156 | 11        | Envelope 1 NOK counter                   | 32bit-Integer value >= 0 |                            | U32  | 4   | RO  |
| 0x2156 | 12        | Envelope 1 entry coordinate X-coordinate | Float value              | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2156 | 13        | Envelope 1 entry coordinate Y-coordinate | Float value              | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2156 | 14        | Envelope 1 exit coordinate X-coordinate  | Float value              | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2156 | 15        | Envelope 1 exit coordinate Y-coordinate  | Float value              | Float according to IEEE754 | FLT  | 4   | RO  |

#### 7.2.58 Evaluation results envelope 2 (index 0x2157)

| Index  | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|--------|-----------|----------------------|-------|------------------|------|-----|-----|
| 0x2157 | 0         | Number of subindices | 15    |                  | U8   | 1   | RO  |
| 0x2157 | 1...9     | Reserved             | -     | -                |      | X   | X   |
| 0x2157 | 10...     | See index 0x2156     |       |                  |      | X   | X   |

#### 7.2.59 Evaluation results rotary switch evaluation element 1 (index 0x2158)

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                                     | <b>Value</b>       | <b>Meaning of value</b>    | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|--|--------------------|----------------------------|-------------|------------|------------|
| <b>0x2158</b> | 0                | Number of subindices                                   | 144                | -                          | U8          | 1          | RO         |
| <b>0x2158</b> | 1...9            | Reserved   | -                  | -                          |             | X          | X          |
| <b>0x2158</b> | 10               | Rotary switch evaluation element 1 number of minima    | 0...32             |                            | U16         | 2          | RO         |
| <b>0x2158</b> | 11               | Rotary switch evaluation element 1 number of maxima    | 0...32             |                            | U16         | 2          | RO         |
| <b>0x2158</b> | 12               | Rotary switch evaluation element 1 mean value minima   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 13               | Rotary switch evaluation element 1 mean value maxima   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 14               | Rotary switch evaluation element 1 Max. Y-Diff. minima | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 15               | Rotary switch evaluation element 1 Max. Y-Diff. maxima | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 16               | Rotary switch evaluation element 1 evaluation result   | 0<br>1             | NOK<br>OK                  | U16         | 2          | RO         |
| <b>0x2158</b> | 17               | Rotary switch evaluation element 1 X-coord. minima 1   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 18               | Rotary switch evaluation element 1 X-coord. minima 2   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 19               | Rotary switch evaluation element 1 X-coord. minima 3   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 20               | Rotary switch evaluation element 1 X-coord. minima 4   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 21               | Rotary switch evaluation element 1 X-coord. minima 5   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 22               | Rotary switch evaluation element 1 X-coord. minima 6   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 23               | Rotary switch evaluation element 1 X-coord. minima 7   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 24               | Rotary switch evaluation element 1 X-coord. minima 8   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 25               | Rotary switch evaluation element 1 X-coord. minima 9   | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 26               | Rotary switch evaluation element 1 X-coord. minima 10  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |

| Index         | Sub-Index | Description   | Value              | Meaning of value           | Type | Len | R/W |
|---------------|-----------|---|--------------------|----------------------------|------|-----|-----|
| <b>0x2158</b> | 27        | Rotary switch evaluation element 1 X-coord. minima 11 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 28        | Rotary switch evaluation element 1 X-coord. minima 12 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 29        | Rotary switch evaluation element 1 X-coord. minima 13 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 30        | Rotary switch evaluation element 1 X-coord. minima 14 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 31        | Rotary switch evaluation element 1 X-coord. minima 15 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 32        | Rotary switch evaluation element 1 X-coord. minima 16 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 33        | Rotary switch evaluation element 1 X-coord. minima 17 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 34        | Rotary switch evaluation element 1 X-coord. minima 18 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 35        | Rotary switch evaluation element 1 X-coord. minima 19 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 36        | Rotary switch evaluation element 1 X-coord. minima 20 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 37        | Rotary switch evaluation element 1 X-coord. minima 21 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 38        | Rotary switch evaluation element 1 X-coord. minima 22 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 39        | Rotary switch evaluation element 1 X-coord. minima 23 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 40        | Rotary switch evaluation element 1 X-coord. minima 24 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 41        | Rotary switch evaluation element 1 X-coord. minima 25 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 42        | Rotary switch evaluation element 1 X-coord. minima 26 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 43        | Rotary switch evaluation element 1 X-coord. minima 27 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 44        | Rotary switch evaluation element 1 X-coord. minima 28 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                                    | <b>Value</b>       | <b>Meaning of value</b>    | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---|--------------------|----------------------------|-------------|------------|------------|
| <b>0x2158</b> | 45               | Rotary switch evaluation element 1 X-coord. minima 29 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 46               | Rotary switch evaluation element 1 X-coord. minima 30 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 47               | Rotary switch evaluation element 1 X-coord. minima 31 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 48               | Rotary switch evaluation element 1 X-coord. minima 32 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 49               | Rotary switch evaluation element 1 Y-coord. minima 1  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 50               | Rotary switch evaluation element 1 Y-coord. minima 2  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 51               | Rotary switch evaluation element 1 Y-coord. minima 3  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 52               | Rotary switch evaluation element 1 Y-coord. minima 4  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 53               | Rotary switch evaluation element 1 Y-coord. minima 5  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 54               | Rotary switch evaluation element 1 Y-coord. minima 6  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 55               | Rotary switch evaluation element 1 Y-coord. minima 7  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 56               | Rotary switch evaluation element 1 Y-coord. minima 8  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 57               | Rotary switch evaluation element 1 Y-coord. minima 9  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 58               | Rotary switch evaluation element 1 Y-coord. minima 10 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 59               | Rotary switch evaluation element 1 Y-coord. minima 11 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 60               | Rotary switch evaluation element 1 Y-coord. minima 12 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 61               | Rotary switch evaluation element 1 Y-coord. minima 13 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 62               | Rotary switch evaluation element 1 Y-coord. minima 14 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |

| Index         | Sub-Index | Description   | Value              | Meaning of value           | Type | Len | R/W |
|---------------|-----------|---|--------------------|----------------------------|------|-----|-----|
| <b>0x2158</b> | 63        | Rotary switch evaluation element 1 Y-coord. minima 15 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 64        | Rotary switch evaluation element 1 Y-coord. minima 16 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 65        | Rotary switch evaluation element 1 Y-coord. minima 17 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 66        | Rotary switch evaluation element 1 Y-coord. minima 18 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 67        | Rotary switch evaluation element 1 Y-coord. minima 19 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 68        | Rotary switch evaluation element 1 Y-coord. minima 20 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 69        | Rotary switch evaluation element 1 Y-coord. minima 21 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 70        | Rotary switch evaluation element 1 Y-coord. minima 22 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 71        | Rotary switch evaluation element 1 Y-coord. minima 23 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 72        | Rotary switch evaluation element 1 Y-coord. minima 24 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 73        | Rotary switch evaluation element 1 Y-coord. minima 25 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 74        | Rotary switch evaluation element 1 Y-coord. minima 26 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 75        | Rotary switch evaluation element 1 Y-coord. minima 27 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 76        | Rotary switch evaluation element 1 Y-coord. minima 28 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 77        | Rotary switch evaluation element 1 Y-coord. minima 29 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 78        | Rotary switch evaluation element 1 Y-coord. minima 30 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 79        | Rotary switch evaluation element 1 Y-coord. minima 31 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| <b>0x2158</b> | 80        | Rotary switch evaluation element 1 Y-coord. minima 32 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                                    | <b>Value</b>       | <b>Meaning of value</b>    | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---|--------------------|----------------------------|-------------|------------|------------|
| <b>0x2158</b> | 81               | Rotary switch evaluation element 1 X-coord. maxima 1  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 82               | Rotary switch evaluation element 1 X-coord. maxima 2  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 83               | Rotary switch evaluation element 1 X-coord. maxima 3  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 84               | Rotary switch evaluation element 1 X-coord. maxima 4  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 85               | Rotary switch evaluation element 1 X-coord. maxima 5  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 86               | Rotary switch evaluation element 1 X-coord. maxima 6  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 87               | Rotary switch evaluation element 1 X-coord. maxima 7  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 88               | Rotary switch evaluation element 1 X-coord. maxima 8  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 89               | Rotary switch evaluation element 1 X-coord. maxima 9  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 90               | Rotary switch evaluation element 1 X-coord. maxima 10 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 91               | Rotary switch evaluation element 1 X-coord. maxima 11 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 92               | Rotary switch evaluation element 1 X-coord. maxima 12 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 93               | Rotary switch evaluation element 1 X-coord. maxima 13 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 94               | Rotary switch evaluation element 1 X-coord. maxima 14 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 95               | Rotary switch evaluation element 1 X-coord. maxima 15 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 96               | Rotary switch evaluation element 1 X-coord. maxima 16 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 97               | Rotary switch evaluation element 1 X-coord. maxima 17 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |

| Index  | Sub-Index | Description   | Value              | Meaning of value           | Type | Len | R/W |
|--------|-----------|---|--------------------|----------------------------|------|-----|-----|
| 0x2158 | 98        | Rotary switch evaluation element 1 X-coord. maxima 18 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 99        | Rotary switch evaluation element 1 X-coord. maxima 19 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 100       | Rotary switch evaluation element 1 X-coord. maxima 20 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 101       | Rotary switch evaluation element 1 X-coord. maxima 21 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 102       | Rotary switch evaluation element 1 X-coord. maxima 22 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 103       | Rotary switch evaluation element 1 X-coord. maxima 23 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 104       | Rotary switch evaluation element 1 X-coord. maxima 24 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 105       | Rotary switch evaluation element 1 X-coord. maxima 25 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 106       | Rotary switch evaluation element 1 X-coord. maxima 26 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 107       | Rotary switch evaluation element 1 X-coord. maxima 27 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 108       | Rotary switch evaluation element 1 X-coord. maxima 28 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 109       | Rotary switch evaluation element 1 X-coord. maxima 29 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                                       | <b>Value</b>       | <b>Meaning of value</b>    | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|--|--------------------|----------------------------|-------------|------------|------------|
| <b>0x2158</b> | 110              | Rotary switch evaluation element 1<br>X-coord. maxima 30 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 111              | Rotary switch evaluation element 1<br>X-coord. maxima 31 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 112              | Rotary switch evaluation element 1<br>X-coord. maxima 32 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 113              | Rotary switch evaluation element 1<br>Y-coord. maxima 1  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 114              | Rotary switch evaluation element 1<br>Y-coord. maxima 2  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 115              | Rotary switch evaluation element 1<br>Y-coord. maxima 3  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 116              | Rotary switch evaluation element 1<br>Y-coord. maxima 4  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 117              | Rotary switch evaluation element 1<br>Y-coord. maxima 5  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 118              | Rotary switch evaluation element 1<br>Y-coord. maxima 6  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 119              | Rotary switch evaluation element 1<br>Y-coord. maxima 7  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 120              | Rotary switch evaluation element 1<br>Y-coord. maxima 8  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 121              | Rotary switch evaluation element 1<br>Y-coord. maxima 9  | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |

| Index  | Sub-Index | Description  | Value              | Meaning of value           | Type | Len | R/W |
|--------|-----------|--|--------------------|----------------------------|------|-----|-----|
| 0x2158 | 122       | Rotary switch evaluation element 1<br>Y-coord. maxima 10 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 123       | Rotary switch evaluation element 1<br>Y-coord. maxima 11 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 124       | Rotary switch evaluation element 1<br>Y-coord. maxima 12 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 125       | Rotary switch evaluation element 1<br>Y-coord. maxima 13 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 126       | Rotary switch evaluation element 1<br>Y-coord. maxima 14 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 127       | Rotary switch evaluation element 1<br>Y-coord. maxima 15 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 128       | Rotary switch evaluation element 1<br>Y-coord. maxima 16 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 129       | Rotary switch evaluation element 1<br>Y-coord. maxima 17 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 130       | Rotary switch evaluation element 1<br>Y-coord. maxima 18 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 131       | Rotary switch evaluation element 1<br>Y-coord. maxima 19 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 132       | Rotary switch evaluation element 1<br>Y-coord. maxima 20 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |
| 0x2158 | 133       | Rotary switch evaluation element 1<br>Y-coord. maxima 21 | <i>Float value</i> | Float according to IEEE754 | FLT  | 4   | RO  |

