



OPERATION MANUAL

DIGIFORCE® 9311 EtherNet/IP manual

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|--|-------------------------------|
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| Networks(s) Supported: | EtherNet/IP™ |
| CIP Device Profile Supported: | Programmable Logic Controller |
| Classification of Declaration: | Single Product |

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| No. | Vendor Product Code (attribute 3) | Vendor Product Revision (attribute 4) | Vendor Product Name (attribute 7) |
| 1 | 2 | 18.001 | DIGIFORCE 9311-VXX04 |

Declaration of Conformity

File No.: 11535.02

Part 1 of 1 - page 2 of 2

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1 For your safety

The following symbols on the DIGIFORCE® 9311 and in this operation manual warn of hazards.

1.1 Symbols used in the instruction manual

1.1.1 Signal words

The following signal words are used in the operation manual according to the specified hazard classification.

| | |
|--|----------------|
|  | DANGER |
| High degree of risk: indicates a hazardous situation which, if not avoided, will result in death or serious injury. | |
|  | WARNING |
| Moderate degree of risk: indicates a hazardous situation which, if not avoided, may result in death or serious injury. | |
|  | CAUTION |
| Low degree of risk: indicates a hazardous situation which, if not avoided, could result in minor or moderate injury. | |
| NOTICE | |
| Property damage to the equipment or the surroundings will result if the hazard is not avoided. | |

Note: It is important to heed these safety notices in order to ensure you handle the DIGIFORCE® 9311 correctly.

Caution: Follow the information given in the operation manual.

1.1.2 Pictograms

| Symbol | Description |
|---|--|
|  | Warning concerning the use and installation of the device and software. |
|  | Observe the advice for protecting the instrument. |

1.2 Symbols and precautionary statements on the instrument

| Symbol | Description |
|---|--|
|  | Hazard warning Disconnect the power plug before opening – Follow safety instructions – Professional servicing only |
| Warning ! To prevent electrical shock do not open device. | Warning of electrical shock hazard Do not open the unit. |
| To prevent fire replace only with same type and rating of fuse ! | Warning of fire hazard Always replace the fuse with a fuse of the same type and rating. |

1.2.1 Conventions used in the instruction manual

| Designation | Description |
|-------------|---|
| [Fx] | Function keys F1 to F3 on the touchscreen display |
| [Text] | Buttons on the touchscreen display |
| "Term" | Terms used in the instrument menus |

1.3 Abbreviations

| Abbreviation | Description |
|--------------|---|
| BF | Bus error |
| ODVA | ODVA is a trade and standards development organization, whose members are suppliers of devices for industrial automation application. |
| ESD | Electronic Data Sheet |

2 Introduction

2.1 General safety instructions



DANGER

Warning concerning installation of the device and software

Installation of the device and the interface must be carried out by qualified personnel only. Qualified personnel meets the following requirements:

- You are familiar with the safety designs used in automation engineering, and understand how to deal with them in your capacity as configuration engineer.
- You are an operator of automation systems and have been instructed in how to handle the system. You are familiar with the operation of the equipment described in this documentation.
- You are a commissioning or service engineer and have successfully completed a training course qualifying you to repair automation systems. In addition you are authorized to commission, ground and label circuits and equipment in accordance with safety engineering standards.



Always observe the current safety and accident prevention regulations when commissioning the equipment.

Install automation engineering equipment and installations with sufficient protection against accidental actuation.



DANGER

Warning concerning use of the device

- Take suitable precautions in both the hardware and software to prevent any undefined states of the automation installation in the event of an open circuit.
- In installations where major damage to property or even personal injury may be caused by a malfunction, take suitable precautions to establish a safe operating state in the event of a fault. This may be achieved using limit switches, mechanical interlocks etc. for example.
- Do not make unauthorized modifications to the device or to the EtherNet/IP interface.



NOTICE

- Install the power, signal and sensor cables so as to prevent electromagnetic interference from impairing operation of the equipment.
- Proper transportation, storage, installation and assembly plus careful operation and maintenance are essential for trouble-free and safe operation of the equipment.
- Have non-functional instruments inspected by the manufacturer.

2.2 Intended use

The DIGIFORCE® 9311 is an instrument for monitoring repetitive production processes. Its core function is to record and analyze signals from processes in which physical variables, such as force, pressure or torque, vary as a function of displacement, angle or time according to a defined curve. The resultant measurement curve is analyzed using graphical evaluation elements such as windows, envelopes and thresholds. The result of the analysis is classified as "OK" or "NOT OK" (NOK) and can be retrieved from various interfaces.

The instrument is not a substitute for a safety device; for instance it cannot be used as an emergency stop device in a press for when the pressure exceeds a set limit.

3 Technical data

3.1 Supported EtherNet/IP-Services

- Implicit Messaging
- Explicit Messaging
- Vendor Specific Services (used for Device Configuration)
- Address Conflict Detection (ACD)
- Device Level Ring (DLR)

Identity Object of a sample device

| Attribut | Wert |
|----------------|----------------------|
| Vendor ID | 0x565 (1381) |
| Device Type | 0x2B (43) |
| Product Code | 0x02 (2) |
| Major Revision | 0x10 (16) |
| Minor Revision | 0x01 (1) |
| Summary Status | 0x60 (96) |
| Serial Number | 123456 |
| Product Name | DIGIFORCE 9311-VXX04 |
| Present State | 0x00 (0) |

You will find further information about EtherNet/IP at: www.odva.org.

3.2 Model 9311 device data

| | |
|---------------|----------------------------|
| Bus connector | RJ45 |
| EDS file | BURSTER-DIGIFORCE-9311.EDS |

3.3 Electrical safety

| | |
|-----------------------------|---|
| Reverse voltage protection | Yes |
| Air clearance/leakage paths | To DIN EN 61010-1:2010 |
| Electrical isolation | Between fieldbus and internal electronics |
| Withstand voltage | DC 500 V |

3.4 Electromagnetic compatibility

3.4.1 Interference immunity

Interference immunity to EN 61326-1:2013

Industrial locations

3.4.2 Emitted interference

Emitted interference to EN 61326-1:2013

Class A

EN 61000-3-2:2014

EN 61000-3-3:2013

3.5 Notes on CE labeling

burster equipment carrying the CE mark meets the requirements of the EU directives and the harmonized European standards (EN) cited therein.

The EU declarations of conformity are available to the relevant authorities as specified in the directives. A copy of the declaration of conformity is included in the relevant equipment documentation.

4 Installation

Please note that you can download various documents such as installation guidelines and specifications about EtherNet/IP at ODVA: www.odva.org.

4.1 Connection of fieldbus lines

burster devices with a EtherNet/IP option have two **RJ 45** connectors for the fieldbus connection.

4.2 Meaning of LEDs states



| LED | Blinking | On |
|----------|---------------------|--|
| ACT | Data transmission | x |
| LNK / LA | x | Ethernet line monitoring |
| MOD | Off | x No power |
| | Green | Standby Device operational |
| | Red | Minor fault Incorrect or inconsistent configuration Major fault A non-recoverable fault |
| | Green/Red | Self-test x |
| NET | Off | x Not powered, no IP-Addr. |
| | Green | No connections Device connected |
| | Red | Connection timeout Duplicated IP |
| | Green/Red | Self-test x |
| BF | x | x |
| BOOT | Device in boot mode | x |
| US1 | x | Supply voltage |

4.3 Configuration menu in DIGIFORCE® 9311

To access the menu

Start in measurement mode. After power on the measurement mode is always set. The display will look differently dependent on your settings or your last measurements.

PROFINET settings for the DIGIFORCE® 9311 are configured via the "PROFINET" menu.



This is how it works

- 1 In measurement mode, tap anywhere on the touchscreen. The  icon appears in the bottom-right corner.
- 2 Tap  to open the "Configuration Main Menu".
- 3 Tap the "Basic setup" icon.
- 4 Tap the "EtherNet/IP" icon.

| P 0 | EtherNet/IP | M77 |
|------------------|-----------------------|---|
| SW-version | EIP-V1601 | |
| Serial number | 01234567 | |
| Control via | EtherNet/IP | |
| MAC address | 00-23-6E-00-02-F9 | |
| IP Configuration | DHCP | |
| IP address | 169 254 044 011 | |
| Subnet mask | 255 255 000 000 |  |
| Gateway | 000 000 000 000 | |

Diagram 1: EtherNet/IP settings

Parameters in the "EtherNet/IP" menu (M77)

| | |
|-------------------------|---|
| SW-version | Firmware version of the EtherNet/IP Fieldbus module |
| Serial number | Serial number of the Fieldbus module |
| Control via | EtherNet/IP: the DIGIFORCE® 9311 responds solely to control signals (inputs) from the EtherNet/IP interface. PLC: the DIGIFORCE® 9311 responds solely to control signals (inputs) from the PLC I/O interface. When control via PLC I/O is selected, data is still transferred on the EtherNet/IP real-time channel. |
| MAC address | Address for identifying the Fieldbus module in the EtherNet/IP network. |
| IP configuration | Network configuration type (BOOTP, DHCP, static) Please note: this parameter cannot be changed in the DIGIFORCE® 9311. |
| IP address | IP address If BOOTP or DHCP is selected for "IP Configuration", the IP address is assigned by a BOOTP or DHCP server. Please note: the IP address cannot be changed by the user if BOOTP or DHCP is selected for the IP configuration mode. |
| Subnet mask | Subnet mask If BOOTP or DHCP is selected for "IP Configuration", the subnet mask is assigned by a BOOTP or DHCP server. Please note: the subnet mask cannot be changed by the user if BOOTP or DHCP is selected for the IP configuration mode. |
| Gateway | Gateway address If BOOTP or DHCP is selected for "IP Configuration", the gateway is assigned by a BOOTP or DHCP server. Please note: the gateway address cannot be changed by the user if BOOTP or DHCP is selected for the IP configuration mode. |

5 EtherNet/IP

5.1 General information on EtherNet/IP data transfer

For EtherNet/IP (implicit messaging) one must define at the configuration stage how many bytes are transferred between Controller (Scanner) and Device (Adapter) during each cyclic access.

The device is controlled using the data transferred from Controller (Scanner) to Device (Adapter). This data always consists of three bytes for the DIGIFORCE® 9311 unit. The function of these three bytes is explained in chapter 5.2 PLC inputs – Transfer from Scanner to Adapter (Digiforce).

The DIGIFORCE® 9311 sends cyclic 92 bytes to controller. This packet contains PLC status, evaluation information and 20 measurement values which are user selectable within the 9311 configuration and the live values of max. 2 active measurement channels.

5.2 EDS file

DIGIFORCE® equipment with the EtherNet/IP option is supplied with a CD. This disk includes the **E**lectronic **D**ata **S**heet (**EDS**) file *BURSTER-DIGIFORCE-9311.EDS*. This EDS file contains the EtherNet/IP configuration information for the DIGIFORCE 9311®.

The structure, contents and encoding of this device description data is standardized so that any EtherNet/IP devices can be configured using configuration tools from various manufacturers.

The EDS file does not specify what data is transferred or how this data should be interpreted. The user must glean this information from the operating manual and program his Controller accordingly.

5.3 Data conversion

5.3.1 Description of the data formats in this manual

The terms PLC inputs and PLC outputs refer to the DIGIFORCE® 9311 unit. These terms are reversed when referred to the Controller.

The function of the PLC-In / PLC-Out bits is identical to the parallel PLC I/O ports on the unit itself and can be found within the DIGIFORCE® 9311 operating manual.

The floating-point numbers ("float") mentioned are four bytes long (32 bits) and are based on the IEEE-754 standard.

Numbers that are not specifically labeled or are labeled with "d" or "dec" are decimal numbers. (Example: 1234, 1234dec, dec1234, 1234d)

Numbers that are labeled with "0x" or "hex" are hexadecimal numbers. (Example: 0x1234, hex1234, 1234hex, 1234h)

Numbers that are labeled with "b" or "bin" are binary numbers. (Example: b1100, bin1100, 1100b, 1100bin).

5.3.2 Handling problems that arise when reading floating-point numbers

This only concerns cases in which floating-point numbers need to be read from the DIGIFORCE® 9311 unit.