| <b>Index</b>  | <b>Sub-Index</b> | <b>Description</b>                                    | <b>Value</b>       | <b>Meaning of value</b>    | <b>Type</b> | <b>Len</b> | <b>R/W</b> |
|---------------|------------------|---|--------------------|----------------------------|-------------|------------|------------|
| <b>0x2158</b> | 134              | Rotary switch evaluation element 1 Y-coord. maxima 22 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 135              | Rotary switch evaluation element 1 Y-coord. maxima 23 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 136              | Rotary switch evaluation element 1 Y-coord. maxima 24 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 137              | Rotary switch evaluation element 1 Y-coord. maxima 25 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 138              | Rotary switch evaluation element 1 Y-coord. maxima 26 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 139              | Rotary switch evaluation element 1 Y-coord. maxima 27 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 140              | Rotary switch evaluation element 1 Y-coord. maxima 28 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 141              | Rotary switch evaluation element 1 Y-coord. maxima 29 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 142              | Rotary switch evaluation element 1 Y-coord. maxima 30 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 143              | Rotary switch evaluation element 1 Y-coord. maxima 31 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |
| <b>0x2158</b> | 144              | Rotary switch evaluation element 1 Y-coord. maxima 32 | <i>Float value</i> | Float according to IEEE754 | FLT         | 4          | RO         |

### 7.2.60 Evaluation results rotary switch evaluation element 2 (index 0x2159)

| Index         | Sub-Index | Description          | Value | Meaning of value | Type | Len | R/W |
|---------------|-----------|----------------------|-------|------------------|------|-----|-----|
| <b>0x2159</b> | 0         | Number of subindices | 144   | -                | U8   | 1   | RO  |
| <b>0x2159</b> | 1...9     | Reserved             | -     | -                |      | X   | X   |
| <b>0x2159</b> | 10...     | See index 0x2158     |       |                  |      | X   | X   |

### 7.2.61 Evaluation results mathematical functions (index 0x2160)

| Index         | Sub-Index | Description                              | Value                              | Meaning of value | Type | Len | R/W |
|---------------|-----------|--|------------------------------------|------------------|------|-----|-----|
| <b>0x2160</b> | 0         | Number of subindices                     | 21                                 | -                | U8   | 1   | RO  |
| <b>0x2160</b> | 1...9     | Reserved                                 | -                                  | -                |      | X   | X   |
| <b>0x2160</b> | 10        | Math. functions evaluation result line 1 | 0<br>1                             | NOK<br>OK        | U16  | 2   | RO  |
| <b>0x2160</b> | 11        | Math. functions evaluation result line 2 | 0<br>1                             | NOK<br>OK        | U16  | 2   | RO  |
| <b>0x2160</b> | 12        | Math. functions evaluation result line 3 | 0<br>1                             | NOK<br>OK        | U16  | 2   | RO  |
| <b>0x2160</b> | 13        | Math. functions evaluation result line 4 | 0<br>1                             | NOK<br>OK        | U16  | 2   | RO  |
| <b>0x2160</b> | 14        | Math. functions evaluation result line 5 | 0<br>1                             | NOK<br>OK        | U16  | 2   | RO  |
| <b>0x2160</b> | 15        | Math. functions evaluation result line 6 | 0<br>1                             | NOK<br>OK        | U16  | 2   | RO  |
| <b>0x2160</b> | 16        | Math. functions NOK counter line 1       | <i>32bit-Integer value &gt;= 0</i> |                  | U32  | 4   | RO  |
| <b>0x2160</b> | 17        | Math. functions NOK counter line 2       | <i>32bit-Integer value &gt;= 0</i> |                  | U32  | 4   | RO  |
| <b>0x2160</b> | 18        | Math. functions NOK counter line 3       | <i>32bit-Integer value &gt;= 0</i> |                  | U32  | 4   | RO  |
| <b>0x2160</b> | 19        | Math. functions NOK counter line 4       | <i>32bit-Integer value &gt;= 0</i> |                  | U32  | 4   | RO  |
| <b>0x2160</b> | 20        | Math. functions NOK counter line 5       | <i>32bit-Integer value &gt;= 0</i> |                  | U32  | 4   | RO  |
| <b>0x2160</b> | 21        | Math. functions NOK counter line 6       | <i>32bit-Integer value &gt;= 0</i> |                  | U32  | 4   | RO  |