Floating-point numbers (data type REAL), according to IEEE 754, are encoded as four bytes for transfer. This may create problems depending on the type of PLC used.

Cause

In the DIGIFORCE® 9311-PROFINET, the sign byte is transferred first if using acyclic data transfer (see 6. Unconnected Explicit Messaging) and last while cyclic data transmission. Some PLCs expect this byte in the highest of the four addresses not in the lowest address. This inevitably leads to misinterpretation of the numeric value. In this case the order of the four bytes has to be changed by the PLC as shown in the figure.

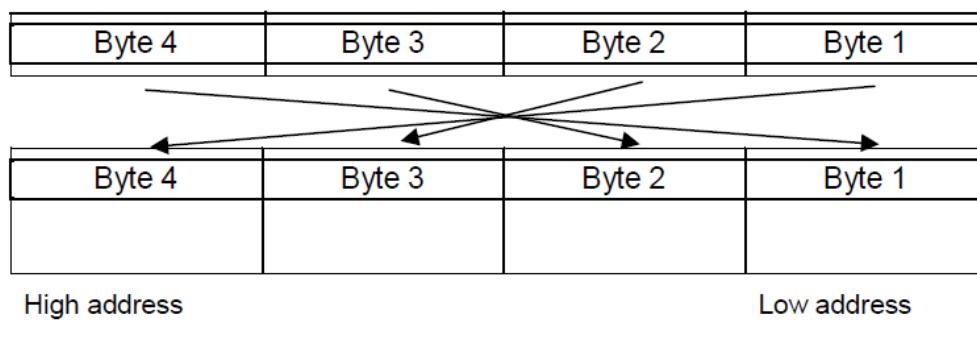


Diagram 2: Exchange of the order of bytes caused by misinterpretation of the numeric value

6 EtherNet/IP data protocol (real-time data)

6.1 Meaning of the content of the cyclic data packet from adapter (DIGIFORCE®) to scanner

Overview of the packet content:

| Content | Length/Bytes | Bytes |
|---|--------------|-------------------|
| PLC output status | 2 | Σ 92 bytes |
| Evaluation info | 2 | |
| 20 evaluation values (float) , user-defined values* | 20x4 | |
| 2 live values (X, Y) * ¹ | 2x4 | |

* The user-defined values contain values which are defined within the DIGIFORCE® 9311 device. The following values are available:

- General curve data
- Evaluation results of each evaluation element (e.g. window entry/exit window extended evaluation results like Min/Max window limits Xmin, Xmax, Ymin, Ymax threshold crossing point)

¹ The live values of the sensor channels are updated at a rate of 100 Hz. The values are only updated when the DIGIFORCE® 9311 is ready to record measurements or is actively taking a measurement.

How to define the user-defined values: The parameterization of the list is done in the main setup menu "Setup user defined values" (Note that this setting is specific for each measurement program. For details refer to the DIGIFORCE® 9311 operation manual, section 6.3.8 User-defined values.)

6.2 PLC inputs – Transfer from scanner to adapter (DIGIFORCE®)

Three bytes of PLC-In data for the DIGIFORCE® 9311 are always transferred from the EtherNet/IP Controller (Scanner) to the DIGIFORCE® 9311. These bits have the same function as the parallel PLC inputs to the DIGIFORCE® 9311 unit. (See detailed documentation of these signals within the DIGIFORCE® 9311 operation manual, 6.1.3 PLC inputs).

6.2.1 PLC inputs byte 1 - Scanner to adapter (DIGIFORCE®)

| PLC inputs Byte 1 - Scanner to adapter (DIGIFORCE®) | | |
|---|---|-----------|
| Valid values: | Adjustable input #1 (Pin 4) Default: IN_TARE_X | Bit 0 LSB |
| | Adjustable input #2 (Pin 5) Default: IN_RES_STAT | Bit 1 |
| Set reserved bits to '0' | Adjustable input #3 (Pin 6) Default: IN_STEST | Bit 2 |
| | IN_STROBE | Bit 3 |
| | IN_AUTO | Bit 4 |
| | Reserved | Bit 5 |
| | Reserved | Bit 6 |
| | Reserved | Bit 7 MSB |

6.2.2 PLC inputs byte 2 - Scanner to adapter (DIGIFORCE®)

| PLC inputs Byte 2 - Scanner to adapter (DIGIFORCE®) | | |
|---|----------|-----------|
| Valid values: | IN_PROG0 | Bit 0 LSB |
| | IN_PROG1 | Bit 1 |
| Set reserved bits to '0' | IN_PROG2 | Bit 2 |
| | IN_PROG3 | Bit 3 |
| | Reserved | Bit 4 |
| | Reserved | Bit 5 |
| | Reserved | Bit 6 |
| | Reserved | Bit 7 MSB |

6.2.3 PLC inputs byte 3 - Scanner to adapter (DIGIFORCE®)

| PLC inputs Byte 3 - Scanner to adapter (DIGIFORCE®) | | |
|---|----------|-----------|
| Valid values: | IN_START | Bit 0 LSB |
| | Reserved | Bit 1 |
| Set reserved bits to '0' | Reserved | Bit 2 |
| | Reserved | Bit 3 |
| | Reserved | Bit 4 |
| | Reserved | Bit 5 |
| | Reserved | Bit 6 |
| | Reserved | Bit 7 MSB |



NOTICE

Note that the adjustable PLC inputs (Pin 4, 5 and 6) can be assigned with different functions. The assignment can be changed within the DIGIFORCE® 9311 “Basic setup” menu (M18) under “Assignment of the PLC inputs” (for further information see DIGIFORCE® model 9311 operation manual chapter 6.1.3 “PLC inputs”).

6.3 PLC outputs – Transfer from adapter (DIGIFORCE®) to scanner

The data refers to the PLC output of the DIGIFORCE® 9311. The data described here is the data transferred from the DIGIFORCE® 9311 to the EtherNet/IP controller.

The function of the PLC-In / PLC-Out bits is identical to the parallel PLC I/O ports on the unit itself and can be found within the DIGIFORCE® 9311 operation manual for the unit. Also the signal timing is available within the DIGIFORCE® 9311 operation manual.

6.3.1 PLC outputs byte 1

| PLC outputs Byte 1 - Adapter (DIGIFORCE®) to scanner | | |
|--|--|-----------|
| Valid values: | OUT_READY | Bit 0 LSB |
| | OUT_OK | Bit 1 |
| | OUT_NOK | Bit 2 |
| | OUT_NOK_ONL | Bit 3 |
| | OUT_S1 | Bit 4 |
| | OUT_S2 | Bit 5 |
| | Adjustable output #1 (Pin 20) Default: OUT_OK_STEST | Bit 6 |
| | Adjustable output #6 (Pin 25) Default: OUT_MEAS_ACT | Bit 7 MSB |

6.3.2 PLC outputs byte 2

| PLC outputs Byte 2 - Adapter (DIGIFORCE®) to scanner | | |
|--|--|-----------|
| Valid values: | Adjustable output #2 (Pin 21) Default: OUT_STROBE | Bit 0 LSB |
| | Adjustable output #3 (Pin 22) Default: OUT_PROG0 | Bit 1 |
| | Adjustable output #4 (Pin 23) Default: OUT_PROG1 | Bit 2 |
| | Adjustable output #5 (Pin 24) Default: OUT_PROG2 | Bit 3 |
| | Reserved | Bit 4 |
| | Reserved | Bit 5 |
| | Reserved | Bit 6 |
| | Reserved | Bit 7 MSB |



NOTICE

Note that PLC outputs [6..1] can be assigned with different functions. The assignment can be changed within the DIGIFORCE® 9311 "Basic setup" menu (M18) under "Assignment of the PLC outputs"(see DIGIFORCE® model 9311 operation manual chapter 6.1.2 "PLC outputs").

6.4 Evaluation info – Transfer from adapter (DIGIFORCE®) to scanner

The evaluation info (2 bytes) contains the evaluation result of each element.

6.4.1 Evaluation info byte 1

| Evaluation info byte 1 - Adapter (DIGIFORCE®) to scanner | | |
|--|-----------------|-----------|
| Valid values: | Global_NOK | Bit 0 LSB |
| | Overload _NOK | Bit 1 |
| | Window_1_NOK | Bit 2 |
| | Window_2_NOK | Bit 3 |
| | Window_3_NOK | Bit 4 |
| | Threshold_1_NOK | Bit 5 |
| | Threshold_2_NOK | Bit 6 |
| | Trapezoid_1_NOK | Bit 7 MSB |

6.4.2 Evaluation info byte 2

| Evaluation info byte 2 - Adapter (DIGIFORCE®) to scanner | | |
|--|-----------------------|-----------|
| Valid values: | Trapezoid_2_NOK | Bit 0 LSB |
| | Envelope_NOK | Bit 1 |
| | Measurement w/o READY | Bit 2 |
| | USB logging error | Bit 3 |
| | Reserved | Bit 4 |
| | Reserved | Bit 5 |
| | Reserved | Bit 6 |
| | Reserved | Bit 7 MSB |

6.5 Byte reference list

Data from scanner to adapter (DIGIFORCE®)

| Byte | Function | Section | Comments |
|------|-------------------|---------|----------|
| 0 | PLC inputs Byte 1 | 6.2.1 | |
| 1 | PLC inputs Byte 2 | 6.2.2 | |
| 2 | PLC inputs Byte 3 | 6.2.3 | |

Data from adapter (DIGIFORCE®) to scanner

| Byte | Function | Section | Comments |
|------|---|---|--|
| 0 | PLC outputs Byte 1 | 6.3.1 | |
| 1 | PLC outputs Byte 2 | 6.3.2 | |
| 2 | Evaluation info Byte 1 | 6.4.1 | |
| 3 | Evaluation info Byte 2 | 6.4.2 | |
| 4 | User-defined value_1 (1 st Byte) | see DIGIFORCE® 9311 operation manual 6.3.8 User defined values | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 5 | User-defined value_1 (2 nd Byte) | see above | |
| 6 | User-defined value_1 (3 rd Byte) | see above | |
| 7 | User-defined value_1 (4 th Byte) | see above | |
| 8 | User-defined value_2 (1 st Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 9 | User-defined value_2 (2 nd Byte) | see above | |
| 10 | User-defined value_2 (3 rd Byte) | see above | |
| 11 | User-defined value_2 (4 th Byte) | see above | |
| 12 | User-defined value_3 (1 st Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 13 | User-defined value_3 (2 nd Byte) | see above | |
| 14 | User-defined value_3 (3 rd Byte) | see above | |
| 15 | User-defined value_3 (4 th Byte) | see above | |
| 16 | User-defined value_4 (1 st Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 17 | User-defined value_4 (2 nd Byte) | see above | |
| 18 | User-defined value_4 (3 rd Byte) | see above | |
| 19 | User-defined value_4 (4 th Byte) | see above | |
| 20 | User-defined value_5 (1 st Byte) | see above | User defined value in |

| Byte | Function | Section | Comments |
|-------------|--|----------------|--|
| 21 | User-defined value_5 (2 nd Byte) | see above | DIGIFORCE® 9311 (32-Bit float) |
| 22 | User-defined value_5 (3 rd Byte) | see above | |
| 23 | User-defined value_5 (4 th Byte) | see above | |
| 24 | User-defined value_6 (1 st Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 25 | User-defined value_6 (2 nd Byte) | see above | |
| 26 | User-defined value_6 (3 rd Byte) | see above | |
| 27 | User-defined value_6 (4 th Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 28 | User-defined value_7 (1 st Byte) | see above | |
| 29 | User-defined value_7 (2 nd Byte) | see above | |
| 30 | User-defined value_7 (3 rd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 31 | User-defined value_7 (4 th Byte) | see above | |
| 32 | User-defined value_8 (1 st Byte) | see above | |
| 33 | User-defined value_8 (2 nd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 34 | User-defined value_8 (3 rd Byte) | see above | |
| 35 | User-defined value_8 (4 th Byte) | see above | |
| 36 | User-defined value_9 (1 st Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 37 | User-defined value_9 (2 nd Byte) | see above | |
| 38 | User-defined value_9 (3 rd Byte) | see above | |
| 39 | User-defined value_9 (4 th Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 40 | User-defined value_10 (1 st Byte) | see above | |
| 41 | User-defined value_10 (2 nd Byte) | see above | |
| 42 | User-defined value_10 (3 rd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 43 | User-defined value_10 (4 th Byte) | see above | |
| 44 | User-defined value_11 (1 st Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 45 | User-defined value_11 (2 nd Byte) | see above | |
| 46 | User-defined value_11 (3 rd Byte) | see above | |
| 47 | User-defined value_11 (4 th Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 48 | User-defined value_12 (1 st Byte) | see above | |
| 49 | User-defined value_12 (2 nd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |

| Byte | Function | Section | Comments |
|-------------|--|----------------|--|
| 50 | User-defined value_12 (3 rd Byte) | see above | |
| 51 | User-defined value_12 (4 th Byte) | see above | |
| 52 | User-defined value_13 (1 st Byte) | see above | |
| 53 | User-defined value_13 (2 nd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 54 | User-defined value_13 (3 rd Byte) | see above | |
| 55 | User-defined value_13 (4 th Byte) | see above | |
| 56 | User-defined value_14 (1 st Byte) | see above | |
| 57 | User-defined value_14 (2 nd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 58 | User-defined value_14 (3 rd Byte) | see above | |
| 59 | User-defined value_14 (4 th Byte) | see above | |
| 60 | User-defined value_15 (1 st Byte) | see above | |
| 61 | User-defined value_15 (2 nd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 62 | User-defined value_15 (3 rd Byte) | see above | |
| 63 | User-defined value_15 (4 th Byte) | see above | |
| 64 | User-defined value_16 (1 st Byte) | see above | |
| 65 | User-defined value_16 (2 nd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 66 | User-defined value_16 (3 rd Byte) | see above | |
| 67 | User-defined value_16 (4 th Byte) | see above | |
| 68 | User-defined value_17 (1 st Byte) | see above | |
| 69 | User-defined value_17 (2 nd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 70 | User-defined value_17 (3 rd Byte) | see above | |
| 71 | User-defined value_17 (4 th Byte) | see above | |
| 72 | User-defined value_18 (1 st Byte) | see above | |
| 73 | User-defined value_18 (2 nd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 74 | User-defined value_18 (3 rd Byte) | see above | |
| 75 | User-defined value_18 (4 th Byte) | see above | |
| 76 | User-defined value_19 (1 st Byte) | see above | |
| 77 | User-defined value_19 (2 nd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 78 | User-defined value_19 (3 rd Byte) | see above | |

| Byte | Function | Section | Comments |
|------|--|-----------|---|
| 79 | User-defined value_19 (4 th Byte) | see above | |
| 80 | User-defined value_20 (1 st Byte) | see above | |
| 81 | User-defined value_20 (2 nd Byte) | see above | User defined value in DIGIFORCE® 9311 (32-Bit float) |
| 82 | User-defined value_20 (3 rd Byte) | see above | |
| 83 | User-defined value_20 (4 th Byte) | see above | |
| 84 | Live value Channel X (1 st Byte) | | |
| 85 | Live value Channel X (2 nd Byte) | | (32-Bit float) Channel X live value Updating rate of the live values 100/sec. |
| 86 | Live value Channel X (3 rd Byte) | | |
| 87 | Live value Channel X (4 th Byte) | | |
| 88 | Live value Channel Y (1 st Byte) | | |
| 89 | Live value Channel Y (2 nd Byte) | | (32-Bit float) Channel Y live value Updating rate of the live values 100/sec. |
| 90 | Live value Channel Y (3 rd Byte) | | |
| 91 | Live value Channel Y (4 th Byte) | | |

7 Unconnected Explicit Messaging (Acyclic services)

The services are described from the point of view of the controller.

Note: The instance number has always to be set to 1.

The acyclic EtherNet/IP services allow access to following DIGIFORCE® 9311 functions:

- Complete device configuration
- Transfer of component/worker/job data for logging
- Retrieval of large amounts of process and curve data

7.1 Instrument configuration

7.1.1 General settings (Class 100)

Class 100, Attributes 0 to 18

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|-------------------------|--|-------|-----|-----|
| 100 | 0 | | - | Not possible | | | X |
| 100 | 1...9 | Reserved | - | Not possible | | | X |
| 100 | 10 | Device detection | DIGIFORCE model 9311 | | STR18 | 18 | RO |
| 100 | 11 | Serial number | 12345678 | | STR11 | 11 | RO |
| 100 | 12 | Software version | V201600 | | STR25 | 25 | RO |
| 100 | 13 | Version boot loader software | V201500 | | STR25 | 25 | RO |
| 100 | 14 | Software version Field bus interface | PN-V201600 | | STR25 | 25 | RO |
| 100 | 15 | Optional analog interface enabled | 0 1 2 3 | Strain gauge+Potent. Piezo+Potentiometer Strain gauge+Increm. Piezo+Incremental | U16 | 2 | RO |
| 100 | 16 | Info: Calibration date analog interface | 07.11.2016 | | STR10 | 10 | RO |
| 100 | 17 | Station name | Stat14 right | | STR15 | 15 | RW |
| 100 | 18 | reserved | - | - | - | - | - |

Class 100, Attributes 19 to 35

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|--|--|-------|-----|-----|
| 100 | 19 | Language | 0 1 2 3 4 5 | German English French Spanish Italian Chinese | U16 | 2 | RW |
| 100 | 20 | Date | [dd.mm.yyyy] | e.g.: 21.09.2016 | STR10 | 10 | RW |
| 100 | 21 | Time | [hh:mm:ss], 24h | e.g.: 16:15:00 | STR8 | 8 | RW |
| 100 | 22 | LCD brightness | 1 ... 10 | Integer value (10 max.) | U16 | 2 | RW |
| 100 | 23 | Measurement menu function key definition F1 | 0 1 2 3 4 5 6 7 8 9 | Off Meas. program incremental Meas. program decremental Tare X Tare Y Measurement Start/Stop Acknowledge OK parts Acknowledge NOK parts Sensor test Edit mode | U16 | 2 | RW |
| 100 | 24 | Measurement menu function key definition F2 | 0 1 2 3 4 5 6 7 8 9 | Off Meas. program incremental Meas. program decremental Tare X Tare Y Measurement Start/Stop Acknowledge OK parts Acknowledge NOK parts Sensor test Edit mode | U16 | 2 | RW |
| 100 | 25 | Measurement menu function key definition F3 | 0 1 2 3 4 5 6 7 8 9 | Off Meas. program incremental Meas. program decremental Tare X Tare Y Measurement Start/Stop Acknowledge OK parts Acknowledge NOK parts Sensor test Edit mode | U16 | 2 | RW |
| 100 | 26 | Display mode of function Keys | 0 1 | Fade out Always on | U16 | 2 | RW |
| 100 | 27 | Meas. menu display control GRAPHIC | 0 1 | Meas. menu disabled Meas. menu enabled | U16 | 2 | RW |
| 100 | 28 | Meas. menu display control GENERAL CURVE | 0 1 | Meas. menu disabled Meas. menu enabled | U16 | 2 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|---|--|------------|----------|-----------|
| | | DATA | | | | | |
| 100 | 29 | Meas. menu display control TOTAL (Off/Smiley/text) | 0 1 2 | Meas. menu disabled Smiley Text | U16 | 2 | RW |
| 100 | 30 | Meas. menu display control ENTRY/EXIT VALUES | 0 1 | Meas. menu disabled Meas. menu enabled | U16 | 2 | RW |
| 100 | 31 | Meas. menu display control USER DEFINED MEAS. VALUES | 0 1 | Meas. menu disabled Meas. menu enabled | U16 | 2 | RW |
| 100 | 32 | Meas. menu display control STATISTICS | 0 1 | Meas. menu disabled Meas. menu enabled | U16 | 2 | RW |
| 100 | 33 | Meas. menu display control ORDER SHEET | 0 1 | Meas. menu disabled Meas. menu enabled | U16 | 2 | RW |
| 100 | 34 | Show/Hide of Live Values | 0 1 | Show Live Values Hide Live Values | U16 | 2 | RW |
| 100 | 35 | Display the measurement menu, read the currently displayed measurement menu Note: The menu is selected here, but not yet displayed. Display only occurs through access to Class 100/68. | 101 102 103 104 105 106 107 | M1 Displaying meas. curves M2 General curve data M3 Total Result M4 Entry/Exit M5 User defined values M6 Statistics M7 Order sheet | U16 | 2 | RW |

Class 100, Attributes 36 to 51

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|--------|---|------|-----|-----|
| 100 | 36 | Access authorisation Password protection on/off | 0 1 | Password protection on Password protection off | U16 | 2 | RW |
| 100 | 37 | Access authorisation BASIC SETUP MENU | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 38 | Access authorisation PROGRAM SELECTION | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 39 | Access authorisation COPY PROGRAMS | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|------------------|---|------|-----|-----|
| 100 | 40 | Access authorisation CURVE ANALYSIS | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 41 | Access authorisation CHANNEL SETTINGS | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 42 | Access authorisation MEASUREMENT MODE | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 43 | Access authorisation EVALUATION | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 44 | Access authorisation REALTIME SWITSCHPOINTS | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 45 | Access authorization TEST OPERATION | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 46 | Access authorisation SENSOR TEST | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 47 | Access authorisation USER DEFINED VALUES | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 48 | Access authorisation EXTERNAL MEMORY | 0 1 | Access level disabled Access level enabled | U16 | 2 | RW |
| 100 | 49 | Master password | 0000 ... 9999 | | U16 | 2 | RW |
| 100 | 50 | Set Master password to default | EVENT! | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 100 | 51 | User password | 0000 ... 9999 | | U16 | 2 | RW |

Class 100, Attribute 52 (Assignment adjustable PLC output 1)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|----------------------------|-------|------------------|------|-----|-----|
| 100 | 52 | adj. PLC output 1 (Pin 20) | 0 | OUT_OK_STEST | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 1 | OUT_STROBE | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 2 | OUT_PROG0 | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 3 | OUT_PROG1 | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 4 | OUT_PROG2 | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 5 | OUT_PROG3 | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 6 | OUT_MEAS_ACT | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 7 | OUT_S3 | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 8 | OUT_S4 | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 9 | OUT_S5 | U16 | 2 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|----------------------------|--------------|-------------------------|-------------|------------|------------|
| 100 | 52 | adj. PLC output 1 (Pin 20) | 10 | OUT_S6 | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 11 | OUT_TEST_OP | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 12 | OUT_ERROR | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 13 | OUT_WARN_TARE | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 14 | OUT_CONFIG | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 15 | OUT_ACK_ALARM | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 16 | OUT_ACK_LOCK | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 17 | OUT_ACK_OK | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 18 | OUT_ACK_NOK | U16 | 2 | RW |
| 100 | 52 | adj. PLC output 1 (Pin 20) | 19 | OUT_PC_LOG | U16 | 2 | RW |

Class 100, Attributes 53 to 57 (Assignment adjustable PLC outputs 2 to 6)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|----------------------------|--------------|-------------------------|-------------|------------|------------|
| 100 | 53 | adj. PLC output 2 (Pin 21) | see index 52 | | U16 | 2 | RW |
| 100 | 54 | adj. PLC output 3 (Pin 22) | see index 52 | | U16 | 2 | RW |
| 100 | 55 | adj. PLC output 4 (Pin 23) | see index 52 | | U16 | 2 | RW |
| 100 | 56 | adj. PLC output 5 (Pin 24) | see index 52 | | U16 | 2 | RW |
| 100 | 57 | adj. PLC output 6 (Pin 25) | see index 52 | | U16 | 2 | RW |

Class 100, Attribute 58 (Assignment adjustable PLC input 1)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|--------------------------|--------------|-------------------------|-------------|------------|------------|
| 100 | 58 | adj. PLC input 1 (Pin 4) | 0 | IN_TARE_X | U16 | 2 | RW |
| 100 | 58 | adj. PLC input 1 (Pin 4) | 1 | IN_TARE_Y | U16 | 2 | RW |
| 100 | 58 | adj. PLC input 1 (Pin 4) | 2 | IN_TARE_X+Y | U16 | 2 | RW |
| 100 | 58 | adj. PLC input 1 (Pin 4) | 3 | IN_RES_STAT | U16 | 2 | RW |
| 100 | 58 | adj. PLC input 1 (Pin 4) | 4 | IN_STEST | U16 | 2 | RW |
| 100 | 58 | adj. PLC input 1 (Pin 4) | 5 | IN_TEST_OP | U16 | 2 | RW |
| 100 | 58 | adj. PLC input 1 (Pin 4) | 6 | IN_ACK | U16 | 2 | RW |
| 100 | 58 | adj. PLC input 1 (Pin 4) | 7 | IN_ACK_OK | U16 | 2 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--------------------------|-------|------------------|------|-----|-----|
| 100 | 58 | adj. PLC input 1 (Pin 4) | 8 | IN_ACK_NOK | U16 | 2 | RW |
| 100 | 58 | adj. PLC input 1 (Pin 4) | 9 | IN_ACK_ERROR | U16 | 2 | RW |

Class 100, Attributes 59 to 60 (Assignment PLC inputs 2 to 3)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--------------------------|--------------|------------------|------|-----|-----|
| 100 | 59 | adj. PLC input 2 (Pin 5) | see index 58 | | U16 | 2 | RW |
| 100 | 60 | adj. PLC input 3 (Pin 6) | see index 58 | | U16 | 2 | RW |

Class 100, Attributes 61 to 71

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|-----------------|--|--------|-----|-----|
| 100 | 61 | Order sheet: Operator | Michael_Mueller | | STR 64 | 64 | RW |
| 100 | 62 | Order sheet: Order number | AN_123456 | | STR 64 | 64 | RW |
| 100 | 63 | Order sheet: Batch | BATCH_ 257-3 | | STR 64 | 64 | RW |
| 100 | 64 | Order sheet: Component | Cylinder_right | | STR 64 | 64 | RW |
| 100 | 65 | Order sheet: Serial number 1 | SN_123456789 | | STR 64 | 64 | RW |
| 100 | 66 | Order sheet: Serial number 2 | SN_987654321 | | STR 64 | 64 | RW |
| 100 | 67 | Acknowledgement function on/off | 0 1 | Acknowledgement function off Acknowledgement function on | U16 | 2 | RW |
| 100 | 68 | Acknowledgement function: Acknowledge OK parts on/off | 0 1 | Not active User has to confirm OK parts (F-Key or PLC input) | U16 | 2 | RW |
| 100 | 69 | Acknowledgement function: Acknowledge NOK parts on/off | 0 1 | Not active User has to confirm NOK parts (F-Key or PLC input) | U16 | 2 | RW |
| 100 | 70 | Acknowledgement function: Buzzer volume | 0 ... 10 | 10: max. volume | U16 | 2 | RW |
| 100 | 71 | Update display (refresh view) | Event! | Writing an arbitrary byte initiates action | U8 | 1 | WO |

7.1.2 Communication: Change menu, display update, fault indication (Class 101)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|------------------------------------|------------|---|------|-----|-----|
| 101 | 0 | Not possible | - | - | x | x | x |
| 101 | 1 - 9 | Reserved | - | - | x | x | x |
| 101 | 10 | Go to menu | 0 1 | Meas. Menu Graphical test menu | U16 | 2 | WO |
| 101 | 11 | Initiate update of the LCD display | EVENT! | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 101 | 12 | Device fault status | 0x00000001 | PREFIX addressing fault | U32 | 4 | RO |
| | | | 0x00000002 | Enquiry received in Device mode | U32 | 4 | RO |
| | | | 0x00000004 | Blockcheck error | U32 | 4 | RO |
| | | | 0x00000008 | Command fault | U32 | 4 | RO |
| | | | 0x00000010 | Parameter error | U32 | 4 | RO |
| | | | 0x00000020 | Timeout Receive Timer | U32 | 4 | RO |
| | | | 0x00000040 | Timeout Response Timer | U32 | 4 | RO |
| | | | 0x00000080 | Invalid ! or ? | U32 | 4 | RO |
| | | | 0x00000100 | Invalid configuration | U32 | 4 | RO |
| | | | 0x00000400 | No valid measurements are available | U32 | 4 | RO |
| | | | 0x00004000 | Reading out the measurement curve was interrupted by the beginning of a new measurement | U32 | 4 | RO |
| | | | 0x00080000 | No TEDS or TEDS is not valid | U32 | 4 | RO |
| | | | 0x00100000 | TEDS voltage too low | U32 | 4 | RO |
| | | | 0x00200000 | TEDS ID not valid | U32 | 4 | RO |
| | | | 0x00400000 | TEDS Version not valid | U32 | 4 | RO |
| | | | 0x00800000 | Strain gauge sensor connected but another sensor selected | U32 | 4 | RO |
| | | | 0x01000000 | Standard signal sensor connected but another sensor selected | U32 | 4 | RO |
| | | | 0x02000000 | Unknown error | U32 | 4 | RO |
| | | | 0x04000000 | Sensor type is not valid | U32 | 4 | RO |
| | | | 0x08000000 | Potentiometer sensor connected but another sensor selected | U32 | 4 | RO |
| | | | 0x10000000 | Direction of strain gauge is not valid | U32 | 4 | RO |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|-------------|------------|------------------|------|-----|-----|
| | | | 0x20000000 | USB Flash Error | U32 | 4 | RO |

7.1.3 Program Selection/Renaming & Statistics reset (Class 102)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|--------------|---|--------|-----|-----|
| 102 | 0 | Not possible | - | - | X | X | X |
| 102 | 1 - 9 | Reserved | - | - | X | X | X |
| 102 | 10 | Set program number | 0 ... 15 | | U16 | 2 | RW |
| 102 | 11 | Writing/Reading of the current program name | Program name | | STR 20 | 20 | RW |
| 102 | 12 | Reset statistics of a measurement program | 0 ... 15 | EVENT! Selection through writing the program number | U16 | 2 | WO |
| 102 | 13 | Reset statistics in all measurement programs | EVENT! | Writing an arbitrary byte initiates action | U8 | 1 | WO |

7.1.4 General channel settings (Class 103)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|--------------------------------------|---|------|-----|-----|
| 103 | 0 | Not possible | - | - | | | X |
| 103 | 1 - 9 | Reserved | - | - | | | X |
| 103 | 10 | Channel settings channel X Note: First make the settings in Attributes 10, 11 then initiate with index 12! | 0 1 2 3 4 5 | Terminals: A, Potentiometer A, standard signal B, strain gauge B, standard signal B, Piezo Time | U16 | 2 | RW |
| 103 | 11 | Channel settings channel Y Note: First make the settings in Attributes 10, 11 then initiate with index 12! | 0 1 2 3 4 5 | Terminals: A, Potentiometer A, standard signal B, strain gauge B, standard signal B, Piezo Time | U16 | 2 | RW |
| 103 | 12 | Accept channel settings | Event! | The settings from Attributes 10, 11 are being stored. Writing an arbitrary byte initiates action. | U8 | 1 | WO |
| 103 | 13 | Filter channel X Note: Not available for the channel settings "Piezo" | 0 1 2 3 4 5 6 7 | Off 5 Hz filter 10 Hz filter 25 Hz filter 50 Hz filter 100 Hz filter 200 Hz filter 400 Hz filter | U16 | 2 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|--|--|------|-----|-----|
| | | | 8 | 800 Hz filter | | | |
| 103 | 14 | Filter channel Y Notes: Not available for the channel settings "Piezo" | 0 1 2 3 4 5 6 7 8 | Off 5 Hz filter 10 Hz filter 25 Hz filter 50 Hz filter 100 Hz filter 200 Hz filter 400 Hz filter 800 Hz filter | U16 | 2 | RW |
| 103 | 15 | Transmitter supply channel X Note: Entry is not available for the channel settings "Piezo" Only for 'BlackBox' devices | 0 1 | Transmitter supply off Transmitter supply on | U16 | 2 | RW |
| 103 | 16 | Transmitter supply channel Y Note: Entry is not available for the channel settings "Piezo" Only for 'BlackBox' devices | 0 1 | Transmitter supply off Transmitter supply on | U16 | 2 | RW |
| 103 | 17 | Set unit channel X Note: Entry is not available for the channel settings "Time" | 0 1 2 3 4 5 6 7 8 9 10 11 12 | User defined unit 1 User defined unit 2 User defined unit 3 mm N kN Nm Ncm grd bar V s ms | U16 | 2 | RW |
| 103 | 18 | Set unit channel Y Note: Entry is not available for the channel settings "Time" | 0 1 2 3 4 5 6 7 8 9 | User defined unit 1 User defined unit 2 User defined unit 3 mm N kN Nm Ncm grd bar | U16 | 2 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|----------------|--|-------|-----|-----|
| | | | 10 11 12 | V s ms | | | |
| 103 | 19 | Set user defined unit 1 | abcd | | STR 4 | 4 | RW |
| 103 | 20 | Set user defined unit 2 | abcd | | STR 4 | 4 | RW |
| 103 | 21 | Set user defined unit 3 | ijkl | | STR 4 | 4 | RW |
| 103 | 22 | Returns the measured value on channel X Note: Entry is not available for the channel settings "Time" | EVENT! | | FLT | 4 | RO |
| 103 | 23 | Returns the measured value on channel Y Note: Entry is not available for the channel settings "Time" | EVENT! | | FLT | 4 | RO |
| 103 | 24 | Channel to be scaled | 0 1 | Channel X Channel Y | U 16 | 2 | WO |
| 103 | 25 | Lower scale value | | Concerns the channel selected under index 24 | FLT | 4 | RW |
| 103 | 26 | Upper scale value | | Concerns the channel selected under index 24 | FLT | 4 | RW |
| 103 | 27 | Lower calibration value | | Concerns the channel selected under index 24 | FLT | 4 | RW |
| 103 | 28 | Upper calibration value | | Concerns the channel selected under index 24 | FLT | 4 | RW |
| 103 | 29 | Perform scaling (as per index 25 ... 29) | EVENT | Entry is not available for the channel settings "Off" and "Time" | U8 | 1 | WO |
| 103 | 30 | Switch between program depending and global channel settings | 0 1 | Program depending Global Note: If changing to global settings, the individual channel setting will get lost | U 16 | 2 | RW |

7.1.5 Channel settings “Standard signal” (Class 104)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|---------------------------------|--------------|-------------------------------------|-------------|------------|------------|
| 104 | 0 | Not possible | - | - | | | X |
| 104 | 1 - 9 | Reserved | - | - | | | X |
| 104 | 10 | Standard signal input channel X | 0 1 | 5 V input range 10 V input range | U16 | 2 | RW |
| 104 | 11 | Standard signal input channel Y | 0 1 | 5 V input range 10 V input range | U16 | 2 | RW |

7.1.6 Channel settings “Strain gauge” (Class 105)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|---------------------------------------|-----------------------|---|-------------|------------|------------|
| 105 | 0 | Not possible | - | - | | | X |
| 105 | 1 - 9 | Reserved | - | - | | | X |
| 105 | 10 | Strain gauge input range channel X | 0 1 2 3 4 | 2 mV/V input range 4 mV/V input range 10 mV/V input range 20 mV/V input range 40 mV/V input range | U16 | 2 | RW |
| 105 | 11 | Strain gauge input range channel Y | 0 1 2 3 4 | 2 mV/V input range 4 mV/V input range 10 mV/V input range 20 mV/V input range 40 mV/V input range | U16 | 2 | RW |
| 105 | 12 | Strain gauge sensitivity channel X | 0.01 ... 100.0 | IEEE754 Float | FLT | 4 | RW |
| 105 | 13 | Strain gauge sensitivity channel Y | 0.01 ... 100.0 | IEEE754 Float | FLT | 4 | RW |
| 105 | 14 | Level (elect.) strain gauge channel X | 0.01 ... 100.0 | IEEE754 Float | FLT | 4 | RO |
| 105 | 15 | Level (elect.) strain gauge channel Y | 0.01 ... 100.0 | IEEE754 Float | FLT | 4 | RO |