### 7.2.62 Combined results (common curve data and evalution elements) (index 0x2161)

| Index  | Sub-Index | Description                                | Value  | Meaning of value | Type             | Len | R/W |
|--------|-----------|--|--|------------------|------------------|-----|-----|
| 0x2161 | 0         | Number of subindizes                       | 31   | -                | U8               | 1   | RO  |
| 0x2161 | 1...9     | Reserved                                   | -  |                  |                  | X   | X   |
| 0x2161 | 10        | Combined results:<br>general curve data Y1 | <i>The data is bit coded and transmitted as STRUCT.</i><br>X-minimum, X-coord. (FL)<br>X-minimum, Y1-coord. (FL)<br>X-maximum, X-coord. (FL)<br>X-maximum, Y1-coord. (FL)<br>Y1-minimum, X-coord. (FL)<br>Y1-minimum, Y1-coord.(FL)<br>Y1-maximum, X-coord. (FL)<br>Y1-maximum, Y1-coord.(FL)<br>First value X-coord. (FL)<br>First value Y1-coord. (FL)<br>Last value X-coord. (FL)<br>Last value Y1-coord. (FL)<br>Return point X-coord. (FL)<br>Return point Y1-coord. (FL)   |                  | STRUCT OF FLOATS | 56  | RO  |
| 0x2161 | 11        | Combined results:<br>general curve data Y2 | See subindex 10  |                  | STRUCT OF FLOATS | 56  | RO  |
| 0x2161 | 12        | Combined results:<br>window 1              | <i>The data is bit coded and transmitted as STRUCT.</i><br>Evaluation result (UINT32)<br>Entry X-coordinate (FL)<br>Entry Y-coordinate (FL)<br>Exit X-coordinate (FL)<br>Exit Y-coordinate (FL)<br>Absolute Ymax X-coord. (FL)<br>Absolute Ymax Y- coord.(FL)<br>Absolute Ymin X- coord. (FL)<br>Absolute Ymin Y- coord. (FL)<br>Local Ymax X-coord. (FL)<br>Local Ymax Y-coord. (FL)<br>Local Ymin X-coord. (FL)<br>Local Ymin Y-coord. (FL)<br>Bending point X-coord. (FL)<br>Bending point Y-coord. (FL)<br>Mean value Y (FL)<br>Gradient (FL)<br>Area (FL)<br>Window Xmin coord. (FL)<br>Window Xmax coord. (FL)<br>Window Ymin coord. (FL)<br>Window Ymax coord. (FL) |                  | STRUCT           | 88  | RO  |
| 0x2161 | 13        | Combined results:<br>window 2              | See subindex 12  |                  | STRUCT           | 88  | RO  |

| Index         | Sub-Index | Description                      | Value   | Meaning of value | Type   | Len | R/W |
|---------------|-----------|----------------------------------|---|------------------|--------|-----|-----|
| <b>0x2161</b> | 14        | Combined results:<br>window 3    | See subindex 12   |                  | STRUCT | 88  | RO  |
| <b>0x2161</b> | 15        | Combined results:<br>window 4    | See subindex 12   |                  | STRUCT | 88  | RO  |
| <b>0x2161</b> | 16        | Combined results:<br>window 5    | See subindex 12   |                  | STRUCT | 88  | RO  |
| <b>0x2161</b> | 17        | Combined results:<br>window 6    | See subindex 12   |                  | STRUCT | 88  | RO  |
| <b>0x2161</b> | 18        | Combined results:<br>window 7    | See subindex 12   |                  | STRUCT | 88  | RO  |
| <b>0x2161</b> | 20        | Combined results:<br>window 9    | See subindex 12   |                  | STRUCT | 88  | RO  |
| <b>0x2161</b> | 21        | Combined results:<br>window 10   | See subindex 12   |                  | STRUCT | 88  | RO  |
| <b>0x2161</b> | 22        | Combined results:<br>threshold 1 | <i>The data is bit coded and transmitted as STRUCT:</i><br>Evaluation result (UINT16)<br>Threshold type (UINT16)<br>Threshold pass X (FL)<br>Threshold pass Y (FL)<br>Absolute Ymax X-coord. (FL)<br>Absolute Ymax Y- coord. (FL)<br>Absolute Ymin X- coord. (FL)<br>Absolute Ymin Y- coord. (FL)<br>Local Ymax X-coord. (FL)<br>Local Ymax Y-coord. (FL)<br>Local Ymin X-coord. (FL)<br>Local Ymin Y-coord. (FL)<br>Bending point X-coord. (FL)<br>Bending point Y-coord. (FL)<br>Mean value Y (FL)<br>Gradient (FL)<br>Area (FL)<br>Threshold position (FL)<br>Threshold min coord. (FL)<br>Threshold max coord. (FL) |                  | STRUCT | 76  | RO  |
| <b>0x2161</b> | 23        | Combined results:<br>threshold 2 | See subindex 22   |                  | STRUCT | 76  | RO  |
| <b>0x2161</b> | 24        | Combined results:<br>threshold 3 | See subindex 22   |                  | STRUCT | 76  | RO  |
| <b>0x2161</b> | 25        | Combined results:<br>threshold 4 | See subindex 22   |                  | STRUCT | 76  | RO  |
| <b>0x2161</b> | 26        | Combined results:                | <i>The data is bit coded and transmitted as STRUCT:</i><br>Evaluation result (UINT32)   |                  | STRUCT | 44  | RO  |

| Index         | Sub-Index | Description                              | Value   | Meaning of value | Type   | Len | R/W |
|---------------|-----------|--|---|------------------|--------|-----|-----|
|               |           | trapezoid window X1                      | Entry X-coord. (FL)<br>Entry Y-coord. (FL)<br>Exit X-coord. (FL)<br>Exit Y-coord. (FL)<br>Xmin (FL)<br>Xmax (FL)<br>Ymax left (FL)<br>Ymax right (FL)<br>Ymin left (FL)<br>Ymin right (FL)  |                  |        |     |     |
| <b>0x2161</b> | 27        | Combined results:<br>trapezoid window X2 | See subindex 26   |                  | STRUCT | 44  | RO  |
| <b>0x2161</b> | 28        | Combined results:<br>trapezoid window Y1 | <i>The data is bit coded and transmitted as STRUCT:</i><br>Evaluation result (UINT32)<br>Entry X-coord. (FL)<br>Entry Y-coord. (FL)<br>Exit X-coord. (FL)<br>Exit Y-coord. (FL)<br>Ymin (FL)<br>Ymax (FL)<br>Xmin top (FL)<br>Xmax top (FL)<br>Xmin bottom (FL)<br>Xmax bottom (FL) |                  | STRUCT | 44  | RO  |
| <b>0x2161</b> | 29        | Combined results:<br>trapezoid window Y2 | See subindex 28   |                  | STRUCT | 44  | RO  |
| <b>0x2161</b> | 30        | Combined results:<br>envelope 1          | <i>The data is bit coded and transmitted as STRUCT:</i><br>Evaluation result (UINT32)<br>Entry X-coordinate (FL)<br>Entry Y-coordinate (FL)<br>Exit X-coordinate (FL)<br>Exit Y-coordinate (FL)<br>Envelope 1 start (FL)<br>Envelope 1 end (FL)<br>Delta min (FL)<br>Delta max (FL) |                  | STRUCT | 36  | RO  |
| <b>0x2161</b> | 31        | Combined results:<br>envelope 2          | See subindex 30   |                  | STRUCT | 36  | RO  |