7.1.7 Channel settings “Piezo” (Class 106)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|--|--|------|-----|-----|
| 106 | 0 | Not possible | - | - | | | X |
| 106 | 1 - 9 | Reserved | - | - | | | X |
| 106 | 10 | Piezo input range channel X | 0 1 2 3 4 5 6 7 8 9 | 1nC range 2nC range 5nC range 10nC range 20nC range 40nC range 80nC range 200nC range 400nC range 1uC range | U16 | 2 | RW |
| 106 | 11 | Piezo input range channel Y | 0 1 2 3 4 5 6 7 8 9 | 1nC range 2nC range 5nC range 10nC range 20nC range 40nC range 80nC range 200nC range 400nC range 1uC range | U16 | 2 | RW |
| 106 | 12 | Piezo short-circuit on/to channel X | 0 1 | Do not short-circuit piezo input Short-circuit piezo input | U16 | 2 | WO |
| 106 | 13 | Piezo short-circuit on/to channel Y | 0 1 | Do not short-circuit piezo input Short-circuit piezo input | U16 | 2 | WO |

7.1.8 Tare (Class 107)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W | |
|-------|-------|--------------------------------------|---|------------------|--|-----|-----|----|
| 107 | 0 | Not possible | - | - | | | X | |
| 107 | 1...9 | Reserved | - | - | | | X | |
| 107 | 10 | Tare at meas. start channel X | 0 1 | off on | U16 | 2 | RW | |
| 107 | 11 | Tare at meas. start channel Y | 0 1 | off on | U16 | 2 | RW | |
| 107 | 12 | Standard value for tare channel X | <i>between</i> <i>-9999999.0</i> <i>and</i> <i>9999999.0</i> | | Float value, Float according to IEEE754 | FLT | 4 | RW |
| 107 | 13 | Standard value for tare channel Y | <i>between</i> <i>-9999999.0</i> <i>and</i> <i>9999999.0</i> | | Float value, Float according to IEEE754 | FLT | 4 | RW |
| 107 | 14 | Tare warning on/off channel X | 0 1 | off on | U16 | 2 | RW | |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|----------------------------------|-----------------------------|--|------|-----|-----|
| 107 | 15 | Tare warning on/off channel Y | 0 1 | off on | U16 | 2 | RW |
| 107 | 16 | Set tare warning limit channel X | <i>between 1.0 and 20.0</i> | Float value, Float according to IEEE754 | FLT | 4 | RW |
| 107 | 17 | Set tare warning limit channel Y | <i>between 1.0 and 20.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 107 | 18 | Tare channel X | <i>EVENT!</i> | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 107 | 19 | Delete tare channel X | <i>EVENT!</i> | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 107 | 20 | Tare channel Y | <i>EVENT!</i> | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 107 | 21 | Delete tare channel Y | <i>EVENT!</i> | Writing an arbitrary byte initiates action | U8 | 1 | WO |

7.1.9 Measurement mode (Class 108)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|---|---|------|-----|-----|
| 108 | 0 | Not possible | - | - | | | X |
| 108 | 1...9 | Reserved | - | - | | | X |
| 108 | 10 | X sampling off/on | 0 1 | off on | U16 | 2 | RW |
| 108 | 11 | X sample rate | <i>between 0.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 108 | 12 | Y sampling off/on | 0 1 | off on | U16 | 2 | RW |
| 108 | 13 | Y sample rate | <i>between 0.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 108 | 14 | Time sampling off/on | 0 1 | off on | U16 | 2 | RW |
| 108 | 15 | Time sample rate | <i>between 0.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 108 | 16 | Set reference of curve Note: "Underrun" is not permitted if the channel concerned is set to time. | 0 1 2 3 4 5 | Absolute Final force Y reference line overrun Y reference line underrun Y trigger overrun Y trigger underrun | U16 | 2 | RW |
| 108 | 17 | Set reference line Y | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 108 | 18 | Set trigger line Y | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|---|--|------|-----|-----|
| 108 | 19 | Set return point | 0 1 2 3 | XMIN XMAX YMIN YMAX | U16 | 2 | RW |
| 108 | 20 | Set "Record curve to" | 0 1 | Complete curve Up to return point | U16 | 2 | RW |
| 108 | 21 | Set start mode | 0 1 2 3 4 | External X internal overrun X internal underrun Y internal overrun Y internal underrun | U16 | 2 | RW |
| 108 | 22 | Set stop mode | 0 1 2 3 4 5 6 | External X internal overrun X internal underrun Y internal overrun Y internal underrun Timeout Defined number of measured values | U16 | 2 | RW |
| 108 | 23 | Set X start value for internal start | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 108 | 24 | Set Y start value for internal start | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 108 | 25 | Set X stop value for internal stop | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 108 | 26 | Set Y stop value for internal stop | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 108 | 27 | Set the "stop" timeout value | <i>between 0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 108 | 28 | Set the "stop" number of measured values | <i>0 bis 5000</i> | Integer value | U16 | 2 | RW |

7.1.10 Evaluation window 1 (Class 109)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|--|---|--|-------------|------------|------------|
| 109 | 0 | Not possible | - | - | | | X |
| 109 | 1...9 | Reserved | - | - | | | X |
| 109 | 10 | Window 1 off/on | 0 1 | off on | U16 | 2 | RW |
| 109 | 11 | Window 1 limit Xmin Note: At the end, entry must be adopted through index 15. | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 109 | 12 | Window 1 limit Xmax Note: At the end, entry must be adopted through index 15. | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 109 | 13 | Window 1 limit Ymin Note: At the end, entry must be adopted through index 15. | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 109 | 14 | Window 1 limit Ymax Note: At the end, entry must be adopted through index 15. | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 109 | 15 | Window 1 copy limit Note: Values entered into Attributes 11, 12, 13,14 are adopted | EVENT! | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 109 | 16 | Window 1 entry left Note: At the end, entry must be adopted through index 24. | 0 1 | no yes | U16 | 2 | RW |
| 109 | 17 | Window 1 entry right Note: At the end, entry must be adopted through index 24. | 0 1 | no yes | U16 | 2 | RW |
| 109 | 18 | Window 1 entry bottom Note: At the end, entry must be adopted through index 24. | 0 1 | no yes | U16 | 2 | RW |
| 109 | 19 | Window 1 entry top Note: At the end, entry must be adopted through index 24. | 0 1 | no yes | U16 | 2 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|-----------------------|---|------|-----|-----|
| 109 | 20 | Window 1 exit left Note: At the end, entry must be adopted through index 24. | 0 1 | no yes | U16 | 2 | RW |
| 109 | 21 | Window 1 exit right Note: At the end, entry must be adopted through index 24. | 0 1 | no yes | U16 | 2 | RW |
| 109 | 22 | Window 1 exit bottom Note: At the end, entry must be adopted through index 24. | 0 1 | no yes | U16 | 2 | RW |
| 109 | 23 | Window 1 exit top Note: At the end, entry must be adopted through index 24. | 0 1 | no yes | U16 | 2 | RW |
| 109 | 24 | Copy window entry/exit Note: Values entered into Attributes 16 - 23 are adopted | EVENT! | no yes | U8 | 1 | WO |
| 109 | 25 | Window 1 curve segment for evaluation | 0 1 2 | Forward Return Complete curve | U16 | 2 | RW |
| 109 | 26 | Window 1 online evaluation | 0 1 2 3 4 | Off left - right right - left bottom - top top - bottom | U16 | 2 | RW |
| 109 | 27 | Window 1 Online signal level | 0 1 | Low active High active | U16 | 2 | RW |

7.1.11 Evaluation window 2 (Class 110)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|--------|---------------|-------|------------------|------|-----|-----|
| 110 | 0 | Not possible | - | - | | | X |
| 110 | 1...9 | Reserved | - | - | | | X |
| 110 | 10 ... | See Class 109 | | | | | |

7.1.12 Evaluation window 3 (Class 111)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|--------|---------------|-------|------------------|------|-----|-----|
| 111 | 0 | Not possible | - | - | | | X |
| 111 | 1...9 | Reserved | - | - | | | X |
| 111 | 10 ... | See Class 109 | | | | | |

7.1.13 Evaluation trapezoid window 1 (Class 112)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|---|---|------|-----|-----|
| 112 | 0 | Not possible | - | - | | | X |
| 112 | 1...9 | Reserved | - | - | | | X |
| 112 | 10 | Trapezoid 1 off/on | 0 1 | off on | U16 | 2 | RW |
| 112 | 11 | Trapezoid type X/Y | 0 1 | Type X-Trapezoid Type Y-Trapezoid | | | |
| 112 | 12 | Trapezoid 1 limit Type X: Xmin Type Y: Ymin Note: At the end, entry must be adopted through index 18 | between -9999999.0 and 9999999.0 | Float value Float according to IEEE754 | FLT | 4 | RW |
| 112 | 13 | Trapezoid 1 limit Type X: Xmax Type Y: Ymax Note: At the end, entry must be adopted through index 18 | between -9999999.0 and 9999999.0 | Float value Float according to IEEE754 | FLT | 4 | RW |
| 112 | 14 | Trapezoid 1 limit Type X: Ymin left Type Y: Xmin bottom Note: At the end, entry must be adopted through index 18 | between -9999999.0 and 9999999.0 | Float value Float according to IEEE754 | FLT | 4 | RW |
| 112 | 15 | Trapezoid 1 limit Type X: Ymax left Type Y: Xmax bottom | between -9999999.0 and 9999999.0 | Float value Float according to IEEE754 | FLT | 4 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|---|--|------|-----|-----|
| | | Note: At the end, entry must be adopted through index 18 | | | | | |
| 112 | 16 | Trapezoid 1 limit Type X: Ymin right Type Y: Xmin top Note: At the end, entry must be adopted through index 18 | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 112 | 17 | Trapezoid 1 limit Type X: Ymax right Type Y: Xmax top Note: At the end, entry must be adopted through index 18 | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 112 | 18 | Trapezoid 1 copy the limits Note: Values entered into Attributes 12 - 17 are adopted | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 112 | 19 | Trapezoid 1 entry Type X: entry left Type Y: entry bottom Note: At the end, entry must be adopted through index 23 | 0 1 | no yes | U16 | 2 | RW |
| 112 | 20 | Trapezoid 1 entry Type X: entry right Type Y: entry top Note: At the end, entry must be adopted through index 23 | 0 1 | no yes | U16 | 2 | RW |
| 112 | 21 | Trapezoid 1 exit Type X: exit left Type Y:exit bottom Note: At the end, | 0 1 | no yes | U16 | 2 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|-------------|--|------|-----|-----|
| | | entry must be adopted through index 23 | | | | | |
| 112 | 22 | Trapezoid 1 exit Type X: exit right Type Y: exit top Note: At the end, entry must be adopted through index 23 | 0 1 | no yes | U16 | 2 | RW |
| 112 | 23 | Trapezoid 1 copy entry/exit Note: Values entered into Attributes 19- 22 are adopted. | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 112 | 24 | Trapezoid 1 curve segment for evaluation | 0 1 2 | Forward Return Complete curve | U16 | 2 | RW |

7.1.14 Evaluation trapezoid window 2 (Class 113)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|--------|---------------|-------|------------------|------|-----|-----|
| 113 | 0 | Not possible | - | - | | | X |
| 113 | 1...9 | Reserved | - | - | | | X |
| 113 | 10 ... | See Class 112 | | | | | |

7.1.15 Evaluation threshold 1 (Class 114)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|---|---|------|-----|-----|
| 114 | 0 | Not possible | - | - | | | X |
| 114 | 1...9 | Reserved | - | - | | | X |
| 114 | 10 | Threshold 1 off/on | 0 1 | off on | U16 | 2 | RW |
| 114 | 11 | Threshold 1 type of threshold | 0 1 | Type X (vertical) Type Y (horizontal) | U16 | 2 | RW |
| 114 | 12 | Threshold 1 position Type X: X value Type Y: Y value Note: At the end, entry must be adopted through index 15. | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 114 | 13 | Threshold 1 limit | <i>between -9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|---|--|------|-----|-----|
| | | Type X: Ymin Type Y: Xmin Note: At the end, entry must be adopted through index 15. | <i>and</i> 9999999.0 | | | | |
| 114 | 14 | Threshold 1 limit Type X: Ymax Type Y: Xmax Note: At the end, entry must be adopted through index 15. | <i>between</i> -9999999.0 <i>and</i> 9999999.0 | Float value Float according to IEEE754 | FLT | 4 | RW |
| 114 | 15 | Threshold 1 copy position and limits Note: Values entered into Attributes 11 - 14 are adopted | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 114 | 16 | Threshold 1 passage Type X: left > right Type Y: bottom > top Note: At the end, entry must be adopted through index 18. | 0 1 | no yes | U16 | 2 | RW |
| 114 | 17 | Threshold 1 passage Type X: right > left Type Y: top > bottom Note: At the end, entry must be adopted through index 18. | 0 1 | no yes | U16 | 2 | RW |
| 114 | 18 | Threshold 1 Copy passage Note: Values entered into Attributes 16 - 17 are adopted | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 114 | 19 | Threshold 1 Curve segment for evaluation | 0 1 2 | Forward Return Complete curve | U16 | 2 | RW |