## 8 Appendix

### 8.1 Operand table for mathematical functions

| Number | ID of operant                                  |
|--------|--|
| 0      | OFF  |
|        |  |
| 100    | Intermediate Result 1                          |
| 101    | Intermediate Result 2                          |
| 102    | Intermediate Result 3                          |
| 103    | Intermediate Result 4                          |
| 104    | Intermediate Result 5                          |
| 105    | Intermediate Result 6                          |
| 106    | Intermediate Result 7                          |
| 107    | Intermediate Result 8                          |
| 108    | Intermediate Result 9                          |
| 109    | Intermediate Result 10                         |
|        |  |
| 200    | Constant 1                                     |
| 201    | Constant 2                                     |
| 202    | Constant 3                                     |
| 203    | Constant 4                                     |
| 204    | Constant 5                                     |
| 205    | Constant 6                                     |
| 206    | Constant 7                                     |
| 207    | Constant 8                                     |
| 208    | Constant 9                                     |
| 209    | Constant 10                                    |
|        |  |
| 300    | General curve data Y1 – Start X                |
| 301    | General curve data Y1 – Start Y                |
| 302    | General curve data Y1 – End X                  |
| 303    | General curve data Y1 – End Y                  |
| 304    | General curve data Y1 – Abs. Xmax X-coordinate |
| 305    | General curve data Y1 – Abs. Xmax Y-coordinate |

| Number | ID of operant                                     |
|--------|---|
| 306    | General curve data Y1 – Abs. Xmin X-coordinate    |
| 307    | General curve data Y1 – Abs. Xmin Y-coordinate    |
| 308    | General curve data Y1 – Abs. Ymax X-coordinate    |
| 309    | General curve data Y1 – Abs. Ymax Y-coordinate    |
| 310    | General curve data Y1 – Abs. Ymin X-coordinate    |
| 311    | General curve data Y1 – Abs. Ymin Y-coordinate    |
| 312    | General curve data Y1 – Return point X-coordinate |
| 313    | General curve data Y1 – Return point Y-coordinate |
| 314    | Reference point                                   |
|        |   |
| 400    | General curve data Y2 – Start X                   |
| 401    | General curve data Y2 – Start Y                   |
| 402    | General curve data Y2 – End X                     |
| 403    | General curve data Y2 –End Y                      |
| 404    | General curve data Y2 – Abs- Xmax X-coordinate    |
| 405    | General curve data Y2 – Abs. Xmax Y-coordinate    |
| 406    | General curve data Y2 – Abs. Xmin X-coordinate    |
| 407    | General curve data Y2 – Abs. Xmin Y-coordinate    |
| 408    | General curve data Y2 – Abs. Ymax X-coordinate    |
| 409    | General curve data Y2 – Abs. Ymax Y-coordinate    |
| 410    | General curve data Y2 – Abs. Ymin X-coordinate    |
| 411    | General curve data Y2 – Abs. Ymin Y-coordinate    |
| 412    | General curve data Y2 – Return point X-coordinate |
| 413    | General curve data Y2 – Return point Y-coordinate |
| 414    | Reference point                                   |
|        |   |
| 500    | Window 1 – Entry X                                |
| 501    | Window 1 – Entry Y                                |
| 502    | Window 1 – Exit X                                 |
| 503    | Window 1 – Exit Y                                 |
| 504    | Window 1 – Abs. minimum X                         |
| 505    | Window 1 – Abs. minimum Y                         |

| Number | ID of operant              |
|--------|----------------------------|
| 506    | Window 1 – Abs. maximum X  |
| 507    | Window 1 – Abs. maximum Y  |
| 508    | Window 1 – Loc. minimum X  |
| 509    | Window 1 – Loc. minimum Y  |
| 510    | Window 1 – Loc. maximum X  |
| 511    | Window 1 – Loc. maximum Y  |
| 512    | Window 1 – Bend X          |
| 513    | Window 1 – Bend Y          |
| 514    | Window 1 – Mean value Y    |
| 515    | Window 1 – Gradient        |
| 516    | Window 1 – Area            |
| 517    | Window 1 – Coordinate Xmin |
| 518    | Window 1 – Coordinate Xmax |
| 519    | Window 1 – Coordinate Ymin |
| 520    | Window 1 – Coordinate Ymax |
|        |                            |
| 600    | Window 2 – Entry X         |
| 601    | Window 2 – Entry Y         |
| 602    | Window 2 – Exit X          |
| 603    | Window 2 – Exit Y          |
| 604    | Window 2 – Abs. minimum X  |
| 605    | Window 2 – Abs. minimum Y  |
| 606    | Window 2 – Abs. maximum X  |
| 607    | Window 2 – Abs. maximum Y  |
| 608    | Window 2 – Loc. minimum X  |
| 609    | Window 2 – Loc. minimum Y  |
| 610    | Window 2 – Loc. maximum X  |
| 611    | Window 2 – Loc. maximum Y  |
| 612    | Window 2 – Bend X          |
| 613    | Window 2 – Bend Y          |
| 614    | Window 2 – Mean value Y    |
| 615    | Window 2 – Gradient        |