7.1.16 Evaluation threshold 2 (Class 115)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|--------|---------------|-------|------------------|------|-----|-----|
| 115 | 0 | Not possible | - | - | | | X |
| 115 | 1...9 | Reserved | - | - | | | X |
| 115 | 10 ... | See Class 114 | | | | | |

7.1.17 Evaluation envelope (Class 116 to 120)

Class/index data on request

7.1.18 Tolerance band for evaluation elements (Class 121)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|----------------------------------|--|------|-----|-----|
| 121 | 0 | Not possible | - | - | | | X |
| 121 | 1...9 | Reserved | - | - | | | X |
| 121 | 10 | Tolerance band X Note: At the end, entry must be adopted through index 12. | <i>between 0.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 121 | 11 | Tolerance band Y Note: At the end, entry must be adopted through index 12. | <i>between 0.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 121 | 12 | Store tolerance bands Note: Values entered into Attributes 10 - 11 are adopted. | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |

7.1.19 Realtime switchpoints S1 (Class 122)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|---|---|------|-----|-----|
| 122 | 0 | Not possible | - | - | | | X |
| 122 | 1...9 | Reserved | - | - | | | X |
| 122 | 10 | Switchpoint S1 value Note: At the end, entry must be adopted through index 14. | <i>between -9999999.0 and 9999999.0</i> | Float value Float according to IEEE754 | FLT | 4 | RW |
| 122 | 11 | Switchpoint S1 channel Note: At the end, entry must be adopted through index 14. | 0 1 | Channel X Channel Y | U16 | 2 | RW |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|--------|--|------|-----|-----|
| 122 | 12 | Switchpoint S1 level Note: At the end, entry must be adopted through index 14. | 0 1 | Low active High active | U16 | 2 | RW |
| 122 | 13 | Switchpoint 1 reference Note: At the end, entry must be adopted through index 14. | 0 1 | Absolute reference Trigger reference | U16 | 2 | RW |
| 122 | 14 | Switchpoint 1 Copy settings Note: Values entered into Attributes 10 - 13 are adopted. | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |

7.1.20 Realtime switchpoints S2 (Class 123)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---------------|-------|------------------|------|-----|-----|
| 123 | 0 | Not possible | - | - | | | X |
| 123 | 1...9 | Reserved | - | - | | | X |
| 123 | 10.. | See Class 122 | | | | | |

7.1.21 Realtime switchpoints S3 (Class 124)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---------------|-------|------------------|------|-----|-----|
| 124 | 0 | Not possible | - | - | | | X |
| 124 | 1...9 | Reserved | - | - | | | X |
| 124 | 10.. | See Class 122 | | | | | |

7.1.22 Realtime switchpoints S4 (Class 125)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---------------|-------|------------------|------|-----|-----|
| 125 | 0 | Not possible | - | - | | | X |
| 125 | 1...9 | Reserved | - | - | | | X |
| 125 | 10.. | See Class 122 | | | | | |

7.1.23 Realtime switchpoints S5 (Class 126)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---------------|-------|------------------|------|-----|-----|
| 126 | 0 | Not possible | - | - | | | X |
| 126 | 1...9 | Reserved | - | - | | | X |
| 126 | 10.. | See Class 122 | | | | | |

7.1.24 Realtime switchpoints S6 (Class 127)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---------------|-------|------------------|------|-----|-----|
| 127 | 0 | Not possible | - | - | | | X |
| 127 | 1...9 | Reserved | - | - | | | X |
| 127 | 10.. | See Class 122 | | | | | |

7.1.25 Sensors test (Class 128)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------------------|-------|---|---|---|------|-----|-----|
| 128 | 0 | Not possible | - | - | | | X |
| 128 | 1...9 | Reserved | - | - | | | X |
| 128 | 10 | Sensor test Channel X on/off | 0 1 | off on | U16 | 2 | RW |
| 128 | 11 | Sensor test Channel Y on/off | 0 1 | off on | U16 | 2 | RW |
| 128 | 12 | Sensor test Channel X measure reference value | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 128 | 13 | Sensor test Channel Y measure reference value | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 128 | 14 | Sensor test Channel X reference value | between -9999999.0 and 9999999.0 | Float value Float according to IEEE754 | FLT | 4 | RW |
| 128 | 15 | Sensor test Channel Y reference value | between -9999999.0 and 9999999.0 | Float value Float according to IEEE754 | FLT | 4 | RW |
| 128 | 16 | Sensor test Channel X tolerance | between 0.0 and 9999999.0 | Float value Float according to IEEE754 | FLT | 4 | RW |
| 128 | 17 | Sensor test Channel Y tolerance | between 0.0 and 9999999.0 | Float value Float according to IEEE754 | FLT | 4 | RW |
| 128 | 18 | Initiate sensor test | 0 1 | NOK OK | U16 | 2 | RO |
| Note: Read access | | | | | | | |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|-------|------------------|------|-----|-----|
| | | initiates the sensor test and delivers the result. | | | | | |

7.1.26 Setup user-defined values (Class 129)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|------------------------------|----------------------|-------------------------------|------|-----|-----|
| 129 | 0 | Not possible | - | - | | | X |
| 129 | 1...9 | Reserved | - | - | | | X |
| 129 | 10 | User-defined values value 1 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 11 | User-defined values value 2 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 12 | User-defined values value 3 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 13 | User-defined values value 4 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 14 | User-defined values value 5 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 15 | User-defined values value 6 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 16 | User-defined values value 7 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 17 | User-defined values value 8 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 18 | User-defined values value 9 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 19 | User-defined values value 10 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 20 | User-defined values value 11 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 21 | User-defined values value 12 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 22 | User-defined values value 13 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 23 | User-defined values value 14 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 24 | User-defined values value 15 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 25 | User-defined values value 16 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 26 | User-defined values value 17 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 27 | User-defined values value 18 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 28 | User-defined values value 19 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |
| 129 | 29 | User-defined values value 20 | <i>Integer value</i> | See operand table in appendix | U16 | 2 | RW |

7.1.27 Copy/initialize measurement programs (Class 130)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|---|--------------|--|-------------|------------|------------|
| 130 | 0 | Not possible | - | - | | X | X |
| 130 | 1...9 | Reserved | - | - | | X | X |
| 130 | 10 | Meas. program number source Note: The settings from Attributes 10 - 12 are being adopted through Attributes 13, 14 or 15. | 0 ... 15 | | U16 | 2 | WO |
| 130 | 11 | Meas. program number Target start Note: The settings from Attributes 10 - 12 are being adopted through Attributes 13, 14 or 15. | 0 ... 15 | | U16 | 2 | WO |
| 130 | 12 | Meas. program number Target end Note: The settings from Attributes 10 - 12 are being adopted through Attributes 13, 14 or 15. | 0 ... 15 | | U16 | 2 | WO |
| 130 | 13 | Copy whole program setup Note: Copy according to entries in Attributes 10 - 12. | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 130 | 14 | Copy sensor setup Note: Copy according to entries in Attributes 10 - 12. | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 130 | 15 | Initialize selected programs Note: Initializing according to Attributes 11 - 12. | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| 130 | 16 | Initialize all measurement programs and device parameters | EVENT | Writing an arbitrary byte initiates action | U8 | 1 | WO |

7.1.28 Reference curve (Class 131 to 133)

Class/index data on request

7.1.29 Test operation (Class 134)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|-------------------------------------|--------------------|----------------------------|------|-----|-----|
| 134 | 0 | Not possible | | | | | |
| 134 | 1...9 | Reserved | | | | | |
| 134 | 10 | Current measurement value channel X | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 134 | 11 | Current measurement value channel Y | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |

7.1.30 Zoom and autoscale (Class 135)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|--------------------|--|------|-----|-----|
| 135 | 0 | Not possible | - | - | | X | X |
| 135 | 1...9 | Reserved | - | - | | X | X |
| 135 | 10 | Switching autoscale/fix scale | 0 1 | Autoscale off Autoscale on | U16 | 2 | RW |
| 135 | 11 | Fix scale Xmin Note: At the end, entry must be adopted through index 15. | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RW |
| 135 | 12 | Fix scale Xmax Note: At the end, entry must be adopted through index 15. | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RW |
| 135 | 13 | Fix scale Ymin Note: At the end, entry must be adopted through index 15. | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RW |
| 135 | 14 | Fix scale Ymax Note: At the end, entry must be adopted through index 15. | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RW |
| 135 | 15 | Store fix scale Note: Values entered into Attributes 11 - 14 are adopted. | <i>EVENT!</i> | Writing an arbitrary byte initiates action | U8 | 1 | WO |

7.1.31 USB-Logging (Class 136)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--------------------------|-----------------------|--|--------|-----|-----|
| 136 | 0 | Not possible | - | - | | X | X |
| 136 | 1...9 | Reserved | - | - | | X | X |
| 136 | 10 | USB-Logging on/off | 0 1 | off on | U16 | 2 | RW |
| 136 | 11 | Designation of file name | 0 1 | Program name Order sheet | U16 | 2 | RW |
| 136 | 12 | State of USB-Drive | 0 1 2 3 | State couldn't be read Not attached Attached but not mounted Attached and mounted | U16 | 2 | RO |
| 136 | 13 | Free space on USB-Drive | String | If USB Drive is not attached or not mounted (see index 12) "0,000 MB" will be returned | STR 15 | 15 | RO |
| 136 | 14 | Format USB Drive | String "formatusb" | "formatusb" works as a password here | STR 9 | 9 | WO |
| 136 | 15 | READY-Control | 0 1 | off on | U16 | 2 | RW |

7.1.32 TEDS-Sensors (Class 137)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|--------|--|------|-----|-----|
| 137 | 0 | Not possible | - | - | | X | X |
| 137 | 1...9 | Reserved | - | - | | X | X |
| 137 | 10 | Connector | 0 1 | A B | U16 | 2 | WO |
| 137 | 11 | Direction | 0 1 | Preferred direction Against preferred direction | U16 | 2 | WO |
| 137 | 12 | Note: applicable for strain gauge sensors only | EVENT! | Writing an arbitrary byte initiates action | U8 | 1 | WO |
| | | | | | | | |

7.1.33 Reserved Classss (Classs 138...148)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|---------------|-------|--------------|-------|------------------|------|-----|-----|
| 138... 148 | XX | Not possible | - | - | X | X | X |

7.2 Measurement results

7.2.1 Status of measurement (Class 149)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|-----------------------------|---|------|-----|-----|
| 149 | 0 | Not possible | - | - | | X | X |
| 149 | 1...9 | Reserved | | | | X | X |
| 149 | 10 | Index of the last measured value of the current curve Caution: The number of the pair of values is shown on the display. The index begins at 0, the number at 1! | <i>16 Bit Integer value</i> | 0 means that there is no measurement curve | U16 | 2 | RO |
| 149 | 11 | Running measurement curve counter [only relevant for Digicontrol usage] | <i>32 Bit Integer value</i> | This counter is incremented by 1 when a measurement curve is newly acquired in any menu | U32 | 4 | RO |
| 149 | 12 | Amount of curves in current array of curves | 0...10 | Integer value between 0 and 10 | U16 | 2 | RO |