| Number | ID of operant              |
|--------|----------------------------|
| 616    | Window 2 – Area            |
| 617    | Window 2 – Coordinate Xmin |
| 618    | Window 2 – Coordinate Xmax |
| 619    | Window 2 – Coordinate Ymin |
| 620    | Window 2 – Coordinate Ymax |
|        |                            |
| 700    | Window 3 – Entry X         |
| 701    | Window 3 – Entry Y         |
| 702    | Window 3 – Exit X          |
| 703    | Window 3 – Exit Y          |
| 704    | Window 3 – Abs. minimum X  |
| 705    | Window 3 – Abs. minimum Y  |
| 706    | Window 3 – Abs. maximum X  |
| 707    | Window 3 – Abs. maximum Y  |
| 708    | Window 3 – Loc. minimum X  |
| 709    | Window 3 – Loc. maximum Y  |
| 710    | Window 3 – Loc. maximum X  |
| 711    | Window 3 – Loc. maximum Y  |
| 712    | Window 3 – Bend X          |
| 713    | Window 3 – Bend Y          |
| 714    | Window 3 – Mean value Y    |
| 715    | Window 3 – Gradient        |
| 716    | Window 3 – Area            |
| 717    | Window 3 – Coordinate Xmin |
| 718    | Window 3 – Coordinate Xmax |
| 719    | Window 3 – Coordinate Ymin |
| 720    | Window 3 – Coordinate Ymax |
|        |                            |
| 800    | Window 4 – Entry X         |
| 801    | Window 4 – Entry Y         |
| 802    | Window 4 – Exit X          |
| 803    | Window 4 – Exit Y          |

| Number | ID of operant              |
|--------|----------------------------|
| 804    | Window 4 – Abs. minimum X  |
| 805    | Window 4 – Abs. minimum Y  |
| 806    | Window 4 – Abs. maximum X  |
| 807    | Window 4 – Abs. maximum Y  |
| 808    | Window 4 – Loc. minimum X  |
| 809    | Window 4 – Loc. minimum Y  |
| 810    | Window 4 – Loc. maximum X  |
| 811    | Window 4 – Loc. maximum Y  |
| 812    | Window 4 – Bend X          |
| 813    | Window 4 – Bend Y          |
| 814    | Window 4 – Mean value Y    |
| 815    | Window 4 – Gradient        |
| 816    | Window 4 – Area            |
| 817    | Window 4 – Coordinate Xmin |
| 818    | Window 4 – Coordinate Xmax |
| 819    | Window 4 – Coordinate Ymin |
| 820    | Window 4 – Coordinate Ymax |
|        |                            |
| 900    | Window 5 – Entry X         |
| 901    | Window 5 – Entry Y         |
| 902    | Window 5 – Exit X          |
| 903    | Window 5 – Exit Y          |
| 904    | Window 5 – Abs. minimum X  |
| 905    | Window 5 – Abs. minimum Y  |
| 906    | Window 5 – Abs. maximum X  |
| 907    | Window 5 – Abs. maximum Y  |
| 908    | Window 5 – Loc. minimum X  |
| 909    | Window 5 – Loc. minimum Y  |
| 910    | Window 5 – Loc. maximum X  |
| 911    | Window 5 – Loc. maximum Y  |
| 912    | Window 5 – Bend X          |
| 913    | Window 5 – Bend Y          |

| Number | ID of operant              |
|--------|----------------------------|
| 914    | Window 5 – Mean value Y    |
| 915    | Window 5 – Gradient        |
| 916    | Window 5 – Area            |
| 917    | Window 5 – Coordinate Xmin |
| 918    | Window 5 – Coordinate Xmax |
| 919    | Window 5 – Coordinate Ymin |
| 920    | Window 5 – Coordinate Ymax |
|        |                            |
| 1000   | Window 6 – Entry X         |
| 1001   | Window 6 – Entry Y         |
| 1002   | Window 6 – Exit X          |
| 1003   | Window 6 – Exit Y          |
| 1004   | Window 6 – Abs. minimum X  |
| 1005   | Window 6 – Abs. maximum Y  |
| 1006   | Window 6 – Abs. maximum X  |
| 1007   | Window 6 – Abs. maximum Y  |
| 1008   | Window 6 – Loc. minimum X  |
| 1009   | Window 6 – Loc. minimum Y  |
| 1010   | Window 6 – Loc. maximum X  |
| 1011   | Window 6 – Loc. maximum Y  |
| 1012   | Window 6 – Bend X          |
| 1013   | Window 6 – Bend Y          |
| 1014   | Window 6 – Mean value Y    |
| 1015   | Window 6 – Gradient        |
| 1016   | Window 6 – Area            |
| 1017   | Window 6 – Coordinate Xmin |
| 1018   | Window 6 – Coordinate Xmax |
| 1019   | Window 6 – Coordinate Ymin |
| 1020   | Window 6 – Coordinate Ymax |
|        |                            |
| 1100   | Window 7 – Entry X         |
| 1101   | Window 7 – Entry Y         |

| Number | ID of operant              |
|--------|----------------------------|
| 1102   | Window 7 – Exit X          |
| 1103   | Window 7 – Exit Y          |
| 1104   | Window 7 – Abs. minimum X  |
| 1105   | Window 7 – Abs. minimum Y  |
| 1106   | Window 7 – Abs. maximum X  |
| 1107   | Window 7 – Abs. maximum Y  |
| 1108   | Window 7 – Loc. minimum X  |
| 1109   | Window 7 – Loc. minimum Y  |
| 1110   | Window 7 – Loc. maximum X  |
| 1111   | Window 7 – Loc. maximum Y  |
| 1112   | Window 7 – Bend X          |
| 1113   | Window 7 – Bend Y          |
| 1114   | Window 7 – Mean value Y    |
| 1115   | Window 7 – Gradient        |
| 1116   | Window 7 – Area            |
| 1117   | Window 7 – Coordinate Xmin |
| 1118   | Window 7 – Coordinate Xmax |
| 1119   | Window 7 – Coordinate Ymin |
| 1120   | Window 7 – Coordinate Ymax |
| 1200   | Window 8 – Entry X         |
| 1201   | Window 8 – Entry Y         |
| 1202   | Window 8 – Exit X          |
| 1203   | Window 8 – Exit Y          |
| 1204   | Window 8 – Abs. minimum X  |
| 1205   | Window 8 – Abs. minimum Y  |
| 1206   | Window 8 – Abs. maximum X  |
| 1207   | Window 8 – Abs. maximum Y  |
| 1208   | Window 8 – Loc. minimum X  |
| 1209   | Window 8 – Loc. minimum Y  |
| 1210   | Window 8 – Loc. maximum X  |
| 1211   | Window 8 – Loc. maximum Y  |

| Number      | ID of operant              |
|-------------|----------------------------|
| <b>1212</b> | Window 8 – Bend X          |
| <b>1213</b> | Window 8 – Bend Y          |
| <b>1214</b> | Window 8 – Mean value Y    |
| <b>1215</b> | Window 8 – Gradient        |
| <b>1216</b> | Window 8 – Area            |
| <b>1217</b> | Window 8 – Coordinate Xmin |
| <b>1218</b> | Window 8 – Coordinate Xmax |
| <b>1219</b> | Window 8 – Coordinate Ymin |
| <b>1220</b> | Window 8 – Coordinate Ymax |
|             |                            |
| <b>1300</b> | Window 9 – Entry X         |
| <b>1301</b> | Window 9 – Entry Y         |
| <b>1302</b> | Window 9 – Exit X          |
| <b>1303</b> | Window 9 – Exit Y          |
| <b>1304</b> | Window 9 – Abs. minimum X  |
| <b>1305</b> | Window 9 – Abs. minimum Y  |
| <b>1306</b> | Window 9 – Abs. maximum X  |
| <b>1307</b> | Window 9 – Abs. maximum Y  |
| <b>1308</b> | Window 9 – Loc. minimum X  |
| <b>1309</b> | Window 9 – Loc. minimum Y  |
| <b>1310</b> | Window 9 – Loc. maximum X  |
| <b>1311</b> | Window 9 – Loc. maximum Y  |
| <b>1312</b> | Window 9 – Bend X          |
| <b>1313</b> | Window 9 – Bend Y          |
| <b>1314</b> | Window 9 – Mean value Y    |
| <b>1315</b> | Window 9 – Gradient        |
| <b>1316</b> | Window 9 – Area            |
| <b>1317</b> | Window 9 – Coordinate Xmin |
| <b>1318</b> | Window 9 – Coordinate Xmax |
| <b>1319</b> | Window 9 – Coordinate Ymin |
| <b>1320</b> | Window 9 – Coordinate Ymax |
|             |                            |

| Number | ID of operant                               |
|--------|---|
| 1400   | Window 10 – Entry X                         |
| 1401   | Window 10 – Entry Y                         |
| 1402   | Window 10 – Exit X                          |
| 1403   | Window 10 – Exit Y                          |
| 1404   | Window 10 – Abs. minimum X                  |
| 1405   | Window 10 – Abs. minimum Y                  |
| 1406   | Window 10 – Abs. maximum X                  |
| 1407   | Window 10 – Abs. maximum Y                  |
| 1408   | Window 10 – Loc. minimum X                  |
| 1409   | Window 10 – Loc. minimum Y                  |
| 1410   | Window 10 – Loc. maximum X                  |
| 1411   | Window 10 – Loc. maximum Y                  |
| 1412   | Window 10 – Bend X                          |
| 1413   | Window 10 – Bend Y                          |
| 1414   | Window 10 – Mean value Y                    |
| 1415   | Window 10 – Gradient                        |
| 1416   | Window 10 – Area                            |
| 1417   | Window 10 – Coordinate Xmin                 |
| 1418   | Window 10 – Coordinate Xmax                 |
| 1419   | Window 10 – Coordinate Ymin                 |
| 1420   | Window 10 – Coordinate Ymax                 |
|        |   |
| 1500   | Trapezoid window X1 – Entry X               |
| 1501   | Trapezoid window X1 – Entry Y               |
| 1502   | Trapezoid window X1 – Exit X                |
| 1503   | Trapezoid window X1 – Exit Y                |
| 1504   | Trapezoid window X1 – Coordinate Xmin       |
| 1505   | Trapezoid window X1 – Coordinate Xmax       |
| 1506   | Trapezoid window X1 – Coordinate Ymin left  |
| 1507   | Trapezoid window X1 – Coordinate Ymin right |
| 1508   | Trapezoid window X1 – Coordinate Ymax left  |
| 1509   | Trapezoid window X1 – Coordinate Ymax right |

| Number      | ID of operant                                |
|-------------|--|
|             |  |
| <b>1600</b> | Trapezoid window X2 – Entry X                |
| <b>1601</b> | Trapezoid window X2 – Entry Y                |
| <b>1602</b> | Trapezoid window X2 – Exit X                 |
| <b>1603</b> | Trapezoid window X2 – Exit Y                 |
| <b>1604</b> | Trapezoid window X2 – Coordinate Xmin        |
| <b>1605</b> | Trapezoid window X2 – Coordinate Xmax        |
| <b>1606</b> | Trapezoid window X2 – Coordinate Ymin left   |
| <b>1607</b> | Trapezoid window X2 – Coordinate Ymin right  |
| <b>1608</b> | Trapezoid window X2 – Coordinate Ymax left   |
| <b>1609</b> | Trapezoid window X2 – Coordinate Ymax right  |
|             |  |
| <b>1700</b> | Trapezoid window Y1 – Entry X                |
| <b>1701</b> | Trapezoid window Y1 – Entry Y                |
| <b>1702</b> | Trapezoid window Y1 – Exit X                 |
| <b>1703</b> | Trapezoid window Y1 – Exit Y                 |
| <b>1704</b> | Trapezoid window Y1 – Coordinate Ymin        |
| <b>1705</b> | Trapezoid window Y1 – Coordinate Ymax        |
| <b>1706</b> | Trapezoid window Y1 – Coordinate Xmin bottom |
| <b>1707</b> | Trapezoid window Y1 – Coordinate Xmin top    |
| <b>1708</b> | Trapezoid window Y1 – Coordinate Xmax bottom |
| <b>1709</b> | Trapezoid window Y1 – Coordinate Xmax top    |
|             |  |
| <b>1800</b> | Trapezoid window Y2 – Entry X                |
| <b>1801</b> | Trapezoid window Y2 – Entry Y                |
| <b>1802</b> | Trapezoid window Y2 – Exit X                 |
| <b>1803</b> | Trapezoid window Y2 – Exit Y                 |
| <b>1804</b> | Trapezoid window Y2 – Coordinate Ymin        |
| <b>1805</b> | Trapezoid window Y2 – Coordinate Ymax        |
| <b>1806</b> | Trapezoid window Y2 – Coordinate Xmin bottom |
| <b>1807</b> | Trapezoid window Y2 – Coordinate Xmin top    |
| <b>1808</b> | Trapezoid window Y2 – Coordinate Xmax bottom |