7.2.2 Further information for current measurement curve (Class 150)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|-----------------------------|------------------|------|-----|-----|
| 150 | 0 | Not possible | - | - | | X | X |
| 150 | 1...9 | Reserved | - | - | | X | X |
| 150 | 10 | Piece Counter | <i>32 Bit Integer value</i> | | U32 | 4 | RO |
| 150 | 11 | NOK counter (sum) | <i>32 Bit Integer value</i> | | U32 | 4 | RO |
| 150 | 12 | Total evaluation | 0 1 | NOK OK | U16 | 2 | RO |
| 150 | 13 | Attr. of the curve's return point Caution: The number of the pair of values is shown on the display. The index begins at 0, the number at 1! | <i>16 Bit Integer value</i> | | U16 | 2 | RO |
| 150 | 14 | Index of the last measured value of the curve Caution: The number of the pair of values is shown on the display. The index begins at 0, | <i>16 Bit Integer value</i> | | U16 | 2 | RO |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|---------------------------------------|--|---------------------------|-------------|------------|------------|
| | | the number at 1! | | | | | |
| 150 | 15 | Status overdrive of the A/D converter | 0 1 | No overdrive Overdrive | U16 | 2 | RO |
| 150 | 16 | Date of recording | <i>String in format dd.mm.yyyy</i> | | STR 10 | 10 | RO |
| 150 | 17 | Time of recording hh:mm:ss | <i>String in format hh:mm:ss</i> | | STR 8 | 8 | RO |
| 150 | 18 | Unit channel X | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | | STR 4 | 4 | RO |
| 150 | 19 | Unit channel Y | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | | STR 4 | 4 | RO |

7.2.3 General curve data (Class 151)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|--------------------------|--------------------|----------------------------|-------------|------------|------------|
| 151 | 0 | Not possible | - | - | | X | X |
| 151 | 1...9 | Reserved | - | - | | X | X |
| 151 | 10 | X-minimum, X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 11 | X-minimum, Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 12 | X-maximum, X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 13 | X-maximum, Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 14 | Y-minimum, X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 15 | Y-minimum, Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 16 | Y-maximum, X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 17 | Y-maximum, Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 18 | First value X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 19 | First value Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 20 | Last value X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 21 | Last value Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---------------------------|-------------|----------------------------|------|-----|-----|
| 151 | 22 | Return point X-coordinate | Float value | Float according to IEEE754 | FLT | 4 | RO |
| 151 | 23 | Return point Y-coordinate | Float value | Float according to IEEE754 | FLT | 4 | RO |

7.2.4 Request measurement results of user-defined values (Class 152)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|--|---|--------|-----|-----|
| 152 | 0 | Not possible | - | - | | X | X |
| 152 | 1...9 | Reserved | - | - | | X | X |
| 152 | 10 | User-defined value 1 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 11 | User-defined value 1 measurement value | Float value | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 12 | User-defined value 1 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 13 | User-defined value 2 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 14 | User-defined value 2 measurement value | Float value | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 15 | User-defined value 2 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 16 | User-defined value 3 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 17 | User-defined value 3 measurement value | Float value | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 18 | User-defined value 3 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 19 | User-defined value 4 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 20 | User-defined value 4 measurement value | Float value | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 21 | User-defined value 4 unit | <i>String with max. 4</i> | See operand table in appendix. | STR 4 | 4 | RO |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|--|--|---|-------------|------------|------------|
| | | | <i>characters, e.g. "N" or "inch"</i> | | | | |
| 152 | 22 | User-defined value 5 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 23 | User-defined value 5 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 24 | User-defined value 5 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 25 | User-defined value 6 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 26 | User-defined value 6 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 27 | User-defined value 6 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 28 | User-defined value 7 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 29 | User-defined value 7 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 30 | User-defined value 7 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 31 | User-defined value 8 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 32 | User-defined value 8 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 33 | User-defined value 8 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 34 | User-defined value 9 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 35 | User-defined value 9 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|---|--|---|-------------|------------|------------|
| 152 | 36 | User-defined value 9 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 37 | User-defined value 10 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 38 | User-defined value 10 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 39 | User-defined value 10 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 40 | User-defined value 11 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 41 | User-defined value 11 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 42 | User-defined value 11 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 43 | User-defined value 12 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 44 | User-defined value 12 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 45 | User-defined value 12 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 46 | User-defined value 13 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 47 | User-defined value 13 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 48 | User-defined value 13 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 49 | User-defined value 14 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|---|--|---|-------------|------------|------------|
| 152 | 50 | User-defined value 14 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 51 | User-defined value 14 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 52 | User-defined value 15 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 53 | User-defined value 15 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 54 | User-defined value 15 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 55 | User-defined value 16 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 56 | User-defined value 16 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 57 | User-defined value 16 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 58 | User-defined value 17 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 59 | User-defined value 17 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 60 | User-defined value 17 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 61 | User-defined value 18 name | <i>String with the designator of the value</i> | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 62 | User-defined value 18 measurement value | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 63 | User-defined value 18 unit | <i>String with max. 4 characters, e.g. "N" or "inch"</i> | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 64 | User-defined value 19 name | <i>String with the</i> | Designator = "0" means that no value is defined for this | STR 16 | 16 | RO |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|---|---|--------|-----|-----|
| | | | designator of the value | value number | | | |
| 152 | 65 | User-defined value 19 measurement value | Float value | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 66 | User-defined value 19 unit | String with max. 4 characters, e.g. "N" or "inch" | See operand table in appendix. | STR 4 | 4 | RO |
| 152 | 67 | User-defined value 20 name | String with the designator of the value | Designator = "0" means that no value is defined for this value number | STR 16 | 16 | RO |
| 152 | 68 | User-defined value 20 measurement value | Float value | Float according to IEEE754 | FLT | 4 | RO |
| 152 | 69 | User-defined value 20 unit | String with max. 4 characters, e.g. "N" or "inch" | See operand table in appendix. | STR 4 | 4 | RO |

7.2.5 Read-out X-coordinates of current measurement curve (Class 153)

Sequence to read the curve coordinates

1. Load the curve into the field bus card through a write access to index 10.
2. Query the last measured value for the curve (→ end of the curve) through a read access to index 10.
3. The curve can now be read out in coordinate groups of up to 300 coordinates each or 300 coordinates of selected group (attribute 19) can be read in one go over attribute 11 if specified:
 Coordinate group 0: Measured value 0 ... 299
 Coordinate group 1: Measured value 300 ... 599
 Coordinate group 2: Measured value 600 ... 899 ... etc.

Note: Please note that you have to announce the DIGIFORCE® 9311 the length of the buffer to write the curve coordinates. Maximum buffer size required to store 300 float coordinates is 1200 bytes. The device will not send more bytes than you announces.

4. The number of the desired coordinate group is entered through a write access to index 19. Since we want to read the beginning of the curve, we enter a 0.

It is now possible to read curve values no. 0 ... 299 (at present we have selected coordinate group 0) at the Attributes 20 ... 319.

5. Coordinate group 1 (values 300 ... 599) is now read under index 19.
 It is now possible to read curve values no. 300 ... 599 at Attributes 20 ... 319.
6. After this, coordinate group 2 (values 600 ... 899) is read under index 19.
 It is now possible to read curve values no. 600 ... 899 at Attributes 20 ... 319, and so forth.
7. The coordinate groups can be read out in any desired sequence.
8. Only curve values that are smaller than or equal to the number of the last measured value (which was read at index 10) may be read out.

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|---------|--|---|-------------------------------------|------|--------|-----|
| 153 | 0 | Not possible | - | - | | X | X |
| 153 | 1...9 | Reserved | - | - | | X | X |
| 153 | 10 | Write access: If a curve is to be read, it must be prepared through a write access before the curve is first read. Read access: Index of the last coordinate; if 0, there is no curve | <i>EVENT!</i> <i>Writing any two arbitrary bytes initiates action</i> <i>Integer value 0...4999</i> | | U16 | 2 | W_ |
| 153 | 11 | Up to 300 coordinates of selected group (s. attribute 19) as float array. Note: Before reading the coordinates perform a write access on index 10 to prepare the curve and a read access on the same index 10 to determine the number of coordinates | <i>Float array of 0...300 values</i> | Float array according to IEEE754 | FLT | 0-1200 | RO |
| 153 | 12...18 | Reserved | - | - | | X | X |
| 153 | 19 | Write access: Desired group of 300 coordinates. For example, if coordinates 900 ... 1199 are to be displayed, there must be a 3 here. Query the maximum number of value pairs under Class 153/10. Read access: Group of 300 coordinates currently displayed. | <i>Integer value 0 ... 24</i> <i>Integer value 0 ... 24</i> | | U16 | 2 | W_ |
| 153 | 20 | 0. coordinate of group of coordinates | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 153 | 21 | 1. coordinate of group of coordinates | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 153 | 22 | 2. coordinate of group of coordinates | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|---|--------------------|----------------------------|-------------|------------|------------|
| 153 | 23 | 3. coordinate of group of coordinates | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 153 | ... | ... | ... | ... | ... | ... | ... |
| 153 | 317 | 297. coordinate of group of coordinates | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 153 | 318 | 298. coordinate of group of coordinates | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 153 | 319 | 299. coordinate of group of coordinates | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |

7.2.6 Read-out Y-coordinates of current measurement curve (Class 154)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|--------------------|--------------|-------------------------|-------------|------------|------------|
| 154 | 0 | Not possible | - | - | | X | X |
| 154 | 1...9 | Reserved | - | - | | X | X |
| 154 | 10... | See Class 153 | | | | X | X |

7.2.7 Evaluation results window 1 (Class 155)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|--|------------------------------------|----------------------------|-------------|------------|------------|
| 155 | 0 | Not possible | - | - | | X | X |
| 155 | 1...9 | Reserved | - | - | | X | X |
| 155 | 10 | Window 1 evaluation results OK/NOK | 0 1 | NOK OK | U16 | 2 | RO |
| 155 | 11 | Window 1 NOK counter | <i>32bit-Integer value >= 0</i> | | U32 | 4 | RO |
| 155 | 12 | Window 1 entry of curve X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 155 | 13 | Window 1 entry of curve Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 155 | 14 | Window 1 exit of curve X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 155 | 15 | Window 1 exit of curve Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 155 | 16 | Window 1 absolute maximum in window X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 155 | 17 | Window 1 absolute maximum in window Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 155 | 18 | Window 1 absolute minimum in window X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 155 | 19 | Window 1 absolute minimum in window Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |

7.2.8 Evaluation results window 2 (Class 156)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|--------------------|--------------|-------------------------|-------------|------------|------------|
| 156 | 0 | Not possible | - | - | | X | X |
| 156 | 1...9 | Reserved | - | - | | X | X |
| 156 | 10... | See Class 155 | | | | X | X |

7.2.9 Evaluation results window 3 (Class 157)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|--------------------|--------------|-------------------------|-------------|------------|------------|
| 157 | 0 | Not possible | - | - | | X | X |
| 157 | 1...9 | Reserved | - | - | | X | X |
| 157 | 10... | See Class 155 | | | | X | X |

7.2.10 Evaluation results threshold 1 (Class 158)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|---|------------------------------------|----------------------------|-------------|------------|------------|
| 158 | 0 | Not possible | - | - | | X | X |
| 158 | 1...9 | Reserved | - | - | | X | X |
| 158 | 10 | Threshold 1 evaluation result OK/NOK | 0 1 | NOK OK | U16 | 2 | RO |
| 158 | 11 | Threshold 1 NOK counter | <i>32bit-Integer value >= 0</i> | | U32 | 4 | RO |
| 158 | 12 | Threshold intersection point X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 158 | 13 | Threshold intersection point Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |

7.2.11 Evaluation results threshold 2 (Class 159)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|--------------|--------------|--------------------|--------------|-------------------------|-------------|------------|------------|
| 159 | 0 | Not possible | - | - | | X | X |
| 159 | 1...9 | Reserved | - | - | | X | X |
| 159 | 10... | See Class 158 | | | | X | X |

7.2.12 Evaluation results trapezoid window 1 (Class 160)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|------------------------------------|----------------------------|------|-----|-----|
| 160 | 0 | Not possible | - | - | | X | X |
| 160 | 1...9 | Reserved | - | - | | X | X |
| 160 | 10 | Trapezoid 1 evaluation result OK/NOK | 0 1 | NOK OK | U16 | 2 | RO |
| 160 | 11 | Trapezoid 1 NOK counter | <i>32bit-Integer value >= 0</i> | | U32 | 4 | RO |
| 160 | 12 | Trapezoid 1 entry coordinate X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 160 | 13 | Trapezoid 1 entry coordinate Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 160 | 14 | Trapezoid 1 exit coordinate X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 160 | 15 | Trapezoid 1 exit coordinate Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |

7.2.13 Evaluation results trapezoid window 2 (Class 161)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---------------|-------|------------------|------|-----|-----|
| 161 | 0 | Not possible | - | - | | X | X |
| 161 | 1...9 | Reserved | - | - | | X | X |
| 161 | 10... | See Class 160 | | | | X | X |

7.2.14 Evaluation results envelope (Class 162)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|------------------------------------|----------------------------|------|-----|-----|
| 162 | 0 | Not possible | - | - | | X | X |
| 162 | 1...9 | Reserved | - | - | | X | X |
| 162 | 10 | Envelope 1 evaluation result OK/NOK | 0 1 | NOK OK | U16 | 2 | RO |
| 162 | 11 | Envelope 1 NOK counter | <i>32bit-Integer value >= 0</i> | | U32 | 4 | RO |
| 162 | 12 | Envelope 1 entry coordinate X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 162 | 13 | Envelope 1 entry coordinate Y-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |
| 162 | 14 | Envelope 1 exit coordinate X-coordinate | <i>Float value</i> | Float according to IEEE754 | FLT | 4 | RO |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|-------------|----------------------------|------|-----|-----|
| 162 | 15 | Envelope 1 exit coordinate Y-coordinate | Float value | Float according to IEEE754 | FLT | 4 | RO |

7.2.15 Combined results (common curve data and evalution elements – Class 163)

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|--|--|------------------|------|-----|-----|
| 163 | 0 | Not possible | - | | | X | X |
| 163 | 1...9 | Reserved | - | | | X | X |
| 163 | 10 | Combined results: general curve data Y | The data is bit coded and transmitted as STRUCT. X-minimum, X-coord. (FL) X-minimum, Y-coord. (FL) X-maximum, X-coord. (FL) X-maximum, Y-coord. (FL) Y-minimum, X-coord. (FL) Y-minimum, Y-coord.(FL) Y-maximum, X-coord. (FL) Y-maximum, Y-coord.(FL) First value X-coord. (FL) First value Y-coord. (FL) Last value X-coord. (FL) Last value Y-coord. (FL) Return point X-coord. (FL) Return point Y-coord. (FL) | STRUCT OF FLOATS | 56 | RO | |
| 163 | 11 | Combined results: window 1 | The data is bit coded and transmitted as STRUCT. Evaluation result (UINT32): 0: NOK 1: OK Entry X-coordinate (FL) Entry Y-coordinate (FL) Exit X-coordinate (FL) Exit Y-coordinate (FL) Absolute max X-coord. (FL) Absolute max Y- coord.(FL) Absolute min X- coord. (FL) Absolute min Y- coord. (FL) Window Xmin coord. (FL) Window Xmax coord. (FL) Window Ymin coord. (FL) Window Ymax coord. (FL) | STRUCT | 52 | RO | |
| 163 | 12 | Combined results: window 2 | See index 11 | STRUCT | 52 | RO | |
| 163 | 13 | Combined results: window 3 | See index 11 | STRUCT | 52 | RO | |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|---|---|------------------|--------|-----|-----|
| 163 | 14 | Combined results: threshold 1 | <i>The data is bit coded and transmitted as STRUCT:</i> Evaluation result (UINT32): 0 : NOK 1 : OK Threshold type (UINT32): 0 : Type X-Threshold 1 : Type Y-Threshold Threshold pass X (FL) Threshold pass Y (FL) Type X : Position X value (FL) Type Y : Position Y value (FL) Type X : Ymin value (FL) Type Y : Xmin value (FL) Type X : Ymax value (FL) Type Y : Xmax value (FL) | | STRUCT | 28 | RO |
| 163 | 15 | Combined results: threshold 2 | See index 14 | | STRUCT | 28 | RO |
| 163 | 16 | Combined results: trapezoid window 1 | <i>The data is bit coded and transmitted as STRUCT:</i> Evaluation result (UINT32) 0 : NOK 1 : OK Threshold type (UINT32) 0 : Type X-Trapezoid 1 : Type Y-Trapezoid Entry X-coord. (FL) Entry Y-coord. (FL) Exit X-coord. (FL) Exit Y-coord. (FL) Type X : Xmin (FL) Type Y : Ymin (FL) Type X : Xmax (FL) Type Y : Ymax (FL) Type X : Ymin left (FL) Type Y : Xmin bottom (FL) Type X : Ymax left (FL) Type Y : Xmax bottom (FL) Type X : Ymin right (FL) Type Y : Xmin top (FL) Type X : Ymax right (FL) Type Y : Xmax top (FL) | | STRUCT | 48 | RO |
| 163 | 17 | Combined results: trapezoid window 2 | See index 16 | | STRUCT | 48 | RO |
| 163 | 18 | Combined results: envelope | <i>The data is bit coded and transmitted as STRUCT:</i> Evaluation result (UINT32): 0 : NOK 1 : OK Entry X-coordinate (FL) Entry Y-coordinate (FL) Exit X-coordinate (FL) Exit Y-coordinate (FL) | | STRUCT | 36 | RO |

| Class | Attr. | Description | Value | Meaning of value | Type | Len | R/W |
|-------|-------|-------------|--|------------------|------|-----|-----|
| | | | Envelope start (FL) Envelope end (FL) Delta min (FL) Delta max (FL) | | | | |

8 Appendix

8.1 Operand table

| Number | ID of operant |
|--------|--|
| 0 | OFF |
| 100 | General curve data – Start X |
| 101 | General curve data – Start Y |
| 102 | General curve data – End X |
| 103 | General curve data – End Y |
| 104 | General curve data – Abs. Xmax X-coordinate |
| 105 | General curve data – Abs. Xmax Y-coordinate |
| 106 | General curve data – Abs. Xmin X-coordinate |
| 107 | General curve data – Abs. Xmin Y-coordinate |
| 108 | General curve data – Abs. Ymax X-coordinate |
| 109 | General curve data – Abs. Ymax Y-coordinate |
| 110 | General curve data – Abs. Ymin X-coordinate |
| 111 | General curve data – Abs. Ymin Y-coordinate |
| 112 | General curve data – Return point X-coordinate |
| 113 | General curve data – Return point Y-coordinate |
| 200 | Window 1 – Entry X |
| 201 | Window 1 – Entry Y |
| 202 | Window 1 – Exit X |
| 203 | Window 1 – Exit Y |
| 204 | Window 1 – Abs. minimum X |
| 205 | Window 1 – Abs. minimum Y |
| 206 | Window 1 – Abs. maximum X |
| 207 | Window 1 – Abs. maximum Y |
| 208 | Window 1 – Coordinate Xmin |
| 209 | Window 1 – Coordinate Xmax |

| Number | ID of operant |
|------------|----------------------------|
| 210 | Window 1 – Coordinate Ymin |
| 211 | Window 1 – Coordinate Ymax |
| | |
| 300 | Window 2 – Entry X |
| 301 | Window 2 – Entry Y |
| 302 | Window 2 – Exit X |
| 303 | Window 2 – Exit Y |
| 304 | Window 2 – Abs. minimum X |
| 305 | Window 2 – Abs. minimum Y |
| 306 | Window 2 – Abs. maximum X |
| 307 | Window 2 – Abs. maximum Y |
| 308 | Window 2 – Coordinate Xmin |
| 309 | Window 2 – Coordinate Xmax |
| 310 | Window 2 – Coordinate Ymin |
| 311 | Window 2 – Coordinate Ymax |
| | |
| 400 | Window 3 – Entry X |
| 401 | Window 3 – Entry Y |
| 402 | Window 3 – Exit X |
| 403 | Window 3 – Exit Y |
| 404 | Window 3 – Abs. minimum X |
| 405 | Window 3 – Abs. minimum Y |
| 406 | Window 3 – Abs. maximum X |
| 407 | Window 3 – Abs. maximum Y |
| 408 | Window 3 – Coordinate Xmin |
| 409 | Window 3 – Coordinate Xmax |
| 410 | Window 3 – Coordinate Ymin |
| 411 | Window 3 – Coordinate Ymax |
| | |

| Number | ID of operant |
|--------|---|
| 500 | Trapezoid window 1 – Entry X |
| 501 | Trapezoid window 1 – Entry Y |
| 502 | Trapezoid window 1 – Exit X |
| 503 | Trapezoid window 1 – Exit Y |
| 504 | Trapezoid window 1 – Coordinate Type X: Xmin Type Y: Ymin |
| 505 | Trapezoid window 1 – Coordinate Type X: Xmax Type Y: Ymax |
| 506 | Trapezoid window 1 – Coordinate Type X: Ymin left Type Y: Xmin bottom |
| 507 | Trapezoid window 1 – Coordinate Type X: Ymax left Type Y: Xmax bottom |
| 508 | Trapezoid window 1 – Coordinate Type X: Ymin right Type Y: Xmin top |
| 509 | Trapezoid window 1 – Coordinate Type X: Ymax right Type Y: Xmax top |
| 600 | Trapezoid window 2 – Entry X |
| 601 | Trapezoid window 2 – Entry Y |
| 602 | Trapezoid window 2 – Exit X |
| 603 | Trapezoid window 2 – Exit Y |
| 604 | Trapezoid window 2 – Coordinate Type X: Xmin Type Y: Ymin |
| 605 | Trapezoid window 2 – Coordinate Type X: Xmax Type Y: Ymax |
| 606 | Trapezoid window 2 – Coordinate Type X: Ymin left Type Y: Xmin bottom |
| 607 | Trapezoid window 2 – Coordinate Type X: Ymax left Type Y: Xmax bottom |
| 608 | Trapezoid window 2 – Coordinate Type X: Ymin right Type Y: Xmin top |
| 609 | Trapezoid window 2 – Coordinate Type X: Ymax right Type Y: Xmax top |

| Number | ID of operant |
|------------|--|
| | |
| 700 | Threshold 1 – Pass X |
| 701 | Threshold 1 – Pass Y |
| 702 | Threshold 1 – Coordinate Type X: Position X value Type Y: Position Y value |
| 703 | Threshold 1 – Coordinate Type X: Ymin value Type Y: Xmin value |
| 704 | Threshold 1 – Coordinate Type X: Ymax value Type Y: Xmax value |
| | |
| 800 | Threshold 2 – Pass X |
| 801 | Threshold 2 – Pass Y |
| 802 | Threshold 2 – Coordinate Type X: Position X value Type Y: Position Y value |
| 803 | Threshold 2 – Coordinate Type X: Ymin value Type Y: Xmin value |
| 804 | Threshold 2 – Coordinate Type X: Ymax value Type Y: Xmax value |
| | |
| 900 | Envelope – Entry X |
| 901 | Envelope – Entry Y |
| 902 | Envelope – Exit X |
| 903 | Envelope – Exit Y |
| 904 | Envelope – Coordinate Start X |
| 905 | Envelope – Coordinate End X |

9 Error Codes

| Error Code | Description |
|------------|---|
| 0x00 | GSR_SUCCESS <i>No error, write/read successful</i> |
| 0x05 | EIP_GSR_BAD_CLASS_INSTANCE <i>This class/instance is not specified</i> Note: Only instance 1 is supported |
| 0x09 | EIP_GSR_BAD_ATTR_DATA <i>The write request has been declined.</i> <i>Please check your data and data length here</i> |
| 0x0F | EIP_GSR_PERMISSION_DENIED <i>Reading /Writing of this attribute is not supported</i> |
| 0x14 | EIP_GSR_UNDEFINED_ATTR <i>This attribute is not implemented by the firmware. Please refer to operation manual to check whether the attribute number is correct.</i> |
| 0x1E | EIP_GSR_SERVICE_ERROR <i>Read/Write request has been declined by device. Please refer to device operation manual to check if this parameter is writeable/readable</i> |
| 0xB2 | EIP_GSR_RESERVED_CLASS <i>Read/Write from/to this class is not supported</i> |