| Number | ID of operant                             |
|--------|---|
| 1809   | Trapezoid window Y2 – Coordinate Xmax top |
|        |   |
| 1900   | Threshold 1 – Pass X                      |
| 1901   | Threshold 1 – Pass Y                      |
| 1902   | Threshold 1 – Abs. minimum X              |
| 1903   | Threshold 1 – Abs. minimum Y              |
| 1904   | Threshold 1 – Abs. maximum X              |
| 1905   | Threshold 1 – Abs. maximum Y              |
| 1906   | Threshold 1 – Loc. minimum X              |
| 1907   | Threshold 1 – Loc. minimum Y              |
| 1908   | Threshold 1 – Loc. maximum X              |
| 1909   | Threshold 1 – Loc. maximum Y              |
| 1910   | Threshold 1 – Bend X                      |
| 1911   | Threshold 1 – Bend Y                      |
| 1912   | Threshold 1 – Mean value Y                |
| 1913   | Threshold 1 – Gradient                    |
| 1914   | Threshold 1 – Area                        |
| 1915   | Threshold 1 – Coordinate X value          |
| 1916   | Threshold 1 – Coordinate Ymin             |
| 1917   | Threshold 1 – Coordinate Ymax             |
|        |   |
| 2000   | Threshold 2 – Pass X                      |
| 2001   | Threshold 2 – Pass Y                      |
| 2002   | Threshold 2 – Abs. minimum X              |
| 2003   | Threshold 2 – Abs. minimum Y              |
| 2004   | Threshold 2 – Abs. maximum X              |
| 2005   | Threshold 2 – Abs. maximum Y              |
| 2006   | Threshold 2 – Loc. minimum X              |
| 2007   | Threshold 2 – Loc. minimum Y              |
| 2008   | Threshold 2 – Loc. maximum X              |
| 2009   | Threshold 2 – Loc. maximum Y              |
| 2010   | Threshold 2 – Bend X                      |

| Number | ID of operant                    |
|--------|----------------------------------|
| 2011   | Threshold 2 – Bend Y             |
| 2012   | Threshold 2 – Mean value Y       |
| 2013   | Threshold 2 – Gradient           |
| 2014   | Threshold 2 – Area               |
| 2015   | Threshold 2 – Coordinate X value |
| 2016   | Threshold 2 – Coordinate Ymin    |
| 2017   | Threshold 2 – Coordinate Ymax    |
|        |                                  |
| 2100   | Threshold 3 – Pass X             |
| 2101   | Threshold 3 – Pass Y             |
| 2102   | Threshold 3 – Abs. minimum X     |
| 2103   | Threshold 3 – Abs. minimum Y     |
| 2104   | Threshold 3 – Abs. maximum X     |
| 2105   | Threshold 3 – Abs. maximum Y     |
| 2106   | Threshold 3 – Loc. minimum X     |
| 2107   | Threshold 3 – Loc. minimum Y     |
| 2108   | Threshold 3 – Loc. maximum X     |
| 2109   | Threshold 3 – Loc. maximum Y     |
| 2110   | Threshold 3 – Bend X             |
| 2111   | Threshold 3 – Bend Y             |
| 2112   | Threshold 3 – Mean value Y       |
| 2113   | Threshold 3 – Gradient           |
| 2114   | Threshold 3 – Area               |
| 2115   | Threshold 3 – Coordinate X value |
| 2116   | Threshold 3 – Coordinate Ymin    |
| 2117   | Threshold 3 – Coordinate Ymax    |
|        |                                  |
| 2200   | Threshold 4 – Pass X             |
| 2201   | Threshold 4 – Pass Y             |
| 2202   | Threshold 4 – Abs. minimum X     |
| 2203   | Threshold 4 – Abs. minimum Y     |
| 2204   | Threshold 4 – Abs. maximum X     |

| Number | ID of operant                    |
|--------|----------------------------------|
| 2205   | Threshold 4 – Abs. maximum Y     |
| 2206   | Threshold 4 – Loc. minimum X     |
| 2207   | Threshold 4 – Loc. minimum Y     |
| 2208   | Threshold 4 – Loc. maximum X     |
| 2209   | Threshold 4 – Loc. maximum Y     |
| 2210   | Threshold 4 – Bend X             |
| 2211   | Threshold 4 – Bend Y             |
| 2212   | Threshold 4 – Mean value Y       |
| 2213   | Threshold 4 – Gradient           |
| 2214   | Threshold 4 – Area               |
| 2215   | Threshold 4 – Coordinate X value |
| 2216   | Threshold 4 – Coordinate Ymin    |
| 2217   | Threshold 4 – Coordinate Ymax    |
|        |                                  |
| 2300   | Envelope 1 – Entry X             |
| 2301   | Envelope 1 – Entry Y             |
| 2302   | Envelope 1 – Exit X              |
| 2303   | Envelope 1 – Exit Y              |
| 2304   | Envelope 1 – Coordinate Start X  |
| 2305   | Envelope 1 – Coordinate End X    |
|        |                                  |
| 2400   | Envelope 2 – Entry X             |
| 2401   | Envelope 2 – Entry Y             |
| 2402   | Envelope 2 – Exit X              |
| 2403   | Envelope 2 – Exit Y              |
| 2404   | Envelope 2 – Coordinate Start X  |
| 2405   | Envelope 2 – Coordinate End X    |

## 8.2 Error codes

| Error code | ID of operant                              |
|------------|--|
| 0xC065003A | Subindex does not exist (read access)      |
| 0xC0CF8013 | Subindex does not exist (write access)     |
| 0xC0CF8006 | Object is read only and can not be written |
| 0xC0CF8010 | Data type does not match                   |
| 0xC0CF8011 | Data length is too long                    |
| 0xC0650028 | Timeout                                    |
| 0xC065002F | Object is write only and can not be read   |